# Time Response Utility

Bob Ross, Teraspeed Labs bob@teraspeedlabs.com

#### European IBIS Summit Berlin, Germany, May 13, 2015

#### (Presented by Anders Ekholm, Ericsson)



Copyright 2015 Teraspeed Labs

### Notation and Introduction

**Laplace** Transform

**Differential Equation** 

$$X(s) = \frac{a_{n-1}s^{n-1} + \dots + a_0}{s^n + b_{n-1}s^{n-1} + \dots + b_0},$$
  
$$x^n(t) + b_{n-1}x^{n-1}(t) + \dots + b_0x(t) = 0$$

initial conditions,  $x(0), \dots, x^{n-1}(0)$ ,

Utility calculates and displays immediately 101 points for  $x^i(t)$ , i=0 to i=26 for the time response and all of its derivatives

Extended for more time points by copying and pasting last row

Can be used as an embedded utility involving other Laplace Transform calculations



## Enter Laplace Transform Num. and Den. Coefficients and Time-Step

Laplace Transform Numerator and Denominator Coefficients								
a7	a6	a5	a4	a3	a2	a1	a0	
0	1	-21	210	-1260	4725	-10395	10395	
b7	b6	b5	b4	b3	b2	b1	b0	
1	21	210	1260	4725	10395	10395	0	
T-Step s								
Select 0.08								
		-						

**Step Response of 6<sup>th</sup> order Bessel (maximally flat envelope delay, MFED) all-pass function** 

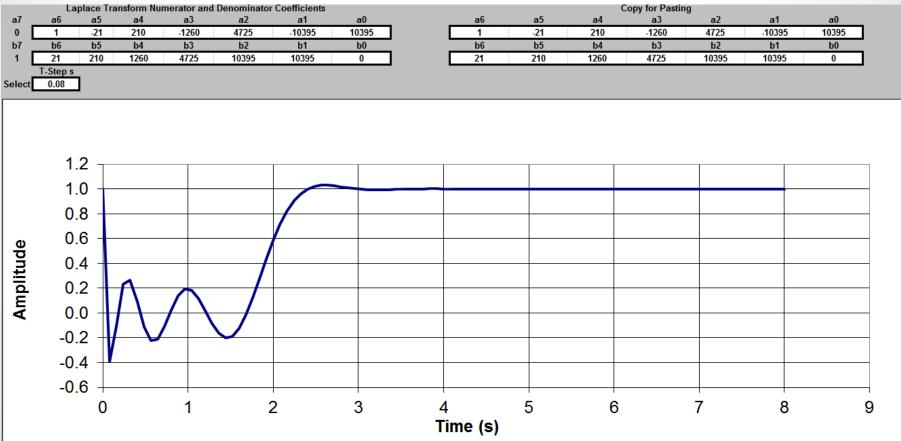
Change time-step to zoom-in or zoom-out and to change resolution

The graph auto-scales over 101 points



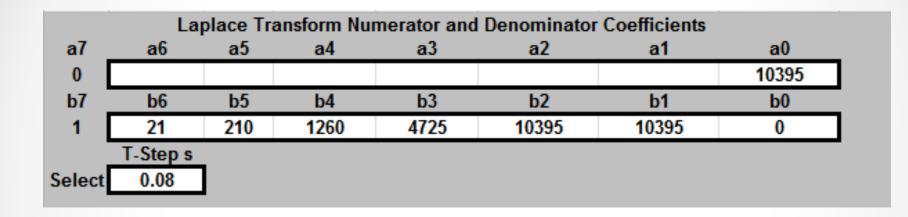
Copyright 2015 Teraspeed Labs

## 6<sup>th</sup> Order MFED All-Pass Step Response





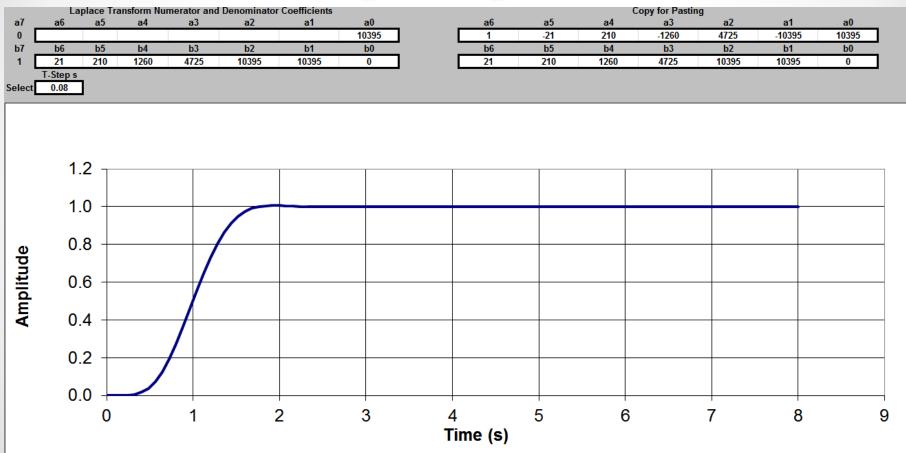
## 6<sup>th</sup> Order MFED Low-Pass Step Response Input



**Convert all-pass to low-pass filter by zeroing out numerator coefficients (click/back-space or enter 0) for real-time modification** 



## 6<sup>th</sup> Order MFED Low-Pass Step Response



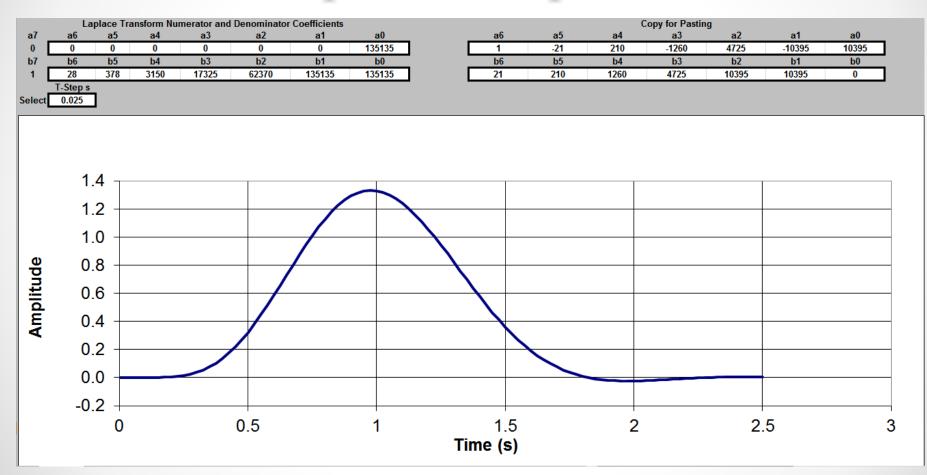


## 7<sup>th</sup> Order MFED Low-Pass Impulse Response Input

Laplace Transform Numerator and Denominator Coefficients								
a7	a6	a5	a4	a3	a2	a1	a0	
0	0	0	0	0	0	0	135135	
b7	b6	b5	b4	b3	b2	b1	b0	
1	28	378	3150	17325	62370	135135	135135	
T-Step s Select 0.025								
Select	0.023							

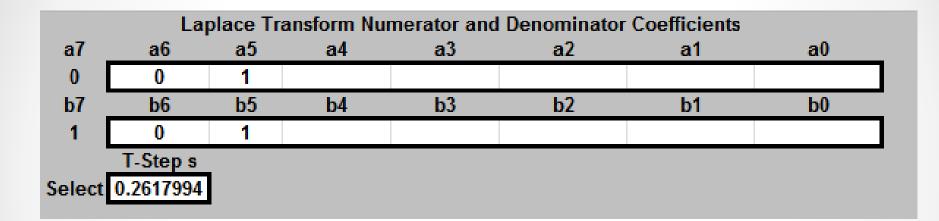


## 7<sup>th</sup> Order MFED Low-Pass Impulse Response





## X(s) = 1/(s<sup>2</sup> + 1) Sine Wave with Left-Shifted Coefficients

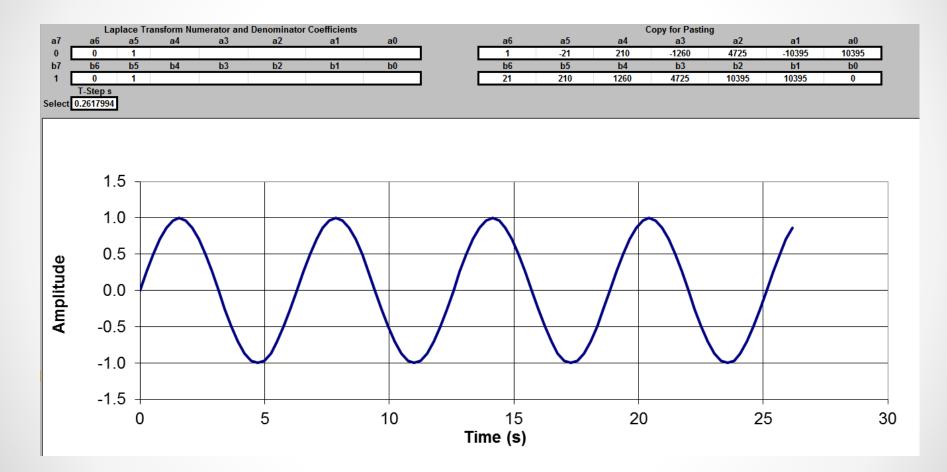


Set Time-Step =PI()/12 for exact  $\pi/12$  (15 degree) steps

**Can compare response with exact solution:**  $x(t) = sin(\pi t/12)$ 



### Sine Wave Response





**Recursive Taylor Series Method** (Repeat b and c) a) Initialize: i = 1, ..., n-1(n = 7) $x(0) = a_{n-1} \qquad x^{i}(0) = a_{n-1-i} - \sum_{j=0}^{i-1} b_{n-i-j} x^{j}(0)$ b) Extend:  $i = n, \dots, p$ (p = 26) $x^{i}(t) = -\sum_{i=0}^{n-1} b_{i} x^{i-n-j}(t)$ c) Next time step: i = 0, ..., n-1 (Taylor Series)  $x^{i}(t+T) = \sum_{j=i}^{p} x^{j}(t) \frac{T^{j-i}}{(i-i)!}$ 

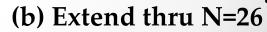
R. I. Ross, "Evaluating the Transient Response of a Network Function," Proc. IEEE, vol.55, pp. 615-616, May 1967



## Spread Sheet Details

Copy for Pastin a4 a3
210 -1260
b4 b3
1260 4725
<u></u>
Sheet
9 10
59204E-11 4.16796E-13
9 10
000E+00 0.000E+00
.659E-01 -2.588E-01
.660E-01 -5.000E-01
.071E-01 -7.071E-01
.000E-01 -8.660E-01
.588E-01 -9.659E-01
.342E-16 -1.000E+00
.588E-01 -9.659E-01
.000E-01 -8.660E-01
.071E-01 -7.071E-01
.660E-01 -5.000E-01
$\longrightarrow$

(c) x(t+T) Taylor Series for new row





## Accurate Time Response for $X(s) = 1/(s^2 + 1); x(t) = sin(\pi t/12)$

	Х	Y	Z	AA	AB	AC
103	-1.05412673E-14	1.00000000E+00	1.05412673E-14	-1.0000000E+00	-1.05412673E-14	1.00000000E+00
104	2.58819045E-01	9.65925826E-01	-2.58819045E-01	-9.65925826E-01	2.58819045E-01	9.65925826E-01
105	5.0000000E-01	8.66025404E-01	-5.0000000E-01	-8.66025404E-01	5.0000000E-01	8.66025404E-01
106	7.07106781E-01	7.07106781E-01	-7.07106781E-01	-7.07106781E-01	7.07106781E-01	7.07106781E-01
107	8.66025404E-01	5.0000000E-01	-8.66025404E-01	-5.00000000E-01	8.66025404E-01	5.00000000E-01
108	9.65925826E-01	2.58819045E-01	-9.65925826E-01	-2.58819045E-01	9.65925826E-01	2.58819045E-01
109	1.00000000E+00	1.10769747E-14	-1.0000000E+00	-1.10769747E-14	1.00000000E+00	1.10769747E-14
110	9.65925826E-01	-2.58819045E-01	-9.65925826E-01	2.58819045E-01	9.65925826E-01	-2.58819045E-01
111	8.66025404E-01	-5.00000000E-01	-8.66025404E-01	5.00000000E-01	8.66025404E-01	-5.00000000E-01
112	7.07106781E-01	-7.07106781E-01	-7.07106781E-01	7.07106781E-01	7.07106781E-01	-7.07106781E-01
113	5.0000000E-01	-8.66025404E-01	-5.00000000E-01	8.66025404E-01	5.0000000E-01	-8.66025404E-01

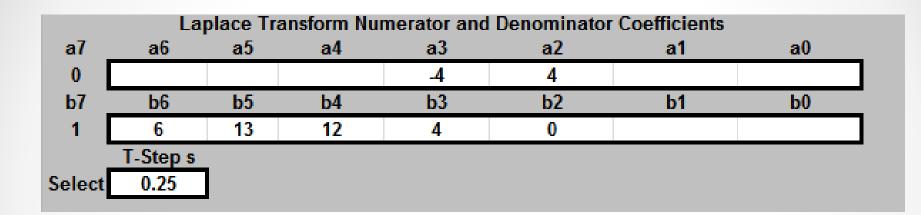
#### **Iterative calculation = exact response to 9 digits**

- up to 101 data points
- up to the 26<sup>th</sup> derivative

#### (Table resolution increased to 9 digits to show accuracy)



## 5<sup>th</sup>-order Step Response

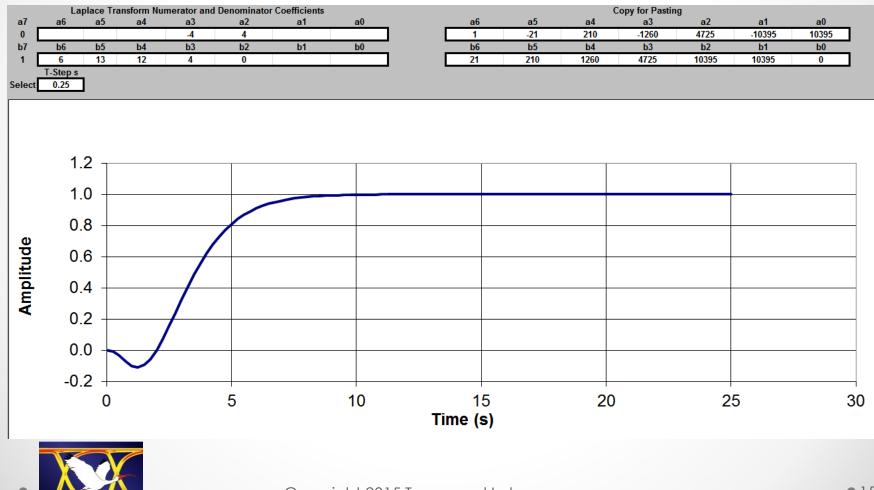


$$X(s) = 4(-s+1)/[(s+1)^2 (s+2)^2 s] = (-4s+4)/(s^5+6s^4+13s^3+12s^2+4s)$$

Laplace transform is normalized ( $b_7 = 1$ ) Left-shift the numerator and denominator coefficients Step response means  $b_2$  is 0 Right-hand plane zero creates pre-shoot



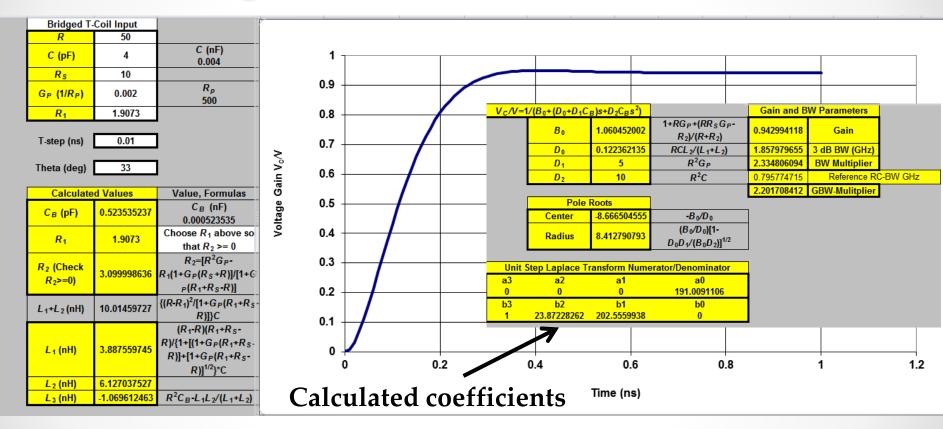
### 5th-Order Step Response



Copyright 2015 Teraspeed Labs

Teraspeed Labs

## Embedded with Constant-R Bridged T-Coil Calculations



#### Scaled Time (ns), L (nH), C (nF) with 3<sup>rd</sup> order Laplace Transform sheet



**Closed-form equations inserted above Time Response** 

Copyright 2015 Teraspeed Labs

#### Guidance

- <u>Normalize coefficients</u> (highest order denominator coefficient set to 1)
- <u>Scale coefficients</u> so that values are meaningful for time-steps between 0.01 and 1 (because of Taylor Series expansion)
- Left-shift the entries for lower-order functions
- <u>Change time-step</u> to zoom-in or zoom-out
- Get numerical values from spread sheet
- <u>Copy and paste</u> last row to extend spread sheet for more time rows (also adjust display range)



### **Final Remarks**

- Works with real, complex, multiple roots, pole-zero canceled roots, and right-hand plane zeros
- Response fast even though spread-sheet implementation is based on inefficient storage
- Recursive routine (slide 11) can be done <u>in-place</u> for better storage efficiency in other programming applications
- Display shows changes as coefficients are modified
- Display diverges if Laplace Transform close-form response diverges



## Some Applications

- Show step and impulse response for network analysis
- Show step and impulse response for lower-order, reduced order (or pole-zero) Touchstone formulations in IBIS-AMI analysis
- Embed for time-response displays in analysis applications by inserting calculations at top



European IBIS Summits Downloads and References

- www.eda.org/ibis/summits/may15/
  - ross.xls (time-response utility)
  - <u>ross.pdf</u> (this presentation for instructions, examples)
- www.eda.org/ibis/summits/may11/
  - ross3.pdf, "Continuous and Discrete Modeling for IBIS-AMI" (gives theoretical background for both differential and difference equations)
  - <u>ross2.pdf</u>, "T-Coils and Bridged-T Networks" (gives general T-coil derivations)

