

Circuit Synthesis of Multiport Networks from Passive Poles and Residues

Chiu-Chih (George) Chou

National Central University, Taoyuan, Taiwan

José E. Schutt-Ainé,

University of Illinois, Urbana, IL

IBIS Summit at DesignCon 2022

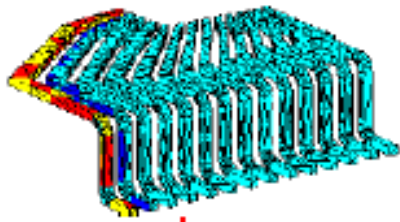
Santa Clara, CA

Virtual

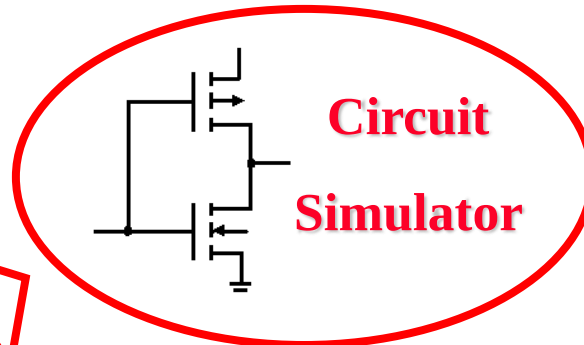
April 8, 2022

Interconnect Structures

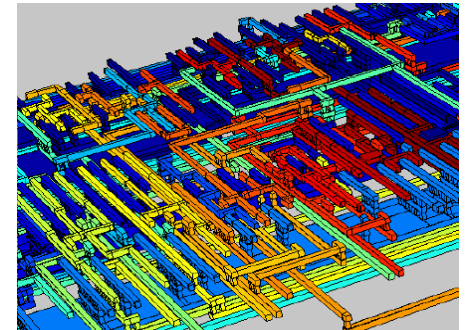
Crosstalk
Couplings
Reflections
Losses
Dispersion



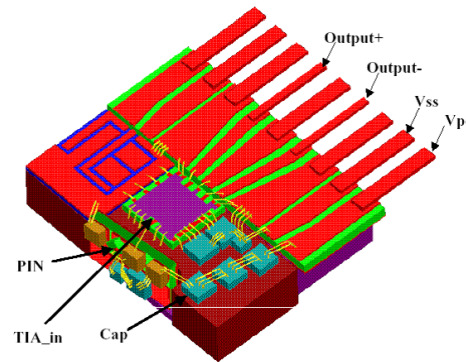
Packages



Ground Noise
Nonlinear effects
Radiation, EMI

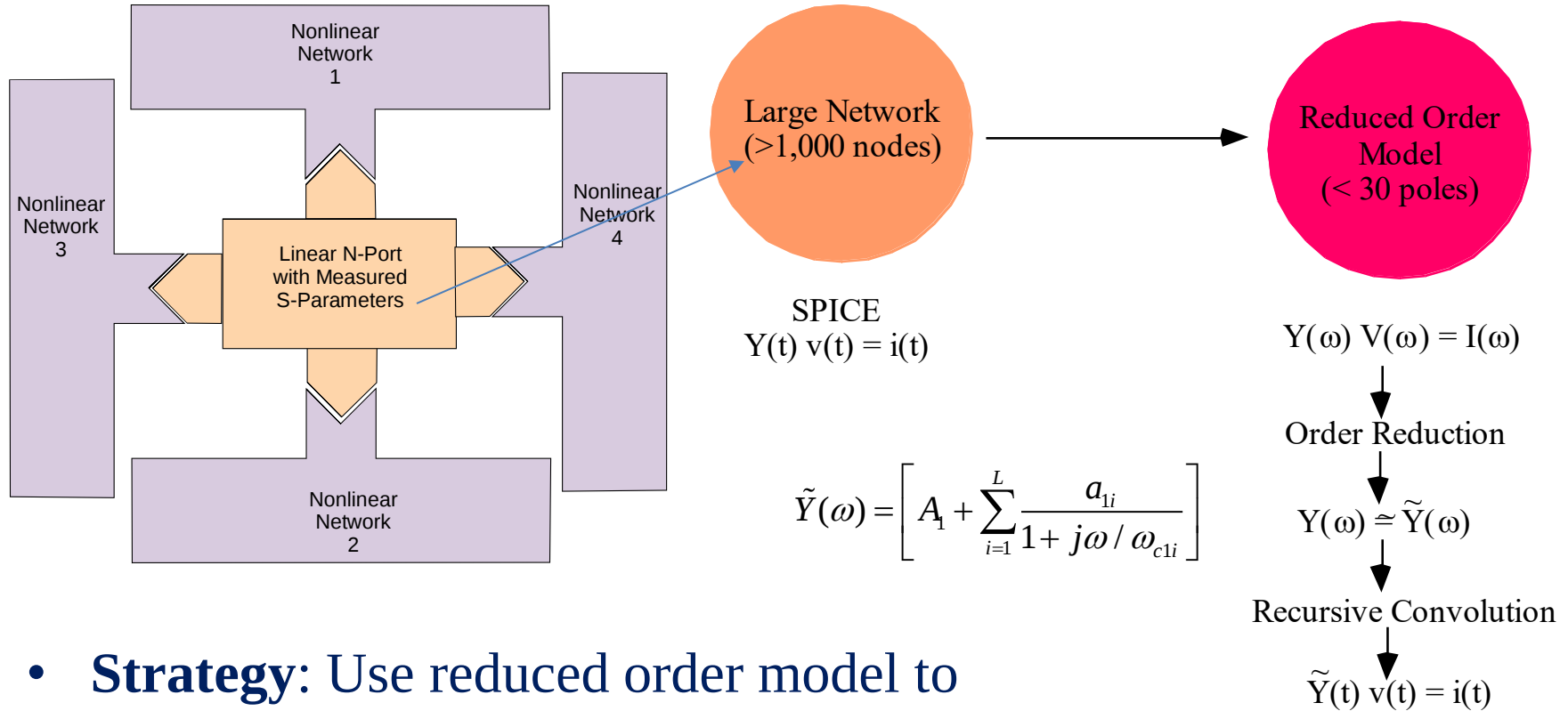


Interconnects



Courtesy of http://www.ansoft.com/hfworkshop03/Weimin_Sun_Vitesse.pdf

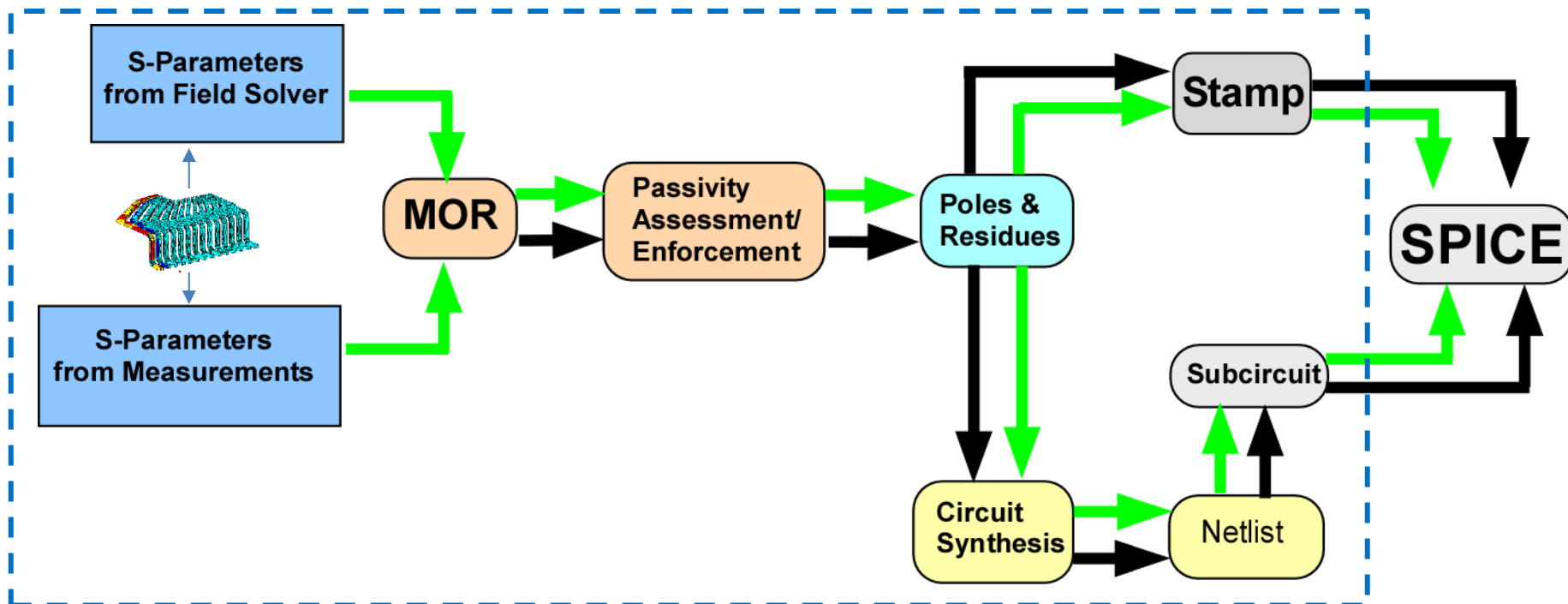
Model-Order Reduction



- **Strategy:** Use reduced order model to minimize computation time.

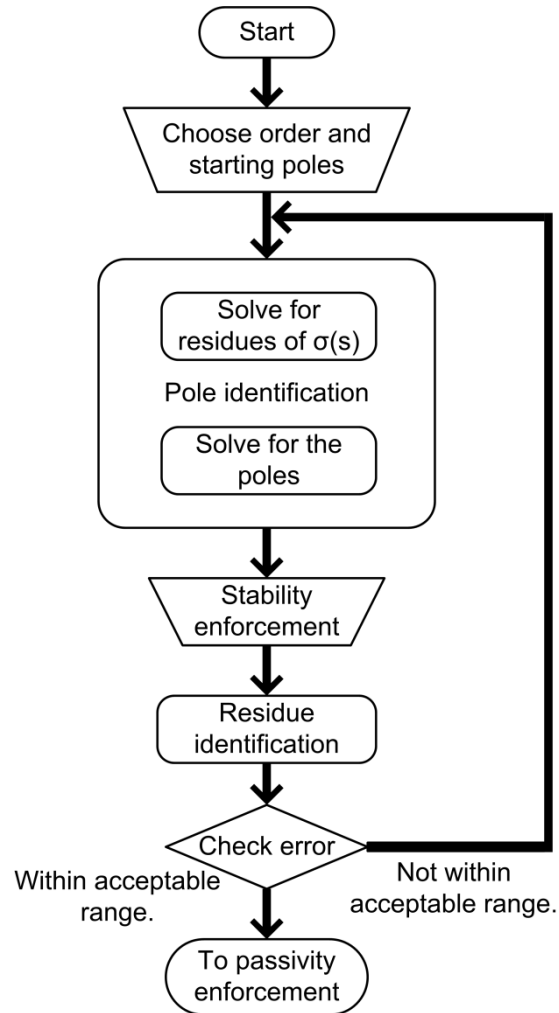
$$\tilde{Y}(\omega) \approx Y(\omega)$$

Model-Order Reduction



- **Objective:** Incorporate frequency dependence into time-domain simulator
- **Approaches:** 1) Direct integration of code into SPICE – 2) Generation of SPICE-compatible netlist

MOR via Vector Fitting



- Rational function approximation:

$$f(s) \approx \sum_{n=1}^N \frac{c_n}{s - a_n} + d + sh$$

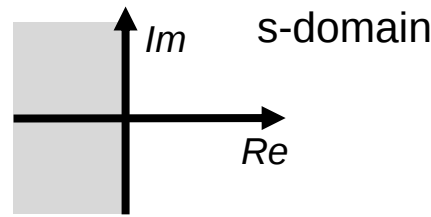
- Introduce an unknown function $\sigma(s)$ that satisfies:

$$\begin{bmatrix} \sigma(s)f(s) \\ \sigma(s) \end{bmatrix} \approx \begin{bmatrix} \sum_{n=1}^N \frac{c_n}{s - \tilde{a}_n} + d + sh \\ \sum_{n=1}^N \frac{\tilde{c}_n}{s - \tilde{a}_n} + 1 \end{bmatrix}$$

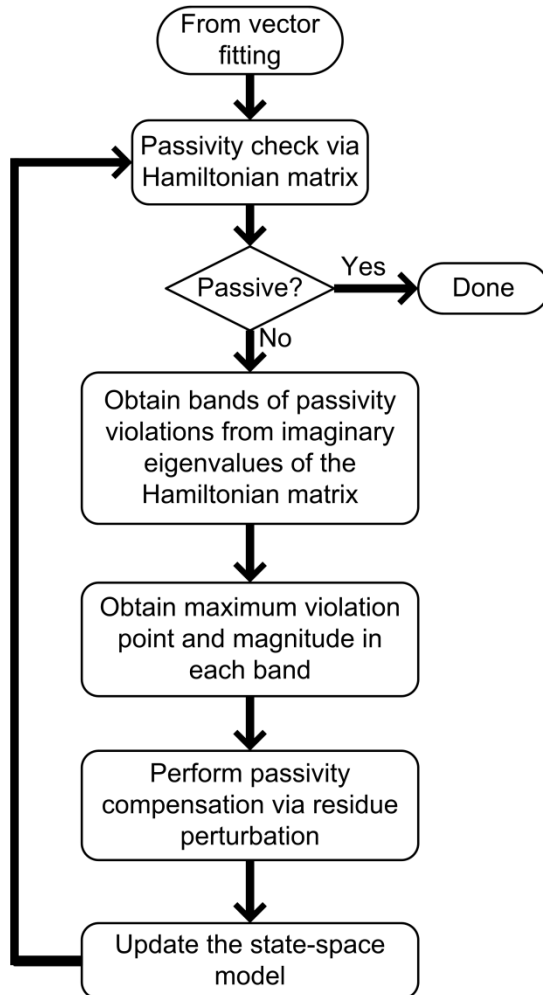
- Poles of $f(s)$
= zeros of $\sigma(s)$:

$$f(s) \approx \frac{\sum_{n=1}^N \frac{c_n}{s - \tilde{a}_n} + d + sh}{\sum_{n=1}^N \frac{\tilde{c}_n}{s - \tilde{a}_n} + 1} = \frac{\prod_{n=1}^{N+1} (s - z_n)}{\prod_{n=1}^N (s - \tilde{z}_n)}$$

- Flip unstable poles into the left half plane.



Passivity Enforcement



- State-space form:

$$\dot{x} = Ax + Bu$$

$$y = Cx + Du$$

- Hamiltonian matrix:

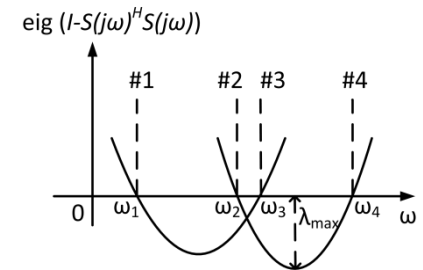
$$M = \begin{bmatrix} A + BKD^T C & BKB^T \\ -C^T L C & -A^T - C^T DKB^T \end{bmatrix}$$

$$K = (I - D^T D)^{-1} \quad L = (I - DD^T)^{-1}$$

- Passive if M has no imaginary eigenvalues.

- Sweep:

$$\text{eig}(I - S(j\omega)^H S(j\omega))$$



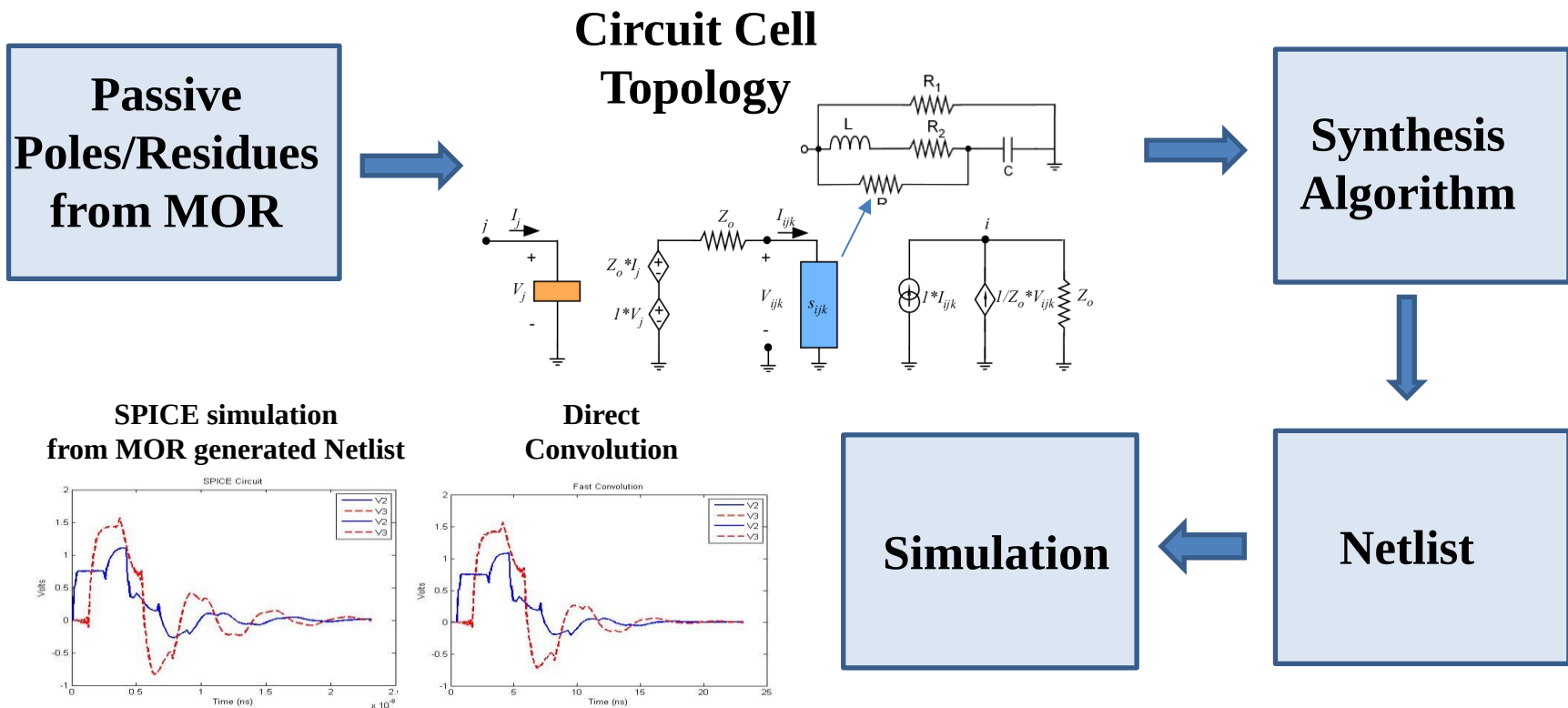
- Quadratic programming:

- Minimize *(change in response)* subject to *(passivity compensation)*.

$$\min(\text{vec}(\Delta C)^T H \text{vec}(\Delta C)) \quad \text{subject to} \quad \Delta \lambda = G \cdot \text{vec}(\Delta C).$$

SPICE Netlist Synthesis

- Goal is to generate (using pole/residue information) a circuit netlist that will exhibit the same (frequency-dependent) behavior as that of the S-parameters of connector under study



Equivalent-Circuit Extraction

Macromodel is curve-fit to take the form

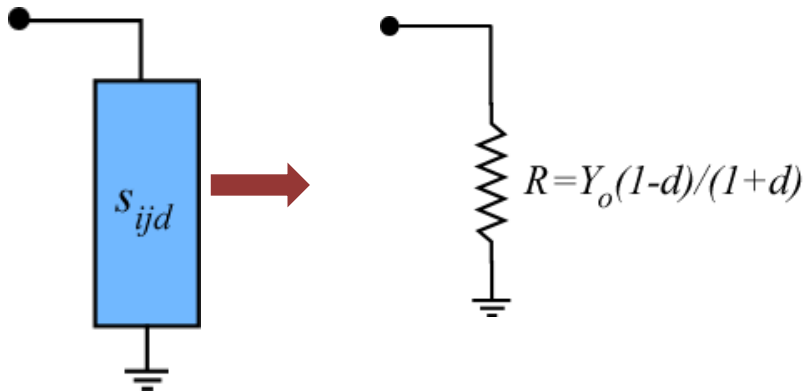
$$S(s) = d + \sum_{k=1}^L \frac{r_k}{s - p_k}$$

Need to find equivalent circuit associated with

- Constant term d
- Real Poles
- Complex Poles

Equivalent-Circuit Extraction

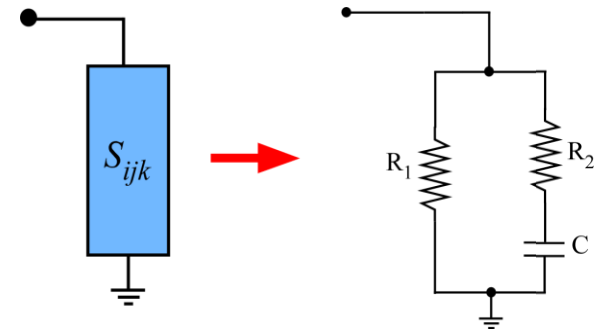
Constant Term



$$R = Y_o \left(\frac{1-d}{1+d} \right)$$

$$a = p_k + r_k, \quad \text{and} \quad b = p_k - r_k$$

Real Poles



$$R_2 = \frac{-1}{bC}$$

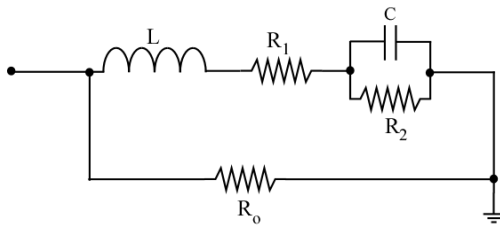
$$R_1 = -R_2 - \frac{1}{aC}$$

$$C = -\frac{(b-a)}{b^2 Z_o}$$

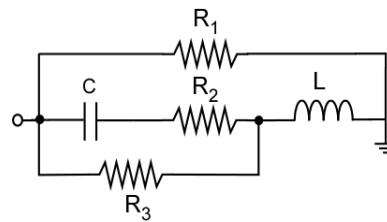
Realization – Complex Poles

There are several circuit topologies that will work

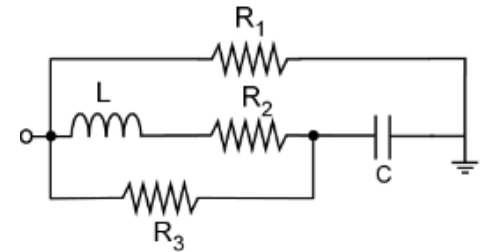
Model 1



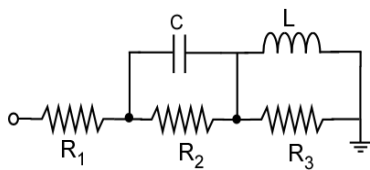
Model 8



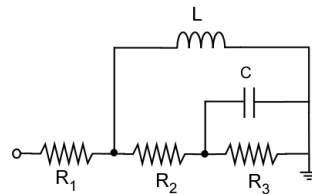
Model 9



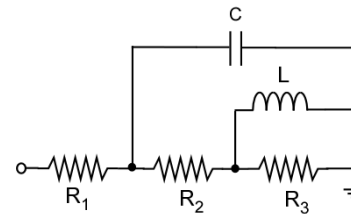
Model 11



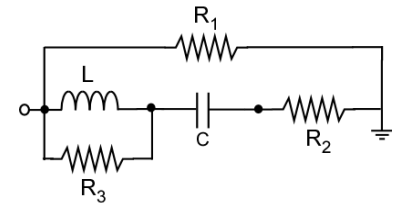
Model 12



Model 13



Model 10



Netlist from Poles & residues

*Poll 2-port S-parameter circuit model

* 14 -pole approximation

.subckt Poll 42000 56000

vsens42001 42000 42001 0.0

vsens56001 56000 56001 0.0

*subcircuit for s[1][1]

*complex residue-pole pairs for S[1][1] at k= 1 -> 1st pole: -4.8961e+00 3.6506e+01 residue: 2.1006e-01 -2.8971e-01

* -> 2nd pole: -4.8961e+00 -3.6506e+01 residue: 2.1006e-01 2.8971e-01

*circuit type = 9

elc1 1 0 42001 0 1.0

hc2 2 1 vsens42001 50.0

rterasc3 2 3 50.0

vp4 3 4 0.0

r1cd5 4 0 5.17406e+01

l1cd5 4 5 -1.25500e-08

r2cd6 5 6 -1.30103e+03

c1cd6 6 0 -7.19920e-15

r3cd6 4 6 1.48633e+03

*complex residue-pole pairs for S[1][1] at k= 2 -> 1st pole: -1.3039e+00 2.7679e+01 residue: -4.3856e-01 -1.9087e+00

* -> 2nd pole: -1.3039e+00 -2.7679e+01 residue: -4.3856e-01 1.9087e+00

rterasc9 8 9 50.0

:

:

gs196 0 56001 196 0 0.020

rnort42001 42001 0 5.00000e+01

rnort56001 56001 0 5.00000e+01

.ends Poll

*main circuit

rgen 1 2 50.0

x1 2 3 Poll

vin 1 0 pulse (0 1 0.20000ns 0.10000ns 0.10000ns 2.00000ns 6.00000ns)

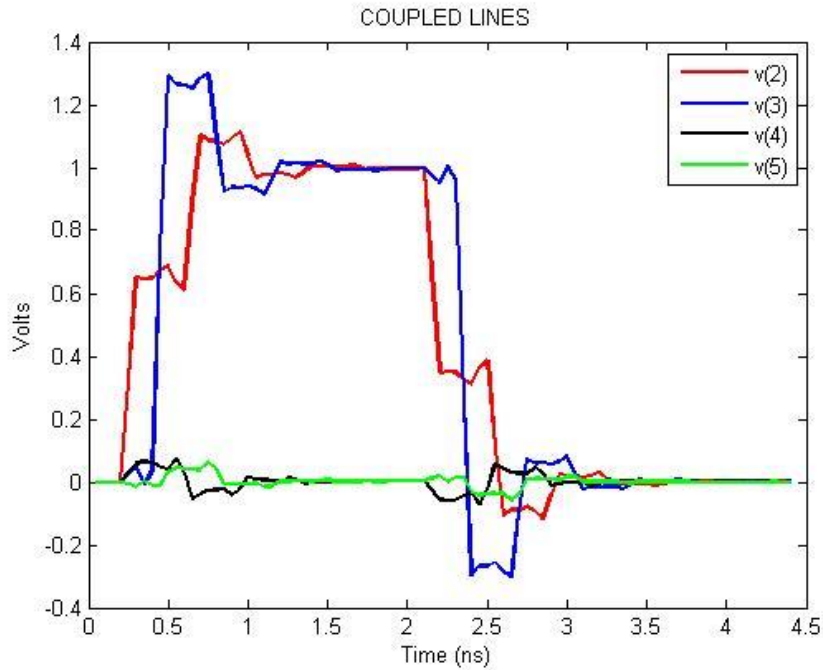
rport2 3 0 50000.0000000

.tran 0.00039ns 7.00000ns

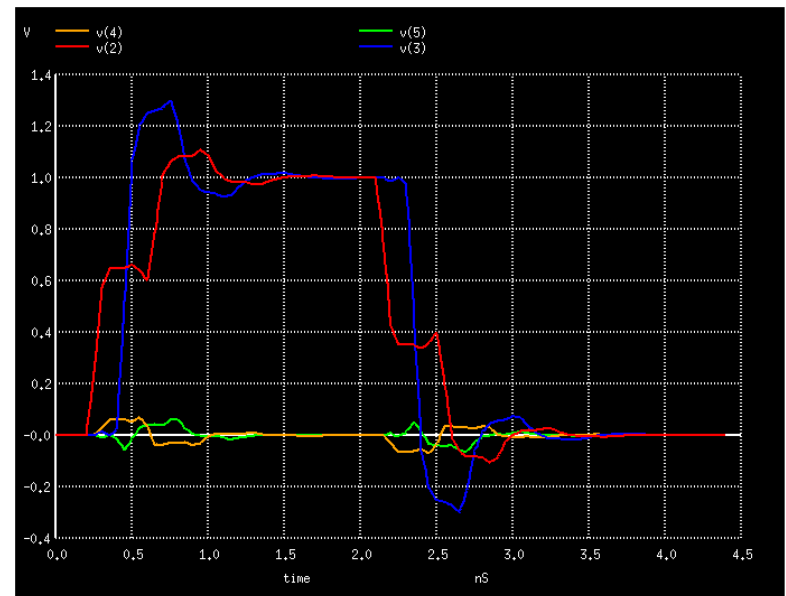
.end

4-Port Network

Direct

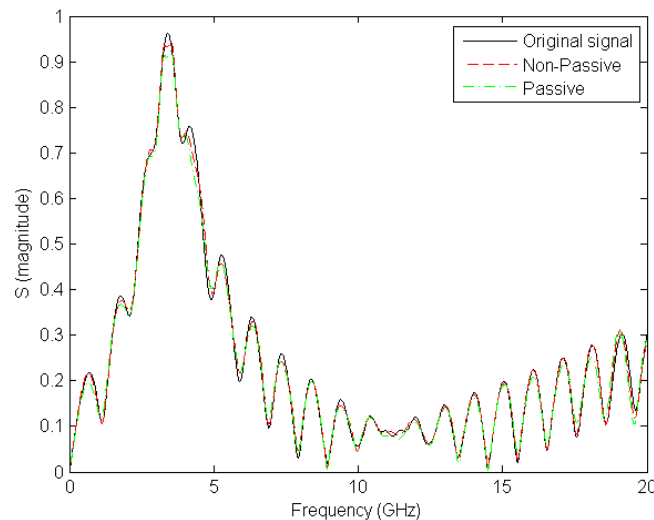


SPICE simulation
Using generated netlist
(Method 2)



Model-Order Reduction

- Start with S parameters from field solver
- Use vector fitting to get poles & residues
- Perform assessment via Hamiltonian
- Enforcement: Residue Perturbation Method
- Simulation: Recursive convolution → **Fast**



Number of Ports	Order	CPU-Time
4	20	1.7 secs
6	32	3.69 secs
10	34	8.84 secs
20	34	33 secs
40	50	142 secs
80	12	255 secs

Review of some classic synthesis approaches for S matrix in pole-residue form*

1. (PI network for Y matrix)
2. PI network for S by Y + VCVS + CCVS
3. State-space S
4. State-space S-to-Y then PI
5. Pole-residue S-as-Y
6. Direct pole-residue specification

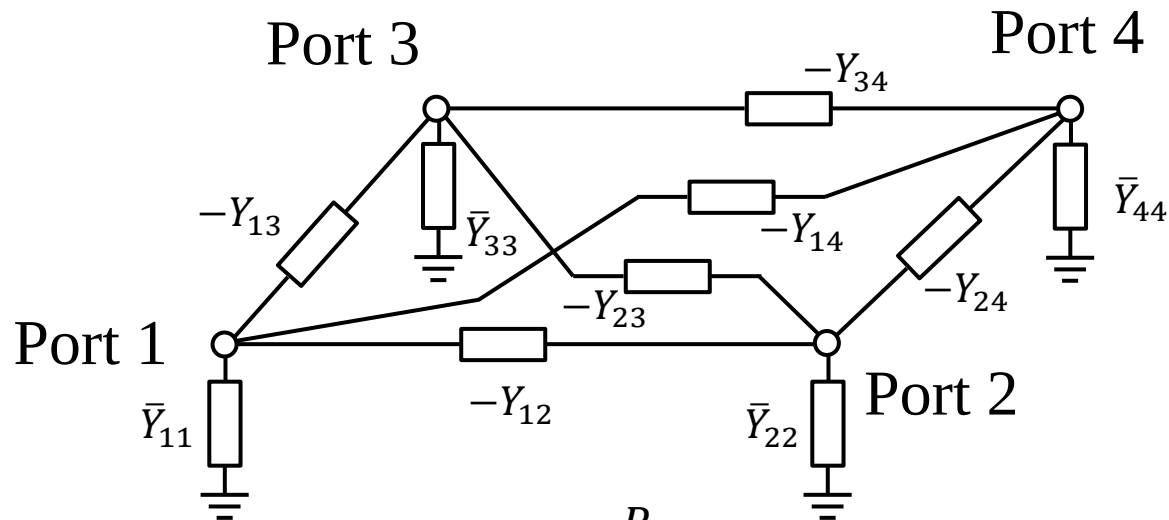
$$S_{ij} = d^{(ij)} + \sum_{k=1}^N \frac{r_k^{(ij)}}{s - p_k^{(ij)}} = d^{(ij)} + \sum_{k=1}^N S_{ij,k}$$

* Chiu-Chih Chou, José E. Schutt-Ainé, "Equivalent Circuit Synthesis of Multiport S Parameters in Pole-Residue Form", *IEEE Transactions on Components, Packaging and Manufacturing Technology*, Volume 11, Issue: 11, pp. 1971-1979, 2021, November 2021

Model 1. PI network for Y matrix (1/2)

$$Y_{ij} = d^{(ij)} + \sum_{k=1}^N \frac{r_k^{(ij)}}{s - p_k^{(ij)}}$$

Pole-residue Y matrix → PI model
(direct correspondence)

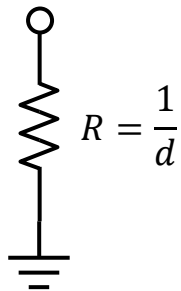


$$\bar{Y}_{ii} = \sum_{j=1}^P Y_{ij}$$

Model 1. PI network for Y matrix (2/2) (no controlled sources, but have negative elements)

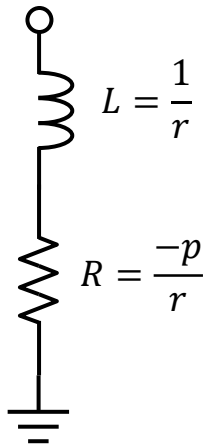
Constant

$$Y = d$$



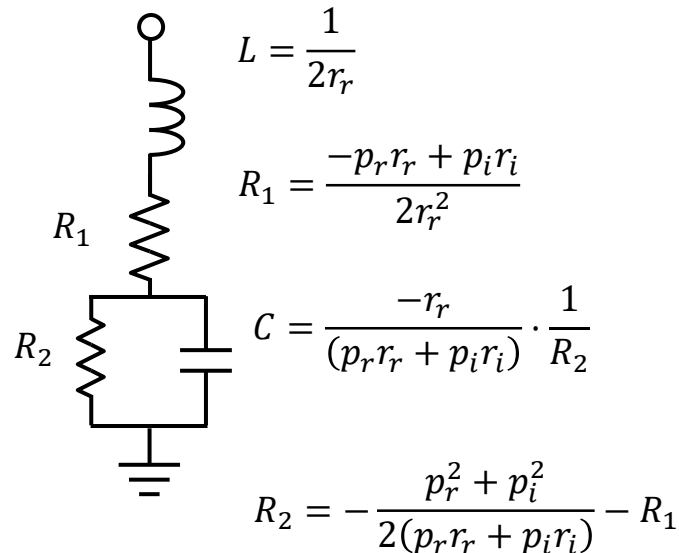
A real pole

$$Y = \frac{r}{s - p}$$



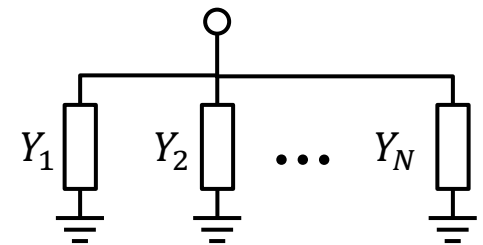
A pair of complex conjugate poles (RLCR)

$$Y = \frac{r}{s - p} + \frac{r^*}{s - p^*}$$

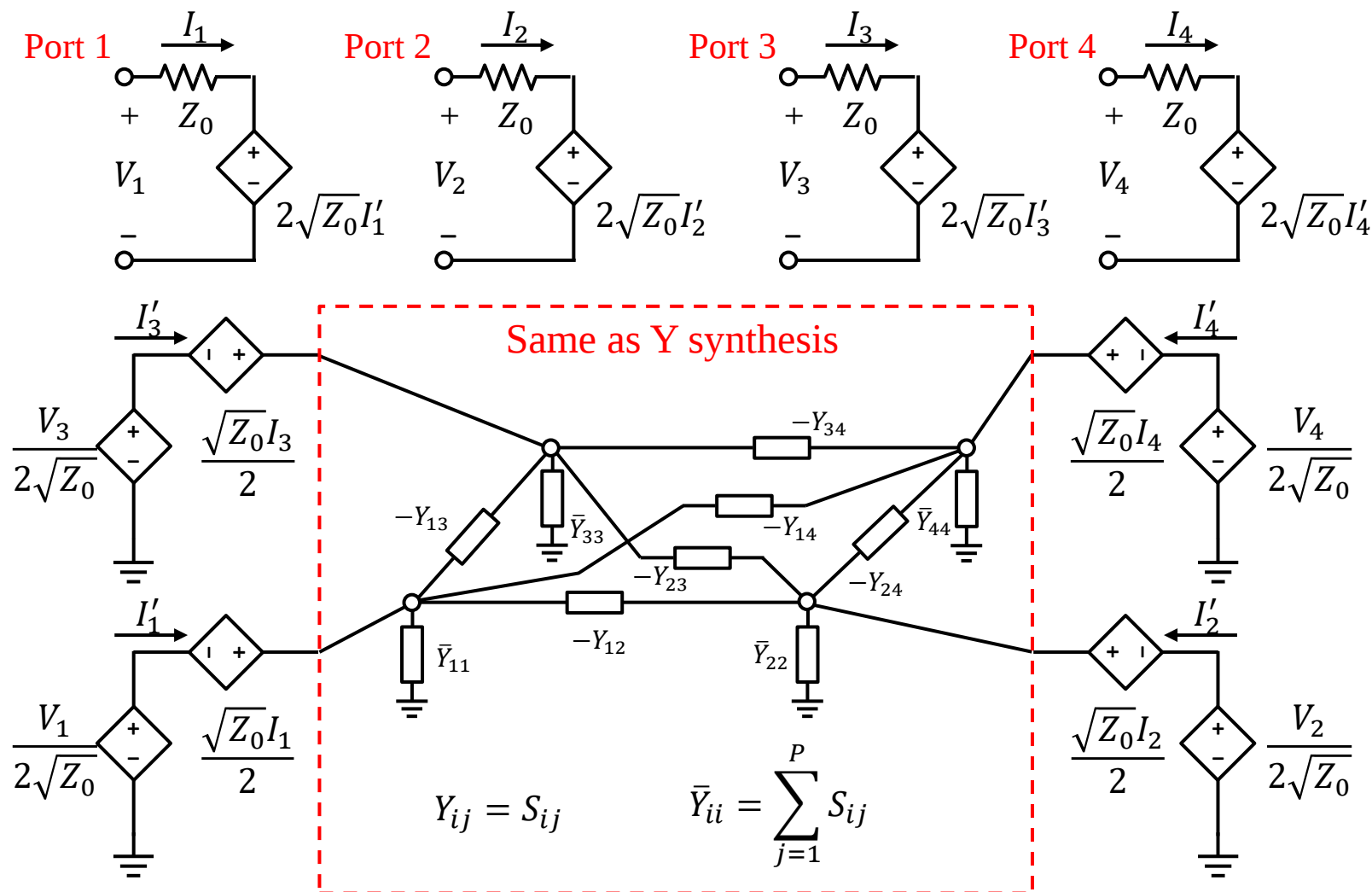


N pole-residue pairs

$$Y = \sum_{k=1}^N Y_k$$

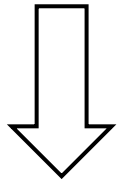


Model 2. PI network for S by Y + VCVS + CCVS



Model 3. State-space S (1/2) (a common cross-platform topology)

$$S_{ij} = d^{(ij)} + \sum_{k=1}^N \frac{r_k^{(ij)}}{s - p_k^{(ij)}}$$



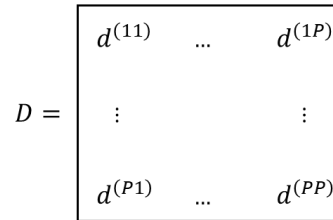
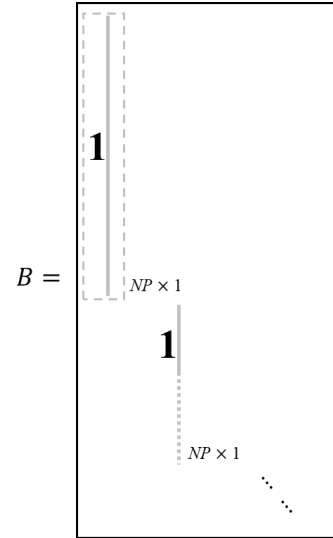
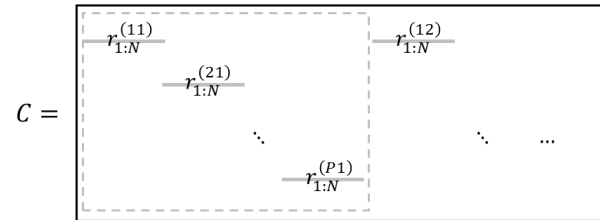
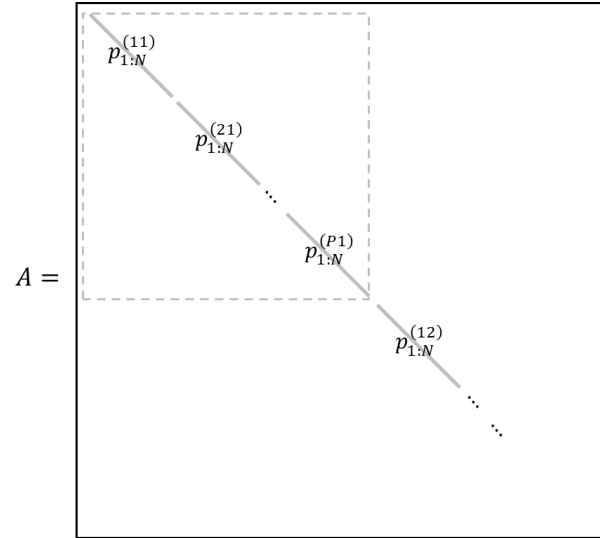
Pole-residue
to state-space

$$A = \text{diag}_{\substack{j=1 \dots P \\ i=1 \dots P \\ k=1 \dots N}} p_k^{(ij)}$$

$$B_{nj} = 1_{\{(j-1)NP < n \leq jNP\}}$$

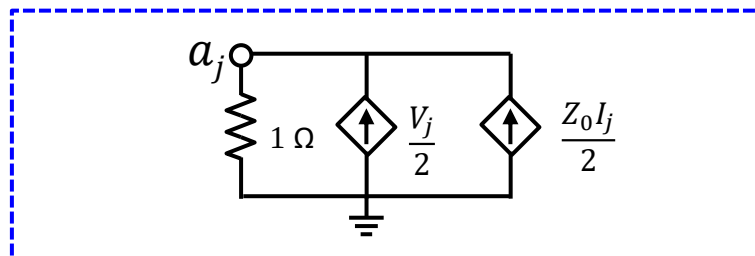
$$C_{in} = r_k^{(ij)} \cdot 1_{\{n = (j-1)NP + (i-1)N + k\}}$$

$$D_{ij} = d^{(ij)}$$

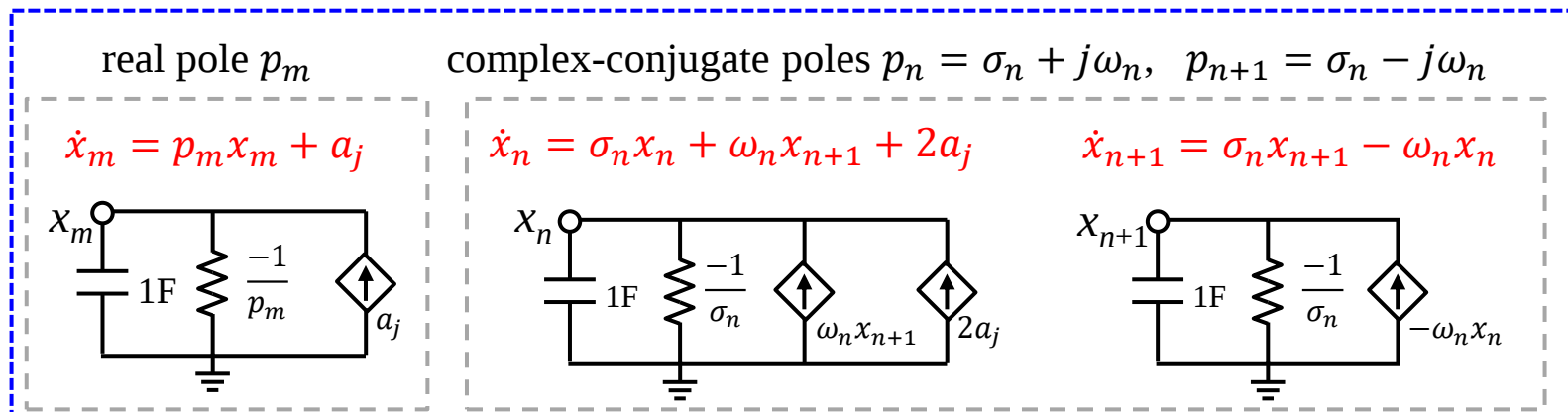


Model 3. State-space S (2/2)

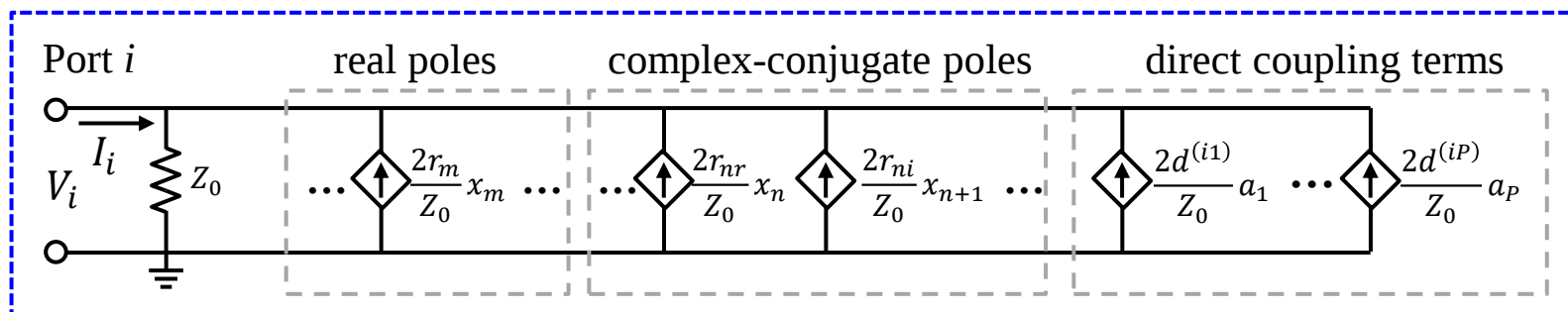
Input equations
(incident wave):



State equations:



Output equations:



Model 4. State-space S to Y then PI (no controlled sources needed)

State-space for S matrix

$$\left\{ \begin{array}{l} A = \text{diag } p_k^{(ij)} \\ \quad \begin{array}{l} j=1 \dots P \\ i=1 \dots P \\ k=1 \dots N \end{array} \\ B_{nj} = 1_{\{(j-1)NP < n \leq jNP\}} \\ C_{in} = r_k^{(ij)} \cdot 1_{\{n = (j-1)NP + (i-1)N + k\}} \\ D_{ij} = d^{(ij)} \end{array} \right.$$

State-space for Y matrix

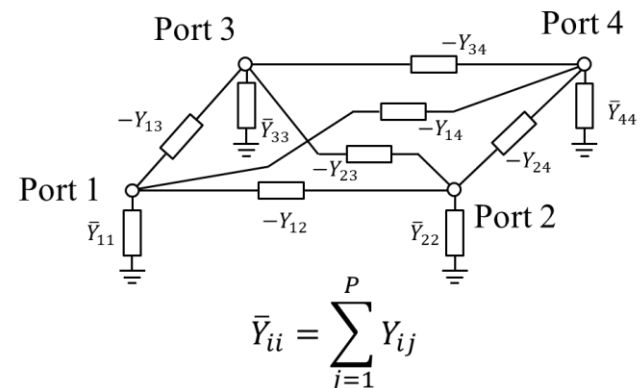
$$\left\{ \begin{array}{l} A' = A - B(I + D)^{-1}C \\ B' = \frac{1}{\sqrt{Z_0}} B(I + D)^{-1} \\ C' = \frac{-2}{\sqrt{Z_0}} (I + D)^{-1}C \\ D' = \frac{1}{Z_0} (I - D)(I + D)^{-1} \end{array} \right.$$

Diagonalization

Pole-residue for Y matrix

$$Y_{ij} = d^{(ij)} + \sum_{k=1}^N \frac{r_k^{(ij)}}{s - p_k^{(ij)}}$$

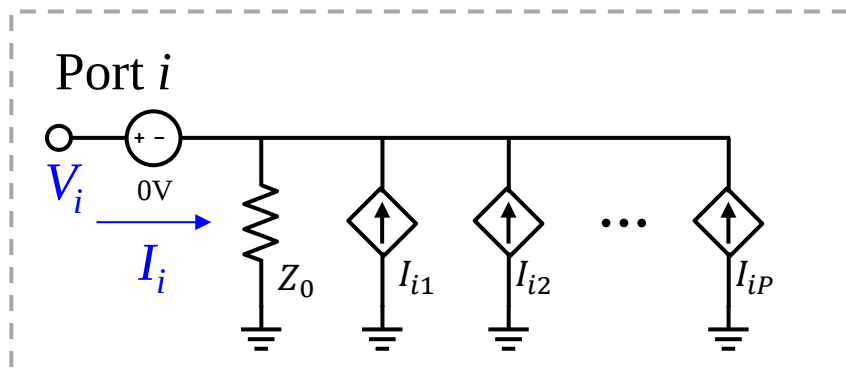
PI model



Problem: $(I + D)$ may be singular!

Model 5. Pole-residue S-as-Y (minimized for SISO pole)

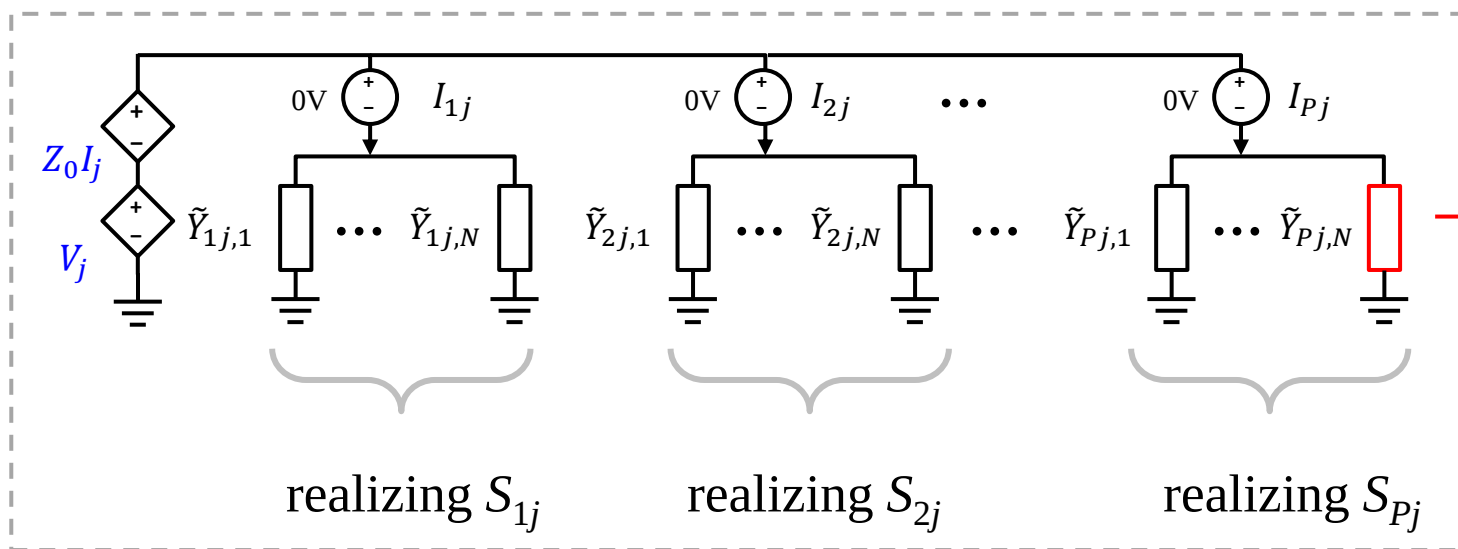
Port sections: $i = 1, 2, \dots, P$



Use the same approach
as model 1 (Y branch)

$$\tilde{Y}_{ij,k} \triangleq \frac{1}{Z_0} S_{ij,k}$$

Intermediate stages: $j = 1, 2, \dots, P$

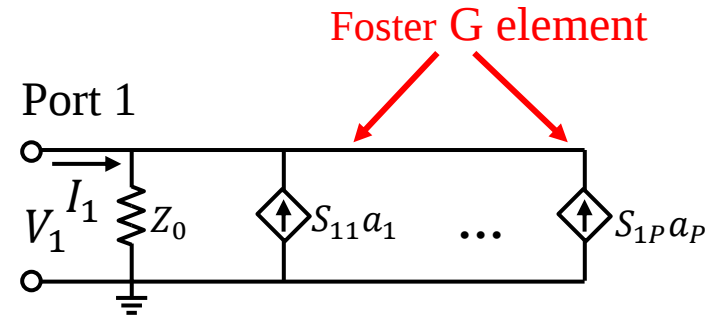
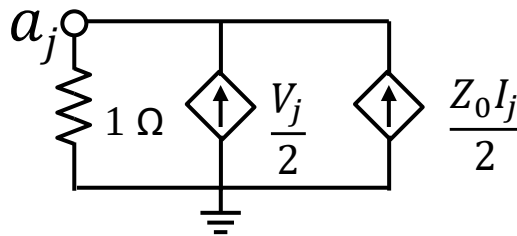


Model 6. Direct pole-residue specification (permit recursive convolution)

$$S_{ij} = d^{(ij)} + \sum_{k=1}^N \frac{r_k^{(ij)}}{s - p_k^{(ij)}}$$

Not all simulator
support this format!

Incident wave calculator for each port



```

Gs_1_1  gnd_0  p_1  FOSTER  inc_1  0  -5.692434755414126e-03  0
+ ( -2.439150431856222e+04, 0 ) / ( -4.960476041619210e+07, 0 )
+ ( 6.160731778543656e+07, 0 ) / ( -1.714170394664603e+09, 0 )
+ ( -1.894788422520538e+07, 5.662293766458602e+07 ) / ( -1.67218
+ ( 8.713966348296802e+07, -8.139622129292254e+07 ) / ( -1.84733
+ ( 2.617173411981527e+08, 1.358464434932994e+08 ) / ( -2.17708
+ ( 1.633543792451439e+07, 6.271573488187740e+08 ) / ( -2.57889
+ ( -7.925453224991798e+08, -3.731457479447733e+07 ) / ( -2.81115
+ ( -1.393416945756004e+08, -3.078398088322048e+08 ) / ( -2.26115
+ ( 3.612283069470346e+06, -4.993908414386742e+06 ) / ( -1.357632
+ ( -1.359750933146977e+07, -2.875752648146065e+08 ) / ( -2.39584
    
```

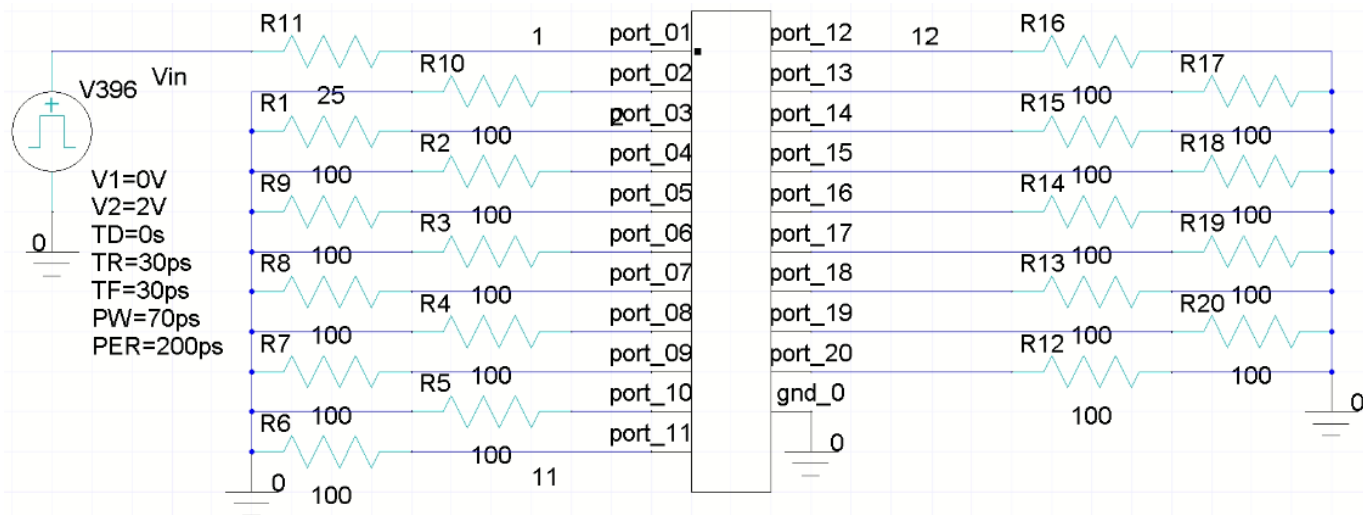
Comparison

	Model 2	Model 3	Model 4	Model 5	Model 6
	PI network for S by Y + VCSV+CCVS	State- space S	State- space S to Y	Pole- residue S- as-Y	Direct pole- residue specification
Controlled sources	Yes	Yes	No	Yes	Yes
Negative RLC	Yes	No	Yes	Yes	No
Recursive convolution	No	No	No	No	Yes
Cross platform	Yes*	Yes	Yes*	Yes*	No

* if negative RLC permitted


 Offered by many commercial EDA tools.

Example: macromodel of 20 ports and 110 MIMO poles (10 coupled microstrips)



TRAN
Tstep = 1ps
Tstop = 100ns

Total simulation time (s)

	State-space S (model 3)	PI network (model 2)	Foster (model 6)
EDA Tool A	338	815	190
EDA Tool B	295	383	94
Ngspice	200	788	

Conclusion

- Many different ways to synthesize equivalent circuits for S-parameters in pole-residue form
- Considerations for choosing circuit topology
 - Want recursive convolution?
 - Want cross platform exchangeability?
 - Controlled source and negative RLC acceptable?
 - SISO or MIMO pole-residue model?