**IBIS**

**(I/O Buffer Information Specification)**

**Version 6.0**

**Draft 1**

Ratified XXX XX, XXXX

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# General Introduction

This section gives a general overview of the remainder of this document.

Sections 2 and 3 contain general information about the IBIS versions and the general rules and guidelines. Several progressions of IBIS documents are referenced in Section 2 and in the discussion below. They are IBIS Version 1.1 (ratified August 1993), IBIS Version 2.1 (ratified as ANSI/EIA-656 in December 1995), IBIS Version 3.2 (ratified as ANSI/EIA-656-A in October 1999 and renewed on August 17, 2005), IBIS Version 4.2 (ratified as ANSI/EIA-656-B on March 1, 2007), IBIS Version 5.0 (ratified on August 29, 2008) and IBIS Version 5.1 (ratified on August 24, 2012)

The functionality of IBIS follows in Sections 3A through 8. Sections 3A through 6 describe the format of the core functionality of IBIS Version 1.1 and the extensions in later versions. The data in these sections are contained in .ibs files. Section 7 describes the package model format of IBIS Version 2.1 and a subsequent extension. Package models can be formatted within .ibs files or can be formatted (along with the Section file header keywords) as .pkg files. Section 8 contains the Electrical Board Description format of IBIS Version 3.2. Along with Section 4 header information, electrical board descriptions must be contained in separate .ebd files.

Sections 6C, 10, and 12 are new in IBIS Version 5.0 and contain reference and modeling information related to the algorithmic modeling interface (AMI) support, and EMI parameters. Sections 6D and 10A are new in IBIS Version 5.1, to place test loads and data appropriately in the keyword hierarchy and to more fully describe algorithmic models, respectively.

Section 9 contains some notes regarding the extraction conditions and data requirements for IBIS. This section focuses on implementation conditions based on measurement or simulation for gathering the IBIS compliant data.

# Statement of Intent

In order to enable an industry standard method to electronically transport IBIS modeling data between semiconductor vendors, EDA tool vendors, and end customers, this template is proposed. The intention of this template is to specify a consistent format that can be parsed by software, allowing EDA tool vendors to derive models compatible with their own products.

One goal of this template is to represent the current state of IBIS data, while allowing a growth path to more complex models/methods (when deemed appropriate). This would be accomplished by a revision of the base template, and possibly the addition of new keywords or categories.

Another goal of this template is to ensure that it is simple enough for semiconductor vendors and customers to use and modify, while ensuring that it is rigid enough for EDA tool vendors to write reliable parsers.

Finally, this template is meant to contain a complete description of the I/O elements on an entire component. Consequently, several models will need to be defined in each file, as well as a table that equates the appropriate buffer to the correct pin and signal name.

Version 5.1 of this electronic template was finalized by an industry-wide group of experts representing various companies and interests. Regular “IBIS Open Forum” meetings were held to accomplish this task.

**Commitment to Backward Compatibility**. Version 1.0 is the first valid IBIS ASCII file format. It represents the minimum amount of I/O buffer information required to create an accurate IBIS model of common CMOS and bipolar I/O structures. Future revisions of the ASCII file will add items considered to be “enhancements” to Version 1.0 to allow accurate modeling of new, or other I/O buffer structures. Consequently, all future revisions will be considered supersets of Version 1.0, allowing backward compatibility. In addition, as modeling platforms develop support for revisions of the IBIS ASCII template, all previous revisions of the template must also be supported.

**Version 1.1 update**. Version 1.1, (published as “ver1\_1.ibs”) is conceptually the same as the 1.0 version of the IBIS ASCII format (published as "ver1\_0.ibs"). However, various comments have been added for further clarification.

**Version 2.0 update**. Version 2.0 maintains backward compatibility with Versions 1.0 and 1.1. All new keywords and elements added in Version 2.0 are optional. A complete list of changes to the specification is in the IBIS Version 2.0 Release Notes document (“ver2\_0.rn.txt”).

**Version 2.1 update**. Version 2.0 contains clarification text changes, corrections, and two additional waveform parameters beyond Version 2.0.

**Version 3.0 update**. Version 3.0 adds a number of new keywords and functionality. A complete list of functions can be found on eda.org under /pub/ibis/birds/birddir.txt showing the approved Buffer Issue Resolution Documents (BIRDs) that have been approved for Version 3.0.

**Version 3.1 update**. Version 3.1 contains a major reformatting of the document and a simplification of the wording. It also contains some new technical enhancements that were unresolved when Version 3.0 was approved.

**Version 3.2 update**. Version 3.2 adds more technical advances and also a number of editorial changes documented in 12 BIRDs and also in responses to public letter ballot comments.

**Version 4.0 update**. Version 4.0 adds more technical advances and a few editorial changes documented in 11 BIRDs.

**Version 4.1 update**. Version 4.1 adds more technical advances and a few editorial changes documented in 10 BIRDs.

**Version 4.2 Update**. Version 4.2 adds more technical advances and some editorial changes documented in 13 BIRDs.

**Version 5.0 Update**. Version 5.0 adds more technical advances and some editorial changes documented in 10 BIRDs.

**Version 5.1 Update**. Version 5.1 adds more technical advances and some editorial changes documented in 23 BIRDs. Additionally, Version 5.1 uses a new document format.

**Version 6.0 Update**. Version 6.0 adds more technical advances and some editorial changes documented in 6 BIRDs:

BIRD121.2 IBIS-AMI New Reserved Parameters for Data Management

BIRD123.5 IBIS-AMI New Reserved Parameters for Jitter/Noise

BIRD152 Analog Model Boundary Definition

BIRD154.1 Using IBIS-AMI Leak List\_Tip in List Parameters

BIRD156.3 IBIS-AMI Extension for Mid-channel Redrivers and Retimers

BIRD160.1 Analog Buffer Modeling Improvements

# General Syntax Rules and Guidelines

This section contains general syntax rules and guidelines for ASCII .ibs files:

1. The content of the files is case sensitive, except for reserved words and keywords.
2. The following words are reserved words and must not be used for any other purposes in the document:

POWER - reserved model name, used with power supply pins

GND - reserved model name, used with ground pins

NC - reserved model name, used with no-connect pins

NA - used where data not available,

CIRCUITCALL - used for circuit call references in Section 6B

1. To facilitate portability between operating systems, file names used in a .ibs file must only have lower case characters. File names should have a basename of no more than forty (40) characters followed by a period (“.”), followed by a file name extension of no more than three characters. The file name and extension must use characters from the set (space, “ ”, 0x20 is not included):

a b c d e f g h i j k l m n o p q r s t u v w x y z

0 1 2 3 4 5 6 7 8 9 \_ ^ $ ~ ! # % & - { } ) ( @ ‘ `

The file name and extension are recommended to be lower case on systems that support such names.

1. A line of the file may have at most 120 characters, followed by a line termination sequence. The line termination sequence must be one of the following two sequences: a linefeed character or a carriage return followed by linefeed character.
2. Anything following the comment character is ignored and considered a comment on that line. The default “|” (pipe) character can be changed by the keyword [Comment Char] to any other character. The [Comment Char] keyword can be used anywhere in the file as desired.
3. Keywords must be enclosed in square brackets, “[]”, and must start in column 1 of the line. No space or tab is allowed immediately after the opening bracket “[” or immediately before the closing bracket “]”. If used, only one space (“ ”) or underscore (“\_”) character separates the parts of a multi-word keyword.
4. Underscores and spaces are equivalent in keywords. Spaces are not allowed in subparameter names.
5. Valid scaling factors are:

T = tera k = kilo n = nano

G = giga m = milli p = pico

M = mega u = micro f = femto

When no scaling factors are specified, the appropriate base units are assumed. (These are volts, amperes, ohms, farads, henries, and seconds.) The parser looks at only one alphabetic character after a numerical entry, therefore it is enough to use only the prefixes to scale the parameters. However, for clarity, it is allowed to use full abbreviations for the units, (e.g., pF, nH, mA, mOhm). In addition, scientific notation IS allowed (e.g., 1.2345e-12).

1. The I-V data tables should use enough data points around sharply curved areas of the I-V curves to describe the curvature accurately. In linear regions there is no need to define unnecessary data points.
2. The use of tab characters is legal, but they should be avoided as much as possible. This is to eliminate possible complications that might arise in situations when tab characters are automatically converted to multiple spaces by text editing, file transferring and similar software. In cases like that, lines might become longer than 120 characters, which is illegal in .ibs files.
3. Currents are considered positive when their direction is into the component.
4. All temperatures are represented in degrees Celsius.
5. Important supplemental information is contained in Section 9, “NOTES ON DATA DERIVATION METHOD”, concerning how data values are derived.
6. Only ASCII characters, as defined in ANSI Standard X3.4-1986, may be used in a .ibs file. The use of characters with codes greater than hexadecimal 07E is not allowed. Also, ASCII control characters (those numerically less than hexadecimal 20) are not allowed, except for tabs or in a line termination sequence. As mentioned in item 10 above, the use of tab characters is discouraged.
7. Keyword Hierarchy

.ibs FILE

├── File Header Section

│ ├── **[IBIS Ver]**

│ ├── **[Comment Char]**

│ ├── **[File Name]**

│ ├── **[File Rev]**

│ ├── **[Date]**

│ ├── **[Source]**

│ ├── **[Notes]**

│ ├── **[Disclaimer]**

│ └── **[Copyright]**

│

├── **[Component]** Si\_location, Timing\_location

│ ├── **[Manufacturer]**

│ ├── **[Package]** R\_pkg, L\_pkg, C\_pkg

│ ├── **[Pin]** signal\_name, model\_name, R\_pin,

│ │ L\_pin, C\_pin

│ ├── **[Package Model]**

│ │ └── **[Alternate Package Models]**

│ │ └── **[End Alternate Package Models]**

│ │

│ ├── **[Pin Mapping]** pulldown\_ref, pullup\_ref,

│ │ gnd\_clamp\_ref, power\_clamp\_ref,

│ │ ext\_ref

│ ├── **[Diff Pin]** inv\_pin, vdiff, tdelay\_typ,

│ │ tdelay\_min, tdelay\_max

│ ├── **[Repeater Pin]** tx\_non\_inv\_pin

│ ├── **[Series Pin Mapping]** pin\_2, model\_name,

│ │ function\_table\_group

│ ├── **[Series Switch Groups]** On, Off

│ │

│ ├── **[Node Declarations]**

│ │ └── **[End Node Declarations]**

│ │

│ ├── **[Circuit Call]** Signal\_pin, Diff\_signal\_pins,

│ │ │ Series\_pins, Port\_map

│ │ └── **[End Circuit Call]**

│ │

│ └── **[Begin EMI Component]** Domain, Cpd, C\_Heatsink\_gnd,

│ │ C\_Heatsink\_float

│ ├── **[Pin EMI]** domain\_name, clock\_div

│ ├── **[Pin Domain EMI]** percentage

│ └── **[End EMI Component]**

│

├── **[Model Selector]**

│

├── **[Model]** Model\_type, Polarity, Enable,

│ │ Vinl, Vinh, C\_comp, C\_comp\_pullup,

│ │ C\_comp\_pulldown,

│ │ C\_comp\_power\_clamp,

│ │ C\_comp\_gnd\_clamp

│ │ Vmeas, Cref, Rref, Vref

│ │ Rref\_diff, Cref\_diff

│ │

│ ├── **[Model Spec]** Vinh, Vinl, Vinh+, Vinh-, Vinl+,

│ │ Vinl-, S\_overshoot\_high,

│ │ S\_overshoot\_low, D\_overshoot\_high,

│ │ D\_overshoot\_low, D\_overshoot\_time,

│ │ D\_overshoot\_area\_h,

│ │ D\_overshoot\_area\_l,

│ │ D\_overshoot\_ampl\_h,

│ │ D\_overshoot\_ampl\_l,

│ │ Pulse\_high, Pulse\_low, Pulse\_time,

│ │ Vmeas, Cref, Rref, Vref, Cref\_rising,

│ │ Cref\_falling, Rref\_rising,

│ │ Rref\_falling, Vref\_rising,

│ │ Vref\_falling, Vmeas\_rising,

│ │ Vmeas\_falling,

│ │ Rref\_diff, Cref\_diff,

│ │ Weak\_R, Weak\_I, Weak\_V

│ ├── **[Receiver Thresholds]** Vth, Vth\_min, Vth\_max, Vinh\_ac,

│ │ Vinh\_dc, Vinl\_ac, Vinl\_dc,

│ │ Threshold\_sensitivity,

│ │ Reference\_supply, Vcross\_low,

│ │ Vcross\_high, Vdiff\_ac, Vdiff\_dc,

│ │ Tslew\_ac, Tdiffslew\_ac

│ ├── **[Add Submodel]**

│ ├── **[Driver Schedule]**

│ ├── **[Temperature Range]**

│ ├── **[Voltage Range]**

│ ├── **[Pullup Reference]**

│ ├── **[Pulldown Reference]**

│ ├── **[POWER Clamp Reference]**

│ ├── **[GND Clamp Reference]**

│ ├── **[External Reference]**

│ ├── **[C Comp Corner]** C\_comp, C\_comp\_pullup,

│ │ C\_comp\_pulldown,

│ │ C\_comp\_power\_clamp,

│ │ C\_comp\_gnd\_clamp

│ ├── **[TTgnd]**

│ ├── **[TTpower]**

│ ├── **[Pulldown]**

│ ├── **[Pullup]**

│ ├── **[GND Clamp]**

│ ├── **[POWER Clamp]**

│ ├── **[ISSO PU]**

│ ├── **[ISSO PD]**

│ ├── **[Rgnd]**

│ ├── **[Rpower]**

│ ├── **[Rac]**

│ ├── **[Cac]**

│ ├── **[On]**

│ ├── **[Off]**

│ ├── **[R Series]**

│ ├── **[L Series]**

│ ├── **[Rl Series]**

│ ├── **[C Series]**

│ ├── **[Lc Series]**

│ ├── **[Rc Series]**

│ ├── **[Series Current]**

│ ├── **[Series MOSFET]** Vds

│ ├── [**Ramp]** dV/dt\_r, dV/dt\_f,

│ │ R\_load

│ ├── **[Rising Waveform]** R\_fixture, V\_fixture,

│ │ │ V\_fixture\_min, V\_fixture\_max,

│ │ │ C\_fixture, L\_fixture, R\_dut,

│ │ │ L\_dut, C\_dut

│ │ └── **[Composite Current]**

│ │

│ ├── **[Falling Waveform]** R\_fixture, V\_fixture,

│ │ │ V\_fixture\_min, V\_fixture\_max,

│ │ │ C\_fixture, L\_fixture, R\_dut,

│ │ │ L\_dut, C\_dut

│ │ └── **[Composite Current]**

│ │

│ ├── **[External Model]** Language, Corner, Parameters,

│ │ │ Ports, D\_to\_A, A\_to\_D

│ │ └── **[End External Model]**

│ │

│ ├── **[Algorithmic Model]** Executable

│ │ └── **[End Algorithmic Model]**

│ │

│ └── **[Begin EMI Model]** Model\_emi\_type, Model\_Domain

│ └── **[End EMI Model]**

│

├── **[Submodel]** Submodel\_type

│ ├── **[Submodel Spec]** V\_trigger\_r, V\_trigger\_f,

│ │ Off\_delay

│ ├── **[POWER Pulse Table]**

│ ├── **[GND Pulse Table]**

│ ├── **[Pulldown]**

│ ├── **[Pullup]**

│ ├── **[GND Clamp]**

│ ├── **[POWER Clamp]**

│ ├── **[Ramp]** dV/dt\_r, dV/dt\_f, R\_load

│ ├── **[Rising Waveform]** R\_fixture, V\_fixture,

│ │ V\_fixture\_min, V\_fixture\_max,

│ │ C\_fixture, L\_fixture, R\_dut, L\_dut,

│ │ C\_dut

│ └── **[Falling Waveform]** R\_fixture, V\_fixture,

│ V\_fixture\_min, V\_fixture\_max,

│ C\_fixture, L\_fixture, R\_dut, L\_dut,

│ C\_dut

│

├── **[External Circuit]** Language, Corner, Parameters,

│ │ Ports, D\_to\_A, A\_to\_D

│ └── **[End External Circuit]**

│

├── **[Test Data]** Test\_data\_type, Driver\_model,

│ │ Driver\_model\_inv, Test\_load

│ ├── **[Rising Waveform Near]**

│ ├── **[Falling Waveform Near]**

│ ├── **[Rising Waveform Far]**

│ ├── **[Falling Waveform Far]**

│ ├── **[Diff Rising Waveform Near]**

│ ├── **[Diff Falling Waveform Near]**

│ ├── **[Diff Rising Waveform Far]**

│ └── **[Diff Falling Waveform Far]**

│

├── **[Test Load]** Test\_load\_type, C1\_near, Rs\_near,

│ Ls\_near, C2\_near, Rp1\_near,

│ Rp2\_near, Td, Zo, Rp1\_far,

│ Rp2\_far, C2\_far, Ls\_far, Rs\_far,

│ C1\_far, V\_term1, V\_term2,

│ Receiver\_model,

│ Receiver\_model\_inv, R\_diff\_near,

│ R\_diff\_far

│

├── **[Define Package Model]**

│ ├── **[Manufacturer]**

│ ├── **[OEM]**

│ ├── **[Description]**

│ ├── **[Number Of Sections]**

│ ├── **[Number Of Pins]**

│ ├── **[Pin Numbers]** Len, L, R, C, Fork, Endfork

│ ├── **[Model Data]**

│ │ ├── **[Resistance Matrix]** Banded\_matrix, Sparse\_matrix,

│ │ │ │ Full\_matrix

│ │ │ ├── **[Bandwidth]**

│ │ │ └── **[Row]**

│ │ │

│ │ ├── **[Inductance Matrix]** Banded\_matrix, Sparse\_matrix,

│ │ │ │ Full\_matrix

│ │ │ ├── **[Bandwidth]**

│ │ │ └── **[Row]**

│ │ │

│ │ ├── **[Capacitance Matrix]** Banded\_matrix, Sparse\_matrix,

│ │ │ │ Full\_matrix

│ │ │ ├── **[Bandwidth]**

│ │ │ └── **[Row]**

│ │ │

│ │ └── **[End Model Data]**

│ │

│ └── **[End Package Model]**

│

└── **[End]**

.pkg FILE

├── File Header Section

│ ├── **[IBIS Ver]**

│ ├── **[Comment Char]**

│ ├── **[File Name]**

│ ├── **[File Rev]**

│ ├── **[Date]**

│ ├── **[Source]**

│ ├── **[Notes]**

│ ├── **[Disclaimer]**

│ └── **[Copyright]**

│

├── **[Define Package Model]**

│ ├── **[Manufacturer]**

│ ├── **[OEM]**

│ ├── **[Description]**

│ ├── **[Number Of Sections]**

│ ├── **[Number Of Pins]**

│ ├── **[Pin Numbers]** Len, L, R, C, Fork, Endfork

│ ├── **[Model Data]**

│ │ ├── **[Resistance Matrix]** Banded\_matrix, Sparse\_matrix,

│ │ │ │ Full\_matrix

│ │ │ ├── **[Bandwidth]**

│ │ │ └── **[Row]**

│ │ │

│ │ ├── **[Inductance Matrix]** Banded\_matrix, Sparse\_matrix,

│ │ │ │ Full\_matrix

│ │ │ ├── **[Bandwidth]**

│ │ │ └── **[Row]**

│ │ │

│ │ ├── **[Capacitance Matrix]** Banded\_matrix, Sparse\_matrix,

│ │ │ │ Full\_matrix

│ │ │ ├── **[Bandwidth]**

│ │ │ └── **[Row]**

│ │ │

│ │ └── **[End Model Data]**

│ │

│ └── **[End Package Model]**

│

└── **[End]**

.ebd FILE

├── File Header Section

│ ├── **[IBIS Ver]**

│ ├── **[Comment Char]**

│ ├── **[File Name]**

│ ├── **[File Rev]**

│ ├── **[Date]**

│ ├── **[Source]**

│ ├── **[Notes]**

│ ├── **[Disclaimer]**

│ └── **[Copyright]**

│

├── **[Begin Board Description]**

│ ├── **[Manufacturer]**

│ ├── **[Number of Pins]**

│ ├── **[Pin List]** signal\_name

│ ├── **[Path Description]** Len, L, R, C, Fork, Endfork, Pin,

│ │ Node

│ ├── **[Reference Designator Map]**

│ └── **[End Board Description]**

│

└── **[End]**

# File Header Information

*Keyword:* [IBIS Ver]

*Required:* Yes

*Description:* Specifies the IBIS template version. This keyword informs electronic parsers of the kinds of data types that are present in the file.

*Usage Rules:* [IBIS Ver] must be the first keyword in any .ibs file. It is normally on the first line of the file, but can be preceded by comment lines that must begin with a “|”.

*Example:*

[IBIS Ver] 5.1 | Used for template variations

*Keyword:* [Comment Char]

*Required:* No

*Description:* Defines a new comment character to replace the default “|” (pipe) character, if desired.

*Usage Rules:* The new comment character to be defined must be followed by the underscore character and the letters “char”. For example: “|\_char” redundantly redefines the comment character to be the pipe character. The new comment character is in effect only following the [Comment Char] keyword. The following characters MAY be used:

! " # $ % & ' ( ) \* , : ; < > ? @ \ ^ ` { | } ~

*Other Notes:* The [Comment Char] keyword can be used anywhere in the file, as desired.

*Example:*

[Comment Char] |\_char

*Keyword:* [File Name]

*Required:* Yes

*Description:* Specifies the name of the .ibs file.

*Usage Rules:* The file name must conform to the rules in paragraph 3 of Section 3, "GENERAL SYNTAX RULES AND GUIDELINES". In addition, the file name must use the extension “.ibs”, “.pkg”, or “.ebd”. The file name must be the actual name of the file.

*Example:*

[File Name] ver5\_1.ibs

*Keyword:* [File Rev]

*Required:* Yes

*Description:* Tracks the revision level of a particular .ibs file.

*Usage Rules:* Revision level is set at the discretion of the engineer defining the file. The following guidelines are recommended:

0.x silicon and file in development

1.x pre-silicon file data from silicon model only

2.x file correlated to actual silicon measurements

3.x mature product, no more changes likely

*Example:*

[File Rev] 1.0 | Used for .ibs file variations

*Keywords:* [Date], [Source], [Notes], [Disclaimer], [Copyright]

*Required:* No

*Description:* Optionally clarifies the file.

*Usage Rules:* The keyword arguments can contain blanks, and be of any format. The [Date] keyword argument is limited to a maximum of 40 characters, and the month should be spelled out for clarity.

Because IBIS model writers may consider the information in these keywords essential to users, and sometimes legally required, design automation tools should make this information available. Derivative models should include this text verbatim. Any text following the [Copyright] keyword must be included, verbatim, in any derivative models.

*Examples:*

[Date] August 24, 2012 | The latest file revision date

|

[Source] Put originator and the source of information here. For

example:

From silicon level SPICE model at NoName.

From lab measurement.

Compiled from manufacturer's data book, etc.

|

[Notes] Use this section for any special notes related to the file.

|

[Disclaimer] This information is for modeling purposes only, and is not

guaranteed. | May vary by component

|

[Copyright] Copyright 2012, XYZ Corp., All Rights Reserved

# Component Description

*Keyword:* [Component]

*Required:* Yes

*Description:* Marks the beginning of the IBIS description of the integrated circuit named after the keyword.

*Sub-Params:* Si\_location, Timing\_location

*Usage Rules:* If the .ibs file contains data for more than one component, each section must begin with a new [Component] keyword. The length of the component name must not exceed 40 characters, and blank characters are allowed.

NOTE: Blank characters are not recommended due to usability issues.

Si\_location and Timing\_location are optional and specify where the Signal Integrity and Timing measurements are made for the component. Allowed values for either subparameter are “Die” or “Pin”. The default location is at the “Pin”.

*Example:*

[Component] 7403398 MC452

|

Si\_location Pin | Optional subparameters to give measurement

Timing\_location Die | location positions

*Keyword:* [Manufacturer]

*Required:* Yes

*Description:* Specifies the name of the component’s manufacturer.

*Usage Rules:* The length of the manufacturer’s name must not exceed 40 characters (blank characters are allowed, e.g., Texas Instruments). In addition, each manufacturer must use a consistent name in all .ibs files.

*Example:*

[Manufacturer] NoName Corp.

*Keyword:* [Package]

*Required:* Yes

*Description:* Defines a range of values for the default packaging resistance, inductance, and capacitance of the component pins.

*Sub-Params:* R\_pkg, L\_pkg, C\_pkg

*Usage Rules:* The typical (typ) column must be specified. If data for the other columns are not available, they must be noted with “NA”.

*Other Notes:* If RLC parameters are available for individual pins, they can be listed in columns   
4-6 under keyword [Pin]. The values listed in the [Pin] description section override the default values defined here. Use the [Package Model] keyword for more complex package descriptions.   
If defined, the [Package Model] data overrides the values in the [Package] keyword. Regardless, the data listed under the [Package] keyword must still contain valid data.

*Example:*

[Package]

| variable typ min max

R\_pkg 250.0m 225.0m 275.0m

L\_pkg 15.0nH 12.0nH 18.0nH

C\_pkg 18.0pF 15.0pF 20.0pF

Keyword: [Pin]

*Required:* Yes

*Description:* Associates the component’s I/O models to its various external pin names and signal names.

*Sub-Params:* signal\_name, model\_name, R\_pin, L\_pin, C\_pin

*Usage Rules:* All pins on a component must be specified. The first column must contain the pin name. The second column, signal\_name, gives the data book name for the signal on that pin. The third column, model\_name, maps a pin to a specific I/O buffer model or model selector name. Each model\_name must have a corresponding model or model selector name listed in a [Model] or [Model Selector] keyword below, unless it is a reserved model name (POWER, GND, or NC).

The model\_name column cannot be used for model or model selector names that reference Series and Series\_switch models.

Each line must contain either three or six columns. A pin line with three columns only associates the pin’s signal and model. Six columns can be used to override the default package values (specified under [Package]) FOR THAT PIN ONLY. When using six columns, the headers R\_pin, L\_pin, and C\_pin must be listed. If “NA” is in columns 4 through 6, the default packaging values must be used. The headers R\_pin, L\_pin, and C\_pin may be listed in any order.

Column length limits are:

[Pin] 5 characters max

model\_name 40 characters max

signal\_name 40 characters max

R\_pin 9 characters max

L\_pin 9 characters max

C\_pin 9 characters max

*Example:*

[Pin] signal\_name model\_name R\_pin L\_pin C\_pin

|

1 RAS0# Buffer1 200.0m 5.0nH 2.0pF

2 RAS1# Buffer2 209.0m NA 2.5pF

3 EN1# Input1 NA 6.3nH NA

4 A0 3-state

5 D0 I/O1

6 RD# Input2 310.0m 3.0nH 2.0pF

7 WR# Input2

8 A1 I/O2

9 D1 I/O2

10 GND GND 297.0m 6.7nH 3.4pF

11 RDY# Input2

12 GND GND 270.0m 5.3nH 4.0pF

| .

| .

| .

18 Vcc3 POWER

19 NC NC

20 Vcc5 POWER 226.0m NA 1.0pF

21 BAD1 Series\_switch1 | Illegal assignment

22 BAD2 Series\_selector1 | Illegal assignment

*Keyword:* [Package Model]

*Required:* No

*Description:* Indicates the name of the package model to be used for the component.

*Usage Rules:* The package model name is limited to 40 characters. Spaces are allowed in the name. The name should include the company name or initials to help ensure uniqueness. The EDA tool will search for a matching package model name as an argument to a [Define Package Model] keyword in the current .ibs file first. If a match is not found, the EDA tool will next look for a match in an external .pkg file. If the matching package model is in an external .pkg file, it must be located in the same directory as the .ibs file. The file names of .pkg files must follow the rules for file names given in Section 3, "GENERAL SYNTAX RULES AND GUIDELINES".

*Other Notes:* Use the [Package Model] keyword within a [Component] to indicate which package model should be used for that component. The specification permits .ibs files to contain [Define Package Model] keywords as well. These are described under “Package Modeling” in Section 7. When package model definitions occur within a .ibs file, their scope is “local”, i.e., they are known only within that .ibs file and no other. In addition, within that .ibs file, they override any globally defined package models that have the same name.

*Example:*

[Package Model] QS-SMT-cer-8-pin-pkgs

*Keywords:* [Alternate Package Models], [End Alternate Package Models]

*Required:* No

*Description:* Used to select a package model from a list of package models.

*Usage Rules:* The [Alternate Package Models] keyword can be used in addition to the [Package Model] keyword. [Alternate Package Models] shall be used only for components that use the [Package Model] keyword.

Each [Alternate Package Models] keyword specifies a set of alternate package model names for only one component, which is given by the previous [Component] keyword. The [Alternate Package Models] keyword shall not appear before the first [Component] keyword in a .ibs file. The [Alternate Package Models] keyword applies only to the [Component] section in which it appears, and must be followed by an [End Alternate Package Models] keyword.

All alternate package model names must appear below the [Alternate Package Models] keyword, and above the following [End Alternate Package Models] keyword. The package model names listed under the [Alternate Package Models] must follow the rules of the package model names associated with the [Package Model] keyword. The package model names correspond to the names of package models defined by [Define Package Model] keywords. EDA tools may offer users a facility for choosing between the default package model and any of the alternate package models, when analyzing occurrences of the [Component].

The package model named by [Package Model] can be optionally repeated in the [Alternate Package Models] list of names.

*Example:*

[Alternate Package Models]

|

208-pin\_plastic\_PQFP\_package-even\_mode | Descriptive names are shown

208-pin\_plastic\_PQFP\_package-odd\_mode

208-pin\_ceramic\_PQFP\_package-even\_mode

208-pin\_ceramic\_PQFP\_package-odd\_mode

|

[End Alternate Package Models]

*Keyword:* [Pin Mapping]

*Required:* No

*Description:* Used to indicate the power and/or ground buses to which a given driver, receiver or terminator is connected.

*Sub-Params:* pulldown\_ref, pullup\_ref, gnd\_clamp\_ref, power\_clamp\_ref, ext\_ref

*Usage Rules:* The [Pin Mapping] keyword names the connections between POWER and/or GND pins and buffer and/or terminator voltage supply references using unique bus labels. All buses with identical labels are assumed to be connected with an ideal short. Each label must be associated with at least one pin whose model\_name is POWER or GND. Bus labels must not exceed 15 characters.

Each line must contain either three, five or six entries. Use the reserved word NC where an entry is required but a bus connection is not made.

The first column contains a pin name. Each pin name must match one of the pin names declared in the [Pin] section of the [Component].

For buffers and terminators, the remaining columns correspond to the voltage supply references for the named pin. Each [Model] supply reference is connected to a particular bus through a bus label in the corresponding column.

The second column, pulldown\_ref, designates the ground bus connections for the buffer or termination associated with that pin. The bus named under pulldown\_ref is associated with the [Pulldown] I-V table for non-ECL [Model]s. This is also the bus associated with the [GND Clamp] I-V table and the [Rgnd] model unless overridden by a label in the gnd\_clamp\_ref column.

The third column, pullup\_ref, designates the power bus connection for the buffer or termination. The bus named under pullup\_ref is associated with the [Pullup] table for non-ECL [Model]s (for ECL models, this bus is associated with the [Pulldown] table). This is also the bus label associated with the [POWER Clamp] I-V table and the [Rpower] model unless overridden by a label in the power\_clamp\_ref column.

The fourth and fifth columns, gnd\_clamp\_ref and power\_clamp\_ref, contain entries, if needed, to specify additional ground bus and power bus connections for clamps. Finally, the sixth column, ext\_ref, contains entries to specify external reference supply bus connections.

The usage of the columns changes for GND and POWER pins. For GND pins, the pulldown\_ref column contains the name of the bus to which the pin connects; the pullup\_ref column in this case must contain the reserved word NC. Similarly, for POWER (including external reference) pins, the pullup\_ref column contains the name of the bus to which the pin connects; the pulldown\_ref column in this case must contain the reserved word NC.

If the [Pin Mapping] keyword is present, then the bus connections for EVERY pin listed under the [Pin] keyword must be given.

If a pin has no connection, then both the pulldown\_ref and pullup\_ref subparameters for it will be NC.

The column length limits are:

[Pin Mapping] 5 characters max

pulldown\_ref 15 characters max

pullup\_ref 15 characters max

gnd\_clamp\_ref 15 characters max

power\_clamp\_ref 15 characters max

ext\_ref 15 characters max

For compatibility with models developed under previous IBIS versions, [Pin Mapping] lines which contain ext\_ref column entries must also explicitly include entries for the pulldown\_ref, pullup\_ref, gnd\_clamp\_ref and power\_clamp\_ref columns. These entries can be NC.

When six columns of data are specified, the headings gnd\_clamp\_ref, power\_clamp\_ref and ext\_ref must be used on the line containing the [Pin Mapping] keyword. Otherwise, these headings can be omitted.

*Example:*

[Pin Mapping] pulldown\_ref pullup\_ref gnd\_clamp\_ref power\_clamp\_ref ext\_ref

|

1 GNDBUS1 PWRBUS1 | Signal pins and their associated

2 GNDBUS2 PWRBUS2 | ground, power and external

| | reference connections

3 GNDBUS1 PWRBUS1 GNDCLMP PWRCLAMP

4 GNDBUS2 PWRBUS2 GNDCLMP PWRCLAMP

5 GNDBUS2 PWRBUS2 NC PWRCLAMP REFBUS1

6 GNDBUS2 PWRBUS2 GNDCLMP NC

7 GNDBUS2 PWRBUS2 GNDCLMP NC REFBUS2

| | Some possible clamping

| | connections are shown above

| . | for illustration purposes

| .

11 GNDBUS1 NC | One set of ground connections.

12 GNDBUS1 NC | NC indicates no connection to

13 GNDBUS1 NC | power bus.

| .

21 GNDBUS2 NC | Second set of ground connections

22 GNDBUS2 NC

23 GNDBUS2 NC

| .

31 NC PWRBUS1 | One set of power connections.

32 NC PWRBUS1 | NC indicates no connection to

33 NC PWRBUS1 | ground bus.

| .

41 NC PWRBUS2 | Second set of power connections

42 NC PWRBUS2

43 NC PWRBUS2

| .

51 GNDCLMP NC | Additional power connections

52 NC PWRCLMP | for clamps

|

| .

71 NC REFBUS1 | External reference connections

72 NC REFBUS2

|

| The following [Pin] list corresponds to the [Pin Mapping] shown above.

|

[Pin] signal\_name model\_name R\_pin L\_pin C\_pin

|

1 OUT1 output\_buffer1 | Output buffers

2 OUT2 output\_buffer2 |

3 IO3 io\_buffer1 | Input/output buffers

4 IO4 io\_buffer2 |

5 SPECIAL1 ref\_buffer1 | Buffers with POWER CLAMP but no

6 SPECIAL2 io\_buffer\_term1 | GND CLAMP I-V tables; two use

7 SPECIAL3 ref\_buffer2 | external reference voltages

11 VSS1 GND

12 VSS1 GND

13 VSS1 GND

21 VSS2 GND

22 VSS2 GND

23 VSS2 GND

31 VCC1 POWER

32 VCC1 POWER

33 VCC1 POWER

41 VCC2 POWER

42 VCC2 POWER

43 VCC2 POWER

51 VSSCLAMP GND | Power connections for clamps

52 VCCCLAMP POWER |

71 V\_EXTREF1 POWER | External reference voltage pins

72 V\_EXTREF2 POWER |

*Keyword:* [Diff Pin]

*Required:* No

*Description:* Associates differential pins and defines their differential receiver threshold voltage and differential driver timing delays.

*Sub-Params:* inv\_pin, vdiff, tdelay\_typ, tdelay\_min, tdelay\_max

*Usage Rules:* Enter only differential pin pairs. The first column, [Diff Pin], contains a non-inverting pin name. The second column, inv\_pin, contains the corresponding inverting pin name for I/O output. Each pin name must match the pin names declared previously in the [Pin] section of the .ibs file. The third column, vdiff, contains the specified differential receiver threshold voltage between the inverting and non-inverting pins for Input or I/O model types. The fourth, fifth, and sixth columns, tdelay\_typ, tdelay\_min, and tdelay\_max, contain launch delays of the non-inverting pins relative to the inverting pins. All of the numerical entries may be a positive, zero, or negative number.

For differential Input or I/O model types, the differential input threshold (vdiff) overrides and supersedes the need for Vinh and Vinl.

*Other Notes:* The output pin polarity specification in the table overrides the [Model] Polarity specification such that the pin in the [Diff Pin] column is Non-Inverting and the pin in the inv\_pin column is Inverting. This convention enables one [Model] to be used for both pins.

The column length limits are:

[Diff Pin] 5 characters max

inv\_pin 5 characters max

vdiff 9 characters max

tdelay\_typ 9 characters max

tdelay\_min 9 characters max

tdelay\_max 9 characters max

Each line must contain either four or six columns. Using four columns is an equivalent of entering “NA”s in the fifth and sixth columns. An “NA” in the vdiff column will be interpreted as a 200 mV default differential receiver threshold. “NA”s in the tdelay\_typ, or tdelay\_min columns are interpreted as 0 ns. If “NA” appears in the tdelay\_max column, its value is interpreted as the tdelay\_typ value. When using six columns, the headers tdelay\_min and tdelay\_max must be listed. Entries for the tdelay\_min column are based on minimum magnitudes; and tdelay\_max column, maximum magnitudes. One entry of vdiff, regardless of its polarity, is used for difference magnitudes.

When a [Model] that is associated with any of the pins listed under the [Diff Pin] keyword contains the [Algorithmic Model] keyword, the tdelay\_\*\*\* parameters in the fourth, fifth and sixth columns of the [Diff Pin] keyword are ignored in algorithmic model interface (AMI) channel characterization simulations, i.e., they are treated as if their value would be zero.

The positioning of numerical entries and/or “NA” must not be used as an indication for the model type. The model type is determined by the model type parameter inside the [Model]s referenced by the [Diff Pin] keyword, regardless of what the [Diff Pin]’s entries are. The simulator may ignore the vdiff or the tdelay\_\*\*\* parameters if not needed by the model type of the [Model], or use the default values defined above if they are needed but not provided in the [Diff Pin] keyword. For example, an “NA” in the third column (vdiff) does not imply that the model type is Output, or three “NA”s in the tdelay columns does not mean that the model type is Input.

Note that the starting point of the flight time measurements will occur when the differential driver’s output waveforms are crossing, i.e., when the differential output voltage is zero, and consequently Vmeas, if defined, will be ignored.

*Example:*

[Diff Pin] inv\_pin vdiff tdelay\_typ tdelay\_min tdelay\_max

|

3 4 150mV -1ns 0ns -2ns

| For Input, tdelay\_typ/min/max ignored

| For Output, vdiff ignored

|

7 8 0V 1ns NA NA

16 15 200mV 1ns

| For Input, tdelay\_typ ignored

| For Output, vdiff ignored and tdelay\_min = 0ns and tdelay\_max = 1ns

| For I/O, tdelay\_min = 0ns and tdelay\_max = 1ns

|

9 10 NA NA NA NA

22 21 NA NA

| For Input, vdiff = 200 mV

| For Output, tdelay\_typ/min/max = 0ns

| For I/O, vdiff = 200 mV and tdelay\_typ/min/max = 0ns

|

20 19 0V NA

| For Output, vdiff ignored and tdelay\_typ/min/max = 0ns

| For I/O, tdelay\_typ/min/max = 0ns

*Keyword:* [Repeater Pin]

*Required:* No

*Description:* Associates a differential Rx non-inv pin with a Tx non-inv pin to form a Repeater.

*Sub-Params:* tx\_non\_inv\_pin

*Usage Rules:* Enter only Repeater pin pairs. The first column, [Repeater Pin] contains a non-inv pin name of an entry in the [Diff Pin] section that represents an Input or Input\_diff model corresponding to the Rx part of the Repeater model. The second column, tx\_non\_inv\_pin contains a non-inv pin name of an entry in the [Diff Pin] section that represents an Output or Output\_diff model corresponding to the Tx part of the Repeater model.

*Other Notes:* Each line must contain two columns. A pin name may appear in only one [Repeater Pin] record.

The column length limits are:

[Repeater Pin] 5 characters max

tx\_non\_inv\_pin 5 characters max

*Example:*

[Repeater Pin] tx\_non\_inv\_pin

3 11

*Keyword:* [Series Pin Mapping]

*Required:* No

*Description:* Used to associate two pins joined by a series model.

*Sub-Params:* pin\_2, model\_name, function\_table\_group

*Usage Rules:* Enter only series pin pairs. The first column, [Series Pin Mapping], contains the series pin for which input impedances are measured. The second column, pin\_2, contains the other connection of the series model. Each pin must match the pin names declared previously in the [Pin] section of the .ibs file. The third column, model\_name, associates models of type Series or Series\_switch, or model selectors containing references to models of type Series or Series\_switch for the pair of pins in the first two columns. Each model\_name must have a corresponding model or model selector name listed in a [Model] or [Model Selector] keyword below. The usage of reserved model names (POWER, GND, or NC) within the [Series Pin Mapping] keyword is not allowed. The fourth column, function\_table\_group, contains an alphanumeric designator string to associate those sets of Series\_switch pins that are switched together.

Each line must contain either three or four columns. When using four columns, the header function\_table\_group must be listed.

One possible application is to model crossbar switches where the straight through On paths are indicated by one designator and the cross over On paths are indicated by another designator. If the model referenced is a Series model, then the function\_table\_group entry is omitted.

The column length limits are:

[Series Pin Mapping] 5 characters max

pin\_2 5 characters max

model\_name 40 characters max

function\_table\_group 20 characters max

*Other Notes:* If the model\_name is for a non-symmetrical series model, then the order of the pins is important. The [Series Pin Mapping] and pin\_2 entries must be in the columns that correspond with Pin 1 and Pin 2 of the referenced model.

This mapping covers only the series paths between pins. The package parasitics and any other elements such as additional capacitance or clamping circuitry are defined by the model\_name that is referenced in the [Pin] keyword. The model\_names under the [Pin] keyword that are also referenced by the [Series Pin Mapping] keyword may include any legal model or reserved model except for Series and Series\_switch models. Normally the pins will reference a [Model] whose Model\_type is “Terminator”. For example, a Series\_switch model may contain Terminator models on EACH of the pins to describe both the capacitance on each pin and some clamping circuitry that may exist on each pin. In a similar manner, Input, I/O or Output models may exist on each pin of a Series model that is serving as a differential termination.

Also, a pin name may appear on more than one entry under the [Series Pin Mapping] keyword. This allows for multiple and perhaps different models or model selectors to be placed between the same, or any arbitrary pin pair combinations.

*Example:*

[Series Pin Mapping] pin\_2 model\_name function\_table\_group

|

2 3 CBTSeries 1 | Four independent groups

5 6 CBTSeries 2

9 8 CBTSeries 3

12 11 CBTSeries 4

|

22 23 CBTSeries 5 | Straight through path

25 26 CBTSeries 5

22 26 CBTSeries 6 | Cross over path

25 23 CBTSeries 6

|

32 33 Fixed\_series | No group needed

*Keyword:* [Series Switch Groups]

*Required:* Yes, if function\_table\_group column data is present under [Series Pin Mapping]

*Description:* Used to define allowable switching combinations of series switches described using the names of the groups in the [Series Pin Mapping] keyword function\_table\_group column.

Sub-Params: On, Off

*Usage Rules:* Each state line contains an allowable configuration. A typical state line will start with “On” followed by all of the on-state group names or an “Off” followed by all of the off-state group names. Only one of “On” or “Off” is required since the undefined states are presumed to be opposite of the explicitly defined states. The state line is terminated with the slash “/”, even if it extends over several lines to fit within the 120 character column width restriction.

The group names in the function\_table\_group are used to associate switches whose switching action is synchronized by a common control function. The first line defines the assumed (default) state of the set of series switches. Other sets of states are listed and can be selected through a user interface or through automatic control.

*Example:*

[Series Switch Groups]

| Function Group States

On 1 2 3 4 / | Default setting is all switched On

|

Off 1 2 3 4 / | All Off setting

On 1 / | Other possible combinations below

On 2 /

On 3 /

On 4 /

On 1 2 /

On 1 3 /

On 1 4 /

On 2 3 /

On 2 4 /

On 3 4 /

On 1 2 3 /

On 1 2 4 /

On 1 3 4 /

On 2 3 4 /

| Off 4 / | The last four lines above could have been replaced

| Off 3 / | with these four lines with the same meaning.

| Off 2 /

| Off 1 /

|

On 5 / | Crossbar switch straight through connection

On 6 / | Crossbar cross over connection

Off 5 6 / | Crossbar open switches

*Keyword:* [Model Selector]

*Required:* No

*Description:* Used to pick a [Model] from a list of [Model]s for a pin which uses a programmable buffer.

*Usage Rules:* A programmable buffer must have an individual [Model] section for each one of its modes used in the .ibs file. The names of these [Model]s must be unique and can be listed under the [Model Selector] keyword and/or pin list. The name of the [Model Selector] keyword must match the corresponding model name listed under the [Pin] or [Series Pin Mapping] keyword and must not contain more than 40 characters. A .ibs file must contain enough [Model Selector] keywords to cover all of the model selector names specified under the [Pin] and [Series Pin Mapping] keywords.

The section under the [Model Selector] keyword must have two fields. The two fields must be separated by at least one white space. The first field lists the [Model] name (up to 40 characters long). The second field contains a short description of the [Model] shown in the first field. The contents and format of this description is not standardized, however it shall be limited in length so that none of the descriptions exceed the 120-character length of the line that it started on. The purpose of the descriptions is to aid the user of the EDA tool in making intelligent buffer mode selections and it can be used by the EDA tool in a user interface dialog box as the basis of an interactive buffer selection mechanism.

The first entry under the [Model Selector] keyword shall be considered the default by the EDA tool for all those pins which call this [Model Selector].

The operation of this selection mechanism implies that a group of pins which use the same programmable buffer (i.e., model selector name) will be switched together from one [Model] to another. Therefore, if two groups of pins, for example an address bus and a data bus, use the same programmable buffer, and the user must have the capability to configure them independently, one can use two [Model Selector] keywords with unique names and the same list of [Model] keywords; however, the usage of the [Model Selector] is not limited to these examples. Many other combinations are possible.

*Example:*

[Pin] signal\_name model\_name R\_pin L\_pin C\_pin

|

1 RAS0# Progbuffer1 200.0m 5.0nH 2.0pF

2 EN1# Input1 NA 6.3nH NA

3 A0 3-state

4 D0 Progbuffer2

5 D1 Progbuffer2 320.0m 3.1nH 2.2pF

6 D2 Progbuffer2

7 RD# Input2 310.0m 3.0nH 2.0pF

| .

| .

| .

18 Vcc3 POWER

|

[Model Selector] Progbuffer1

|

OUT\_2 2 mA buffer without slew rate control

OUT\_4 4 mA buffer without slew rate control

OUT\_6 6 mA buffer without slew rate control

OUT\_4S 4 mA buffer with slew rate control

OUT\_6S 6 mA buffer with slew rate control

|

[Model Selector] Progbuffer2

|

OUT\_2 2 mA buffer without slew rate control

OUT\_6 6 mA buffer without slew rate control

OUT\_6S 6 mA buffer with slew rate control

OUT\_8S 8 mA buffer with slew rate control

OUT\_10S 10 mA buffer with slew rate control

# Model Statement

*Keyword:* **[Model]**

*Required:* Yes

*Description:* Used to define a model, and its attributes.

*Sub-Params:* Model\_type, Polarity, Enable, Vinl, Vinh, C\_comp, C\_comp\_pullup, C\_comp\_pulldown, C\_comp\_power\_clamp, C\_comp\_gnd\_clamp, Vmeas, Cref, Rref, Vref

*Usage Rules:* Each model type must begin with the keyword [Model]. The model name must match the one that is listed under a [Pin], [Model Selector] or [Series Pin Mapping] keyword and must not contain more than 40 characters. A .ibs file must contain enough [Model] keywords to cover all of the model names specified under the [Pin], [Model Selector] and [Series Pin Mapping] keywords, except for those model names that use reserved words (POWER, GND and NC).

Model\_type must be one of the following:

Input, Output, I/O, 3-state, Open\_drain, I/O\_open\_drain, Open\_sink, I/O\_open\_sink, Open\_source, I/O\_open\_source, Input\_ECL, Output\_ECL, I/O\_ECL, 3-state\_ECL, Terminator, Series, and Series\_switch.

For true differential models documented under Section 6B, Model\_type must be one of the following:

Input\_diff, Output\_diff, I/O\_diff, and 3-state\_diff

Special usage rules for particular model types are provided in Table 1. Some definitions are included for clarification.

Table – Special Rules for Keyword [Model]

| **Model Type** | **Definition** |
| --- | --- |
| Input  I/O  I/O\_open\_drain  I/O\_open\_sink  I/O\_open\_source | These model types must have Vinl and Vinh defined. If they are not defined, the parser issues a warning and the default values of Vinl = 0.8 V and Vinh = 2.0 V are assumed. |
| Input\_ECL  I/O\_ECL | These model types must have Vinl and Vinh defined. If they are not defined, the parser issues a warning and the default values of Vinl = 0.8 V and Vinh = 2.0 V are assumed. |
| Terminator | This model type is an input-only model that can have analog loading effects on the circuit being simulated but has no digital logic thresholds. Examples of terminators are: capacitors, termination diodes, and pullup resistors. |
| Output | This model type indicates that an output always sources and/or sinks current and cannot be disabled. |
| 3-state | This model type indicates that an output can be disabled, i.e., put into a high impedance state. |
| Open\_sink  Open\_drain | These model types indicate that the output has an OPEN side (do not use the [Pullup] keyword, or if it must be used, set I = 0 mA for all voltages specified) and the output SINKS current. Open\_drain model type is retained for backward compatibility. |
| Open\_source | This model type indicates that the output has an OPEN side (do not use the [Pulldown] keyword, or if it must be used, set I = 0 mA for all voltages specified) and the output SOURCES current. |
| Input\_ECL  Output\_ECL  I/O\_ECL  3-state\_ECL | These model types specify that the model represents an ECL type logic that follows different conventions for the [Pulldown] keyword. |
| Series | This model type is for series models that can be described by [R Series], [L Series], [Rl Series], [C Series], [Lc Series], [Rc Series], [Series Current] and [Series MOSFET] keywords. |
| Series\_switch | This model type is for series switch models that can be described by [On], [Off], [R Series], [L Series], [Rl Series], [C Series], [Lc Series], [Rc Series], [Series Current] and [Series MOSFET] keywords. |
| Input\_diff  Output\_diff  I/O\_diff  3-state\_diff | These model types specify that the model defines a true differential model available directly through the [External Model] keyword documented in Section 6B. |

The Model\_type subparameter is required.

The C\_comp subparameter is required only when C\_comp\_pullup, C\_comp\_pulldown, C\_comp\_power\_clamp, and C\_comp\_gnd\_clamp are not present. If the C\_comp subparameter is not present, at least one of the C\_comp\_pullup, C\_comp\_pulldown, C\_comp\_power\_clamp, or C\_comp\_gnd\_clamp subparameters is required. It is not illegal to include the C\_comp subparameter together with one or more of the remaining C\_comp\_\* subparameters, but in that case the simulator will have to make a decision whether to use C\_comp or the C\_comp\_pullup, C\_comp\_pulldown, C\_comp\_power\_clamp, and C\_comp\_gnd\_clamp subparameters. Under no circumstances should the simulator use the value of C\_comp simultaneously with the values of the other C\_comp\_\* subparameters.

C\_comp\_pullup, C\_comp\_pulldown, C\_comp\_power\_clamp, and C\_comp\_gnd\_clamp are intended to represent the parasitic capacitances of those structures whose I-V characteristics are described by the [Pullup], [Pulldown], [POWER Clamp] and [GND Clamp] I-V tables. For this reason, the simulator should generate a circuit netlist so that, if defined, each of the C\_comp\_\* capacitors are connected in parallel with their corresponding I-V tables, whether or not the I-V table exists. That is, the C\_comp\_\* capacitors are positioned between the signal pad and the nodes defined by the [Pullup Reference], [Pulldown Reference], [POWER Clamp Reference] and [GND Clamp Reference] keywords, or the [Voltage Range] keyword and GND.

The C\_comp and C\_comp\_\* subparameters define die capacitance. These values should not include the capacitance of the package. C\_comp and C\_comp\_\* are allowed to use “NA” for the min and max values only.

The Polarity, Enable, Vinl, Vinh, Vmeas, Cref, Rref, and Vref subparameters are optional.

Also, optional Rref\_diff and Cref\_diff subparameters discussed further in Section 6B support the true differential buffer timing test loads. They are used only when the [Diff Pin] keyword connects two models, and each buffer references the same model. The Rref\_diff and Cref\_diff subparameters can be used with the Rref, Cref, and Vref subparameters for a combined differential and signal-ended timing test load. Single-ended test loads are permitted for differential applications.

The Rref\_diff and Cref\_diff are recognized only when the [Diff Pin] keyword connects the models. This applies for the true differential buffers in Section 6B and also for differential buffers using identical single-ended models.

The Polarity subparameter can be defined as either Non-Inverting or Inverting, and the Enable subparameter can be defined as either Active-High or Active-Low.

The Cref and Rref subparameters correspond to the test load that the semiconductor vendor uses when specifying the propagation delay and/or output switching time of the model. The Vmeas subparameter is the timing reference voltage level that the semiconductor vendor uses for the model. Include Cref, Rref, Vref, and Vmeas information to facilitate board-level timing simulation. The assumed connections for Cref, Rref, and Vref are shown in Figure 1.



1. - Reference Load Connections

A single-ended or true differential buffer can have Rref\_diff and Cref\_diff (Figure 2).



1. - Single-Ended or True Differential Buffer

*Other Notes:* A complete [Model] description normally contains the following keywords: [Voltage Range], [Pullup], [Pulldown], [GND Clamp], [POWER Clamp], and [Ramp]. A Terminator model may use the [Rgnd], [Rpower], [Rac], and [Cac] keywords. However, some models may have only a subset of these keywords. For example, an input structure normally only needs the [Voltage Range], [GND Clamp], and possibly the [POWER Clamp] keywords. If any of [Rgnd], [Rpower], [Rac], and [Cac] keywords is used, then the Model\_type must be Terminator.

*Examples:*

| Signals CLK1, CLK2,... | Optional signal list, if desired

[Model] Clockbuffer

Model\_type I/O

Polarity Non-Inverting

Enable Active-High

Vinl = 0.8V | Input logic "low" DC voltage, if any

Vinh = 2.0V | Input logic "high" DC voltage, if any

Vmeas = 1.5V | Reference voltage for timing measurements

Cref = 50pF | Timing specification test load capacitance value

Rref = 500 | Timing specification test load resistance value

Vref = 0 | Timing specification test load voltage

| variable typ min max

C\_comp 7.0pF 5.0pF 9.0pF

C\_comp\_pullup 3.0pF 2.5pF 3.5pF | These four can be

C\_comp\_pulldown 2.0pF 1.5pF 2.5pF | used instead of

C\_comp\_power\_clamp 1.0pF 0.5pF 1.5pF | C\_comp

C\_comp\_gnd\_clamp 1.0pF 0.5pF 1.5pF

For a single-ended or true differential buffer (Section 6B):

[Model] External\_Model\_Diff

Model\_type I/O\_diff | Requires [External Model]

Polarity Non-Inverting

Enable Active-High

| The [Diff Pin] vdiff value overrides the thresholds below

Vinl = 0.8V | Input logic "low" DC voltage, if any

Vinh = 2.0V | Input logic "high" DC voltage, if any

| | The true differential measurement point is at

| | the crossover voltage

| | The Vmeas value is overridden

Vmeas = 1.5V | Reference voltage for timing measurements

| | Single-ended timing test load is still permitted

Cref = 5pF | Timing specification test load capacitance value

Rref = 500 | Timing specification test load resistance value

Vref = 0 | Timing specification test load voltage

| | These new subparameters are permitted for

| | single-ended differential operation based on the

| | [Diff Pin] keyword

Rref\_diff = 100 | Timing specification differential resistance value

Cref\_diff = 5pF | Timing specification differential capacitance value

*Keyword:* [Model Spec]

*Required:* No

*Sub-Params:* Vinh, Vinl, Vinh+, Vinh-, Vinl+, Vinl-, S\_overshoot\_high, S\_overshoot\_low, D\_overshoot\_high, D\_overshoot\_low, D\_overshoot\_time, D\_overshoot\_area\_h, D\_overshoot\_area\_l, D\_overshoot\_ampl\_h, D\_overshoot\_ampl\_l, Pulse\_high, Pulse\_low, Pulse\_time, Vmeas, Vref, Cref, Rref, Cref\_rising, C\_ref\_falling, Rref\_rising, Rref\_falling, Vref\_rising, Vref\_falling, Vmeas\_rising, Vmeas\_falling, Rref\_diff, Cref\_diff, Weak\_R, Weak\_I, Weak\_V

*Description:* The [Model Spec] keyword defines four columns under which specification subparameters are defined.

The following subparameters are defined:

Vinh Input voltage threshold high

Vinl Input voltage threshold low

Vinh+ Hysteresis threshold high max Vt+

Vinh- Hysteresis threshold high min Vt+

Vinl+ Hysteresis threshold low max Vt-

Vinl- Hysteresis threshold low min Vt-

S\_overshoot\_high Static overshoot high voltage

S\_overshoot\_low Static overshoot low voltage

D\_overshoot\_high Dynamic overshoot high voltage

D\_overshoot\_low Dynamic overshoot low voltage

D\_overshoot\_time Dynamic overshoot time

D\_overshoot\_area\_h Dynamic overshoot high area (in V-s)

D\_overshoot\_area\_l Dynamic overshoot low area (in V-s)

D\_overshoot\_ampl\_h Dynamic overshoot high max amplitude

D\_overshoot\_ampl\_l Dynamic overshoot low max amplitude

Pulse\_high Pulse immunity high voltage

Pulse\_low Pulse immunity low voltage

Pulse\_time Pulse immunity time

Vmeas Measurement voltage for timing measurements

Vref Timing specification test load voltage

Cref Timing specification capacitive load

Rref Timing specification resistance load

Cref\_rising Timing specification capacitive load for rising edges

Cref\_falling Timing specification capacitive load for falling edges

Rref\_rising Timing specification resistance load for rising edges

Rref\_falling Timing specification resistance load for falling edges

Vref\_rising Timing specification test load voltage for rising edges

Vref\_falling Timing specification test load voltage for falling edges

Vmeas\_rising Measurement voltage for rising edge timing measurements

Vmeas\_falling Measurement voltage for falling edge timing measurements

Rref\_diff Timing specification differential resistance load

Cref\_diff Timing specification differential capacitive load

Weak\_R Weak tie-up or tie-down resistance

Weak\_I Weak tie-up or tie-down current

Weak\_V Weak tie-up or tie-down voltage

*Usage Rules:* [Model Spec] must follow all other subparameters under the [Model] keyword.

For each subparameter contained in the first column, the remaining three columns hold its typical, minimum and maximum values The entries of typical, minimum, and maximum must be placed on a single line and must be separated by at least one white space. All four columns are required under the [Model Spec] keyword. However, data is required only in the typical column. If minimum and/or maximum values are not available, the reserved word “NA” must be used indicating the typical value by default.

The minimum and maximum values are used for specifications subparameter values that may track the min and max operation conditions of the [Model]. Usually it is related to the Voltage Range settings.

Unless noted below, no subparameter requires the presence of any other subparameter.

Vinh, Vinl rules:

The threshold subparameter lines provide additional min and max column values, if needed. The typ column values are still required and would be expected to override the Vinh and Vinl subparameter values specified elsewhere. Note that the syntax rule that requires inserting Vinh and Vinl under models remains unchanged even if the values are defined under the [Model Spec] keyword.

Vinh+, Vinh-, Vinl+, Vinl- rules:

The four hysteresis subparameters (used for Schmitt trigger inputs for defining two thresholds for the rising edges and two thresholds for falling edges) must all be defined before independent input thresholds for rising and falling edges of the hysteresis threshold rules become effective. Otherwise the standard threshold subparameters remain in effect. The hysteresis thresholds shall be at the Vinh+ and Vinh- values for a low-to-high transition, and at the Vinl+ and Vinl- values for a high-to-low transition. See Figure 3.



1. - Receiver Voltage with Hysteresis Thresholds

S\_overshoot\_high, S\_overshoot\_low rules:

The static overshoot subparameters provide the DC voltage values for which the model is no longer guaranteed to function correctly. Often these voltages are given as absolute maximum ratings. However, if any lower \*\_overshoot\_high or higher \*\_overshoot\_low limit for functional specification compliance exists, that limit should be used.

D\_overshoot\_high, D\_overshoot\_low, D\_overshoot\_time rules:

The dynamic overshoot values provide a time window during which the overshoot may exceed the static overshoot limits but be below the dynamic overshoot limits and still guarantee functional specification compliance. D\_overshoot\_time is required for dynamic overshoot testing. In addition, if D\_overshoot\_high is specified, then S\_overshoot\_high is necessary for testing beyond the static limit. Similarly, if D\_overshoot\_low is specified, then S\_overshoot\_low is necessary for testing beyond the static limit. See Figure 4.



1. - Receiver Voltage with Static and Dynamic Overshoot Limits

D\_overshoot\_area\_h, D\_overshoot\_area\_l, D\_overshoot\_ampl\_h, D\_overshoot\_ampl\_l rules:

The dynamic overshoot area values define a maximum V-s area that an overshooting signal must not exceed. The high area is calculated from the point that a signal overshoots above the voltage defined by the [Power Clamp Reference] keyword until the point that the signal crosses back through this same voltage. Note that the area is defined as the complete area-under-the-curve as bounded by the limits defined above and not a “triangular” area, as shown in Figure 5. If [Power Clamp Reference] is not defined, then this crossing voltage is assumed to be defined by the [Voltage Range] keyword. The low area is calculated from the point that a signal overshoots below the voltage defined by the [GND Clamp Reference] keyword until the point that the signal crosses back through this same voltage. If [GND Clamp Reference] is not defined, then this crossing voltage is assumed to be 0.0 V. If D\_overshoot\_area\_h is specified, then D\_overshoot\_ampl\_h must also be specified. D\_overshoot\_ampl\_h provides a maximum amplitude allowed for the overshoot area and is measured as voltage above the [Power Clamp Reference] voltage. Similarly, if D\_overshoot\_area\_l is specified, then D\_overshoot\_ampl\_l must also be specified. D\_overshoot\_ampl\_l is measured as voltage below the [GND Clamp Reference] voltage. Both amplitude parameters should be listed as absolute (non-negative) values. Also, if D\_overshoot\_area\_h, D\_overshoot\_area\_l, D\_overshoot\_ampl\_h, and D\_overshoot\_ampl\_l are specified, then other static and dynamic overshoot parameters are optional.



1. - Receiver Voltage with Dynamic Area Overshoot Limits

Pulse\_high, Pulse\_low, Pulse\_time rules:

The pulse immunity values provide a time window during which a rising pulse may exceed the nearest threshold value but be below the pulse voltage value and still not cause the input to switch. Pulse\_time is required for pulse immunity testing. A rising response is tested only if Pulse\_high is specified. Similarly, a falling response is tested only if Pulse\_low is specified. The rising response may exceed the Vinl value, but remain below the Pulse\_high value.

Similarly, the falling response may drop below the Vinh value, but remain above the Pulse\_low value. In either case the input is regarded as immune to switching if the responses are within these extended windows. If the hysteresis thresholds are defined, then the rising response shall use Vinh- as the reference voltage, and the falling response shall use Vinl+ as the reference voltage. See Figure 6.



1. - Receiver Voltage with Pulse Immunity Thresholds

Vmeas, Vref, Cref, Rref rules:

The Vmeas, Vref, Cref and Rref values under the [Model Spec] keyword override their respective values entered elsewhere. Note that a Vmeas, Vref, Cref or Rref subparameters may not be used if its edge specific version (\*\_rising or \*\_falling) is used.

Cref\_rising, Cref\_falling, Rref\_rising, Rref\_falling, Vref\_rising, Vref\_falling, Vmeas\_rising, Vmeas\_falling rules:

Use these subparameters when specifying separate timing test loads and voltages for rising and falling edges. If one “rising” or “falling” subparameter is used, then the corresponding “rising” or “falling” subparameter must be present. The values listed in these subparameters override any corresponding Cref, Vref, Rref or Vmeas values entered elsewhere.

Rref\_diff, Cref\_diff rules:

The Rref\_diff and Cref\_diff values under the [Model Spec] keyword override their respective values entered elsewhere. These subparameters are used only when the model is referenced by the [Diff Pin] keyword. These follow the same rules as the corresponding subparameters documented under the [Model] keyword. See Section 6B for more discussion on true and single-ended differential operation.

Weak\_R, Weak\_I, and Weak\_V rules:

If an IO circuit uses a simple weak tie-up or tie-down device (resistor or transistor) between the chip IO pad and a power supply, Weak\_R stores the resistance of this device and Weak\_V stores the voltage of the power supply to which the device is connected. A Weak\_I stores the approximate current into the device and Weak\_V stores the voltage of the power supply. They apply to both static and configurable tie-up and tie-down devices.

The Weak\_R, Weak\_I, and Weak\_V subparameters are optional and separate from the current-voltage table keywords, e.g., [Pullup], [GND Clamp], etc. They do not affect how the current-voltage tables are extracted.

(Weak\_R and Weak\_V) or (Weak\_I and Weak\_V) must always be used as a pair. Weak\_R and Weak\_I must not be used together.

The current flow convention for Weak\_I is similar to that of [GND Clamp] and {POWER Clamp] tables. A positive sign documents a weak tie-down current. A negative sign documents a weak tie-up current.

*Examples:*

[Model Spec]

| Subparameter typ min max

|

| Thresholds

|

Vinh 3.5 3.15 3.85 | 70% of Vcc

Vinl 1.5 1.35 1.65 | 30% of Vcc

|

| Vinh 3.835 3.335 4.335 | Offset from Vcc

| Vinl 3.525 3.025 4.025 | for PECL

|

| Hysteresis

|

Vinh+ 2.0 NA NA | Overrides the

Vinh- 1.6 NA NA | thresholds

Vinl+ 1.1 NA NA

Vinl- 0.6 NA NA | All 4 are required

|

| Overshoot

|

S\_overshoot\_high 5.5 5.0 6.0 | Static overshoot

S\_overshoot\_low -0.5 NA NA

D\_overshoot\_high 6.0 5.5 6.5 | Dynamic overshoot

D\_overshoot\_low -1.0 -1.0 -1.0 | requires

| | D\_overshoot\_time

D\_overshoot\_time 20n 20n 20n | & static overshoot

|

| Overshoot defined by area in V-s (Values from DDR2 specification)

|

D\_overshoot\_ampl\_h 0.9 NA NA | Dynamic overshoot

D\_overshoot\_ampl\_l 0.9 NA NA | requires area

D\_overshoot\_area\_h 0.38n NA NA | and amplitude

D\_overshoot\_area\_l 0.38n NA NA | parameters

|

| Pulse Immunity

|

Pulse\_high 3V NA NA | Pulse immunity

Pulse\_low 0 NA NA | requires

Pulse\_time 3n NA NA | Pulse\_time

|

| Timing Thresholds

|

Vmeas 3.68 3.18 4.68 | A 5 volt PECL

| | example

|

| Timing test load voltage reference example

|

Vref 1.25 1.15 1.35 | An SSTL-2 example

|

|

| Rising and falling timing test load example (values from PCI-X

| specification)

|

Cref\_falling 10p 10p 10p

Cref\_rising 10p 10p 10p

Rref\_rising 25 500 25 | typ value not specified

Rref\_falling 25 500 25 | typ value not specified

Vref\_rising 0 1.5 0

Vref\_falling 3.3 1.5 3.6

Vmeas\_rising 0.941 0.885 1.026 | vmeas = 0.285(vcc)

Vmeas\_falling 2.0295 1.845 2.214 | vmeas = 0.615(vcc)

|

| Differential timing test load for true or single-ended differential model

|

Rref\_diff 100 90 110

Cref\_diff 5pF NA NA

|

| Weak tie-up examples:

|

Weak\_R 10k NA NA

Weak\_V 1.5V NA NA

|

Weak\_I -10u NA NA | negative sign for

Weak\_V 1.5V NA NA | tie-up current

*Keyword:* [Receiver Thresholds]

*Required:* No

*Sub-Params:* Vth, Vth\_min, Vth\_max, Vinh\_ac, Vinh\_dc, Vinl\_ac, Vinl\_dc, Threshold\_sensitivity, Reference\_supply, Vcross\_low, Vcross\_high, Vdiff\_ac, Vdiff\_dc, Tslew\_ac, Tdiffslew\_ac

*Description:* The [Receiver Thresholds] keyword defines both a set of receiver input thresholds as well as their sensitivity to variations in a referenced supply. The subparameters are defined as follows:

Vth, Vth\_min, and Vth\_max are the ideal input threshold voltages at which the output of a digital logic receiver changes state. Vth is the nominal input threshold voltage under the voltage, temperature and process conditions that define “typ”. Vth\_min is the minimum input threshold voltage at “typ” conditions while Vth\_max is the maximum input threshold voltage at “typ” conditions.

Vinh\_ac is the voltage that a low-to-high going input waveform must reach in order to guarantee that the receiver’s output has changed state. In other words, reaching Vinh\_ac is sufficient to guarantee a receiver state change. Vinh\_ac is expressed as an offset from Vth.

Vinh\_dc is the voltage that an input waveform must remain above (more positive than) in order to guarantee that a receiver output will NOT change state. Vinh\_dc is expressed as an offset from Vth.

Vinl\_ac is the voltage that a high-to-low going input waveform must reach in order to guarantee that the receiver’s output has changed state. In other words, reaching Vinl\_ac is sufficient to guarantee a receiver state change. Vinl\_ac is expressed as an offset from Vth.

Vinl\_dc is the voltage that an input waveform must remain below (more negative than) in order to guarantee that a receiver’s output will NOT change state. Vinl\_dc is expressed as an offset from Vth.

Threshold\_sensitivity is a unit-less number that specifies how Vth varies with respect to the supply voltage defined by the Reference\_supply subparameter. Threshold\_sensitivity is defined as:

Threshold\_sensitivity must be entered as a whole number or decimal, not as a fraction.

Reference\_supply indicates which supply voltage Vth tracks; i.e., it indicates which supply voltage change causes a change in input threshold. The legal arguments to this subparameter are as follows:

Power\_clamp\_ref The supply voltage defined by the [POWER Clamp Reference] keyword

Gnd\_clamp\_ref The supply voltage defined by the [GND Clamp Reference] keyword

Pullup\_ref The supply voltage defined by the [Pullup reference] keyword

Pulldown\_ref The supply voltage defined by the [Pulldown reference] keyword

Ext\_ref The supply voltage defined by the [External Reference] keyword

Tslew\_ac and Tdiffslew\_ac measure the absolute difference in time between the point at which an input waveform crosses Vinl\_ac and the point it crosses Vinh\_ac. The purpose of this parameter is to document the maximum amount of time an input signal may take to transition between Vinh\_ac and Vinl\_ac and still allow the device to meet its input setup and hold specifications. Tslew\_ac is the parameter used for single ended receivers while Tdiffslew\_ac must be used for receivers with differential inputs.

Vcross\_low is the least positive voltage at which a differential receiver’s input signals may cross while switching and still allow the receiver to meet its timing and functional specifications. Vcross\_low is specified with respect to 0 V.

Vcross\_high is the most positive voltage at which a differential receiver’s input signals may cross while switching and still allow the receiver to meet its timing and functional specifications. Vcross\_high is specified with respect to 0 V.

Vdiff\_dc is the minimum voltage difference between the inputs of a differential receiver that guarantees the receiver will not change state.

Vdiff\_ac is the minimum voltage difference between the inputs of a differential receiver that guarantees the receiver will change state.

*Usage Rules*: [Receiver Thresholds] must follow all subparameters under the [Model] keyword and precede all other keywords of a model except [Model Spec].

The [Receiver Thresholds] keyword is valid if the model type includes any reference to input or I/O. For single ended receivers the Vinh\_ac, Vinh\_dc, Vinl\_ac, Vinh\_dc, Vth and Tslew\_ac subparameters are required and override the Vinh, Vinl, Vinh+/- and Vinl+/- subparameters declared under the [Model] or [Model Spec] keywords. For single ended receivers the Vth\_min, Vth\_max, Threshold\_sensitivity and Reference\_supply subparameters are optional. However, if the Threshold\_sensitivity subparameter is present then the Reference\_supply subparameter must also be present.

For differential receivers (i.e., the [Receiver Thresholds] keyword is part of a [Model] statement that describes a pin listed in the [Diff Pin] keyword), the Vcross\_low, Vcross\_high, Vdiff\_ac, Vdiff\_dc and Tdiffslew\_ac subparameters are required. The rest of the subparameters are not applicable. The Vdiff\_ac and Vdiff\_dc values override the value of the vdiff subparameter specified by the [Diff Pin] keyword. Note that Vcross\_low and Vcross\_high are valid over the device’s minimum and maximum operating conditions.

Subparameter Usage Rules:

Numerical arguments are separated from their associated subparameter by an equals sign (=); white space around the equals sign is optional. The argument to the Reference\_supply subparameter is separated from the subparameter by white space.

Vth at Minimum or Maximum Operating Conditions:

As described above, the Vth\_min and Vth\_max subparameters define the minimum and maximum input threshold values under typical operating conditions. There is no provision for directly specifying Vth under minimum or maximum operating conditions. Instead, these values are calculated using the following equation:

*Vth(min/max) = Vth\* + [(Threshold\_sensitivity) X (change in supply voltage)]*

where Vth\* is either Vth, Vth\_min or Vth\_max as appropriate, and the supply voltage is the one indicated by the Reference\_supply subparameter.

*Examples:*

A basic 3.3 V single ended receiver using only the required subparameters:

[Receiver Thresholds]

Vth = 1.5V

Vinh\_ac = +225mV

Vinh\_dc = +100mV

Vinl\_ac = -225mV

Vinl\_dc = -100mV

Tslew\_ac = 1.2ns

A single ended receiver using an external threshold reference. In this case the input threshold is the external reference voltage so Threshold\_sensitivity equals 1.

[Receiver Thresholds]

Vth = 1.0V

Threshold\_sensitivity = 1

Reference\_supply Ext\_ref

Vinh\_ac = +200mV

Vinh\_dc = +100mV

Vinl\_ac = -200mV

Vinl\_dc = -100mV

Tslew\_ac = 400ps

A fully specified single ended 3.3 V CMOS receiver:

[Receiver Thresholds]

Vth = 1.5V

Vth\_min = 1.45V

Vth\_max = 1.53V

Threshold\_sensitivity = 0.45

Reference\_supply Power\_clamp\_ref

Vinh\_ac = +200mV

Vinh\_dc = +100mV

Vinl\_ac = -200mV

Vinl\_dc = -100mV

Tslew\_ac = 400ps

A differential receiver:

[Receiver Thresholds]

Vcross\_low = 0.65V

Vcross\_high = 0.90V

Vdiff\_ac = +200mV

Vdiff\_dc = +100mV

Tdiffslew\_ac = 200ps

*Keyword:* [Add Submodel]

*Required:* No

*Description:* References a submodel to be added to an existing model.

*Usage Rules:* The [Add Submodel] keyword is invoked within a model to add the functionality that is contained in the submodel or list of submodels in each line that follows. The first column contains the submodel name. The second column contains a submodel mode under which the submodel is used.

If the top-level model type is one of the I/O or 3-state models, the submodel mode may be Driving, Non-Driving, or All. For example, if the submodel mode is Non-Driving, then the submodel is used only in the high-Z state of a 3-state model. Set the submodel mode to All if the submodel is to be used for all modes of operation.

The submodel mode cannot conflict with the top-level model type. For example, if the top-level model type is an Open or Output type, the submodel mode cannot be set to Non-Driving. Similarly, if the top-level model type is Input, the submodel mode cannot be set to Driving.

The submodel mode can be set to All to cover all permitted modes for any top-level model type including, for example, Input, Output, and I/O.

The [Add Submodel] keyword is not defined for Series or Series\_switch model types.

Refer to the Add Submodel description in Section 6A of this document for the descriptions of available submodels.

*Example:*

[Add Submodel]

| Submodel\_name Mode

Bus\_Hold\_1 Non-Driving | Adds the electrical characteristics of

| [Submodel] Bus\_Hold\_1 for receiver or

| high-Z mode only.

Dynamic\_clamp\_1 All | Adds the Dynamic\_clamp\_1 model for

| all modes of operation.

*Keyword:* [Driver Schedule]

*Required:* No

*Description:* Describes the relative model switching sequence for referenced models to produce a multi-staged driver.

*Usage Rules:* The [Driver Schedule] keyword establishes a hierarchical order between models and should be placed under the [Model] which acts as the top-level model. The scheduled models are then referenced from the top-level model by the [Driver Schedule] keyword.

When a multi-staged buffer is modeled using the [Driver Schedule] keyword, all of its stages (including the first stage, or normal driver) have to be modeled as scheduled models.

If there is support for this feature in a EDA tool, the [Driver Schedule] keyword will cause it to use the [Pulldown], [Pulldown Reference], [Pullup], [Pullup Reference], [Voltage Range], [Ramp], [Rising Waveform] and [Falling Waveform] keywords from the scheduled models instead of the top-level model, according to the timing relationships described in the [Driver Schedule] keyword. Consequently, the keywords in the above list will be ignored in the top-level model. All of the remaining keywords not shown in the above list, and all of the subparameters will be used from the top-level model and should be ignored in the scheduled model(s).

However, both the top-level and the scheduled model(s) have to be complete models, i.e., all of the required keywords must be present and follow the syntactical rules.

For backwards compatibility reasons and for EDA tools which do not support multi-staged switching, the keywords in the above list can be used in the top-level [Model] to describe the overall characteristics of the buffer as if it was a composite model. It is not guaranteed, however, that such a top-level model will yield the same simulation results as a full multi-stage model. It is recommended that a “golden waveform” for the device consisting of a [Rising Waveform] table and a [Falling Waveform] table be supplied in the top-level model to serve as a reference for validation.

Even though some of the keywords are ignored in the scheduled model, it may still make sense in some cases to supply correct data with them. One such situation would arise when a [Model] is used both as a regular top-level model as well as a scheduled model.

The [Driver Schedule] table consists of five columns. The first column contains the model names of other models that exist in the .ibs file. The remaining four columns describe delays: Rise\_on\_dly, Rise\_off\_dly, Fall\_on\_dly, and Fall\_off\_dly. The t=0 time of each delay is the event when the EDA tool’s internal pulse initiates a rising or falling transition. All specified delay values must be equal to or greater than 0. There are only five valid combinations in which these delay values can be defined:

1) Rise\_on\_dly with Fall\_on\_dly

2) Rise\_off\_dly with Fall\_off\_dly

3) Rise\_on\_dly with Rise\_off\_dly

4) Fall\_on\_dly with Fall\_off\_dly

5) All four delays defined

(be careful about correct sequencing)

The four delay parameters have the meaning as described below. (Note that this description applies to buffer types which have both pullup and pulldown structures. For those buffer types which have only a pullup or pulldown structure, the description for the missing structure can be omitted.)

Rise\_on\_dly is the amount of time that elapses from the internal simulator pulse initiating a RISING edge to the t = 0 time of the waveform or ramp that turns the I-V table of the PULLUP device ON, and the t = 0 time of the waveform or ramp that turns the I-V table of the PULLDOWN device OFF (if they were not already turned ON and OFF, respectively, by another event).

Rise\_off\_dly is the amount of time that elapses from the internal simulator pulse initiating a RISING edge to the t = 0 time of the waveform or ramp that turns the I-V table of the PULLUP device OFF, and the t = 0 time of the waveform or ramp that turns the I-V table of the PULLDOWN device ON (if they were not already turned ON and OFF, respectively, by another event).

Fall\_on\_dly is the amount of time that elapses from the internal simulator pulse initiating a FALLING edge to the t = 0 time of the waveform or ramp that turns the I-V table of the PULLDOWN device ON, and the t = 0 time of the waveform or ramp that turns the I-V table of the PULLUP device OFF (if they were not already turned ON and OFF, respectively, by another event).

Fall\_off\_dly is the amount of time that elapses from the internal simulator pulse initiating a FALLING edge to the t = 0 time of the waveform or ramp that turns the I-V table of the PULLDOWN device OFF, and the t = 0 time of the waveform or ramp that turns the I-V table of the PULLUP device ON (if they were not already turned ON and OFF, respectively, by another event).

In the above four paragraphs, the word “event” refers to the moment in time when the delay is triggered by the stimulus. This stimulus is provided to the top-level model by the simulation tool. The expiration of delays cannot generate events.

Note that some timing combinations may only be possible if the two halves of a complementary buffer are modeled separately as two open\_\* models.

No [Driver Schedule] table may reference a model which itself has within it a [Driver Schedule] keyword.

Use “NA” when no delay value is applicable. For each scheduled model the transition sequence must be complete, i.e., the scheduled model must return to its initial state.

Only certain numerical entry combinations are permitted to define a complete transition sequence. Table 2 gives the initial scheduled model states for each permitted set of numerical entries. The numerical delay entries, r, r1, and r2 are relative to the internal simulator pulse rising edge, and f, f1, and f2 are the numerical delay entries relative to internal simulator pulse falling edge. For the cases where two delays are given relative to the same edge, the r2 entry is larger than the r1 entry, and the f2 entry is larger than the f1 entry. For cases below, the interchanging of such values corresponds to opposite direction switching. Once the scheduled model is set to its initial state, the switching is controlled by the internal simulator pulse and delays relative to it.

In Table 2, the scheduled model initial states depend on the initial state of the [Model]. This top-level [Model] state (“Low” or “High”) is a function of the stimulus pulse (or simulation control method) and the [Model] Polarity subparameter. For example, if a [Model] Polarity is Inverting and its stimulus pulse starts high, the [Model] initial state is “Low” and all scheduled model initial states follow the settings under the “Low” column. Two possible four-data ordering combinations are omitted because their initial states are ambiguous. Special rules to select the initial states would produce sequencing equivalent to the two-data combinations shown in the first two lines of the table.

Table – Scheduled Model Initial State

| **Table Numerical Delay Entries** | | | | **[Model] Initial State** | |
| --- | --- | --- | --- | --- | --- |
| **Rise\_on** | **Rise\_off** | **Fall\_on** | **Fall\_off** | **Low** | **High** |
| r | NA | f | NA | Low | High |
| NA | r | NA | f | High | Low |
| r1 | r2 | NA | NA | Low | Low |
| r2 | r1 | NA | NA | High | High |
| NA | NA | f1 | f2 | High | High |
| NA | NA | f2 | f1 | Low | Low |
| r1 | r2 | f2 | f1 | Low | Low |
| r2 | r1 | f1 | f2 | High | High |

The delay numbers r, r1, r2, and f, f1, f2 plus the associated model transitions should fit within the corresponding pulse width durations. Smaller pulse width stimuli may change the switching sequencing and is not supported.

*Other Notes:* The added models typically consist of Open\_sink (Open\_drain) or Open\_source models to provide sequentially increased drive strengths. The added drive may be removed within the same transition for a momentary boost or during the opposite transition.

The syntax also allows for reducing the drive strength.

Note that the Rise\_on\_dly, Rise\_off\_dly, Fall\_on\_dly, Fall\_off\_dly parameters are single value parameters, so typical, minimum and maximum conditions cannot be described with them directly. In order to account for those effects, one can refer to the fastest waveform table with the delay number and then insert an appropriate amount of horizontal lead in section in those waveforms which need more delay.

Notice that the C\_comp parameter of a multi-stage buffer is defined in the top-level model. The value of C\_comp therefore includes the total capacitance of the entire buffer, including all of its stages. Since the rising and falling waveform measurements include the effects of C\_comp, each of these waveforms must be generated with the total C\_comp present, even if the various stages of the buffer are characterized individually.

*Note:* In a future release, the [Driver Schedule] keyword may be replaced by a newer method of specification that is consistent with some other planned extensions. However, the [Driver Schedule] syntax will continue to be supported.

*Example:*

[Driver Schedule]

| Model\_name Rise\_on\_dly Rise\_off\_dly Fall\_on\_dly Fall\_off\_dly

MODEL\_OUT 0.0ns NA 0.0ns NA

|

| Examples of added multi-staged transitions

M\_O\_SOURCE1 0.5ns NA 0.5ns NA

| low (high-Z) to high high to low (high-Z)

M\_O\_SOURCE2 0.5n 1.5n NA NA

| low to high to low low (high-Z)

M\_O\_DRAIN1 1.0n NA 1.5n NA

| low to high (high-Z) high (high-Z) to low

M\_O\_DRAIN2 NA NA 1.5n 2.0n

| high (high-Z) high to low to high

*Keyword:* [Temperature Range]

*Required:* Yes, if other than the preferred 0, 50, 100 degree Celsius range

*Description:* Defines the temperature range over which the model is to operate.

*Usage Rules:* List the actual die temperatures (not percentages) in the typ, min, max format. “NA” is allowed for min and max only.

*Other Notes:* The [Temperature Range] keyword also describes the temperature range over which the various I-V tables and ramp rates were derived. Refer to Section 9, "NOTES ON DATA DERIVATION METHOD" for rules on which temperature values to put in the “min” and “max” columns.

*Example:*

| variable typ min max

[Temperature Range] 27.0 -50 130.0

*Keyword:* [Voltage Range]

*Required:* Yes, if [Pullup Reference], [Pulldown Reference], [POWER Clamp Reference], and [GND Clamp Reference] are not present

*Description:* Defines the power supply voltage tolerance over which the model is intended to operate. It also specifies the default voltage rail to which the [Pullup] and [POWER Clamp] I-V data is referenced.

*Usage Rules:* Provide actual voltages (not percentages) in the typ, min, max format. “NA” is allowed for the min and max values only.

*Other Notes:* If the [Voltage Range] keyword is not present, then all four of the keywords described below must be present: [Pullup Reference], [Pulldown Reference], [POWER Clamp Reference], and [GND Clamp Reference]. If the [Voltage Range] is present, the other keywords are optional and may or may not be used as required. It is legal (although redundant) for an optional keyword to specify the same voltage as specified by the [Voltage Range] keyword.

*Example:*

| variable typ min max

[Voltage Range] 5.0V 4.5V 5.5V

*Keyword:* [Pullup Reference]

*Required:* Yes, if the [Voltage Range] keyword is not present

*Description:* Defines a voltage rail other than that defined by the [Voltage Range] keyword as the reference voltage for the [Pullup] I-V data.

*Usage Rules:* Provide actual voltages (not percentages) in the typ, min, max format. “NA” is allowed for the min and max values only.

*Other Notes:* This keyword, if present, also defines the voltage range over which the typ, min, and max dV/dt\_r values are derived.

*Example:*

| variable typ min max

[Pullup Reference] 5.0V 4.5V 5.5V

*Keyword:* [Pulldown Reference]

*Required:* Yes, if the [Voltage Range] keyword is not present

*Description:* Defines a power supply rail other than 0 V as the reference voltage for the [Pulldown] I-V data. If this keyword is not present, the voltage data points in the [Pulldown] I-V table are referenced to 0 V.

*Usage Rules:* Provide actual voltages (not percentages) in the typ, min, max format. “NA” is allowed for the min and max values only.

*Other Notes:* This keyword, if present, also defines the voltage range over which the typ, min, and max dV/dt\_f values are derived.

*Example:*

| variable typ min max

[Pulldown Reference] 0V 0V 0V

*Keyword:* [POWER Clamp Reference]

*Required:* Yes, if the [Voltage Range] keyword is not present

*Description:* Defines a voltage rail other than that defined by the [Voltage Range] keyword as the reference voltage for the [POWER Clamp] I-V data.

*Usage Rules:* Provide actual voltages (not percentages) in the typ, min, max format. “NA” is allowed for the min and max values only.

*Other Notes:* Refer to the “Other Notes” section of the [GND Clamp Reference] keyword.

*Example:*

| variable typ min max

[POWER Clamp Reference] 5.0V 4.5V 5.5V

*Keyword:* [GND Clamp Reference]

*Required:* Yes, if the [Voltage Range] keyword is not present

*Description:* Defines a power supply rail other than 0 V as the reference voltage for the [GND Clamp] I-V data. If this keyword is not present, the voltage data points in the [GND Clamp] I-V table are referenced to 0 V.

*Usage Rules:* Provide actual voltages (not percentages) in the typ, min, max format. “NA” is allowed for the min and max values only.

*Other Notes:* Power Supplies: It is intended that standard TTL and CMOS models be specified using only the [Voltage Range] keyword. However, in cases where the output characteristics of a model depend on more than a single supply and ground, or a [Pullup], [Pulldown], [POWER Clamp], or [GND Clamp] table is referenced to something other than the default supplies, use the additional “reference” keywords.

*Example:*

| variable typ min max

[GND Clamp Reference] 0V 0V 0V

*Keyword:* [External Reference]

*Required:* Yes, if a receiver’s input threshold is determined by an external reference voltage

*Description:* Defines a voltage source that supplies the reference voltage used by a receiver for its input threshold reference.

*Usage Rules:* Provide actual voltages (not percentages) in the typ, min max format. “NA” is allowed for the min and max values only. Note that the numerically largest value should be placed in “max” column, while the numerically smallest value should be placed in the “min” column.

*Example:*

| variable typ min max

[External Reference] 1.00V 0.95V 1.05V

*Keyword:* **[C Comp Corner]**

*Required:* No

*Description:* Used to define C\_comp values associated with the typ/min/max corner

*Sub-Params:* C\_comp, C\_comp\_pullup, C\_comp\_pulldown, C\_comp\_power\_clamp, C\_comp\_gnd\_clamp

*Usage Rules:* If [C Comp Corner] is present, its value or values override any other C\_comp\* representations. The entries are values associated with each of the typ/min/max corners rather than entered by magnitude as with the other C\_comp subparameters.

The C\_comp subparameter under [C Comp Corner] is required only when C\_comp\_pullup, C\_comp\_pulldown, C\_comp\_power\_clamp, and C\_comp\_gnd\_clamp are not present. If the C\_comp subparameter is not present, at least one of the C\_comp\_pullup, C\_comp\_pulldown, C\_comp\_power\_clamp, or C\_comp\_gnd\_clamp subparameters is required. It is not illegal to include the C\_comp subparameter together with one or more of the remaining C\_comp\_\* subparameters, but in that case the simulator will have to make a decision whether to use C\_comp or the C\_comp\_pullup, C\_comp\_pulldown, C\_comp\_power\_clamp, and C\_comp\_gnd\_clamp subparameters. Under no circumstances should the simulator use the value of C\_comp simultaneously with the values of the other C\_comp\_\* subparameters.

C\_comp\_pullup, C\_comp\_pulldown, C\_comp\_power\_clamp, and C\_comp\_gnd\_clamp are intended to represent the parasitic capacitances of those structures whose I-V characteristics are described by the [Pullup], [Pulldown], [POWER Clamp] and [GND Clamp] I-V tables. For this reason, the simulator should generate a circuit netlist so that, if defined, each of the C\_comp\_\* capacitors is connected in parallel with its corresponding I-V table(s), whether or not the I-V table(s) exist(s). That is, the C\_comp\_\* capacitors are positioned between the signal pad and the nodes defined by the [Pullup Reference], [Pulldown Reference], [POWER Clamp Reference] and [GND Clamp Reference] keywords, or the [Voltage Range] keyword and GND.

The C\_comp and C\_comp\_\* subparameters define die capacitance. These values should not include the capacitance of the package. C\_comp and C\_comp\_\* are allowed to use "NA" for the min and max values only.

*Other Notes:* When C\_comp values are obtained by extraction under the corner process, voltage, and temperature conditions, the C\_comp\* entries are often positioned with the maximum values under the min column and the minimum values under the max column. C\_comp\* entries under other keywords are entered into columns by numerical magnitude. The [C Comp Corner] entries override all other C\_comp\* entries under other keywords.

*Example:*

[C Comp Corner]

| variable typ min max

C\_comp 7.0pF 9.0pF 5.0pF

|

C\_comp\_pullup 3.0pF 3.5pF 2.5pF | These four can be

C\_comp\_pulldown 2.0pF 2.5pF 1.5pF | used instead of

C\_comp\_power\_clamp 1.0pF 1.5pF 0.5pF | C\_comp

C\_comp\_gnd\_clamp 1.0pF 1.5pF 0.5pF

|

*Keywords:* [TTgnd], [TTpower]

*Required:* No

*Description:* These keywords specify the transit time parameters used to estimate the transit time capacitances or develop transit time capacitance tables for the [GND Clamp] and [POWER Clamp] tables.

*Usage Rules:* For each of these keywords, the three columns hold the transit values corresponding to the typical, minimum and maximum [GND Clamp] or [POWER Clamp] tables, respectively. The entries for TT(typ), TT(min), and TT(max) must be placed on a single line and must be separated by at least one white space. All three columns are required under these keywords. However, data is required only in the typical column. If minimum and/or maximum values are not available, the reserved word “NA” must be used indicating the TT(typ) value by default.

*Other Notes:* The transit time capacitance is added to C\_comp. It is in a SPICE reference model as Ct = TT \* d(Id)/d(Vd) where d(Id)/d(Vd) defines the DC conductance at the incremental DC operating point of the diode, and TT is the transit time. This expression does not include any internal series resistance. Such a resistance is assumed to be negligible in practice. Assume that the internal diode current (Id) - voltage (Vd) relationship is Id = Is \* (exp(q(Vd)/kT) - 1) where Is is the saturation current, q is electron charge, k is Boltzmann’s constant, and T is temperature in degrees Kelvin. Then d(Id)/d(Vd) is approximately (q/kT) \* Id when the diode is conducting, and zero otherwise. This yields the simplification Ct = TT \* (q/kT) \* Id. The Id is found from the [GND Clamp] and [POWER Clamp] operating points, and the corresponding TTgnd or TTpower is used to calculate the Ct value. If the [Temperature Range] keyword is not defined, then use the default “typ” temperature for all Ct calculations.

The effective TT parameter values are intended to APPROXIMATE the effects. They may be different from the values found in the SPICE diode equations. Refer to Section 9, "NOTES ON DATA DERIVATION METHOD" for extracting the effective values.

*Example:*

| variable TT(typ) TT(min) TT(max)

[TTgnd] 10n 12n 9n

[TTpower] 12n NA NA

*Keywords:* [Pulldown], [Pullup], [GND Clamp], [POWER Clamp]

*Required:* Yes, if they exist in the model

*Description:* The data points under these keywords define the I-V tables of the pulldown and pullup structures of an output buffer and the I-V tables of the clamping diodes connected to the GND and the POWER pins, respectively. Currents are considered positive when their direction is into the component.

*Usage Rules:* In each of these sections, the first column contains the voltage value, and the three remaining columns hold the typical, minimum, and maximum current values. The four entries, Voltage, I(typ), I(min), and I(max) must be placed on a single line and must be separated by at least one white space.

All four columns are required under these keywords. However, data is only required in the typical column. If minimum and/or maximum current values are not available, the reserved word “NA” must be used. “NA” can be used for currents in the typical column, but numeric values MUST be specified for the first and last voltage points on any I-V table. Each I-V table must have at least 2, but not more than 100, rows.

*Other Notes:* The I-V table of the [Pullup] and the [POWER Clamp] structures are “Vcc relative”, meaning that the voltage values are referenced to the Vcc pin. (Note that, under these keywords, all references to “Vcc” refer to the voltage rail defined by the [Voltage Range], [Pullup Reference], or [POWER Clamp Reference] keywords, as appropriate.) The voltages in the data tables are derived from the equation:

*Vtable = Vcc – Voutput*

Therefore, for a 5 V model, -5 V in the table actually means 5 V above Vcc, which is +10 V with respect to ground; and 10 V means 10 V below Vcc, which is -5 V with respect to ground. Vcc-relative data is necessary to model a pullup structure properly, since the output current of a pullup structure depends on the voltage between the output and Vcc pins and not the voltage between the output and ground pins. Note that the [GND Clamp] I-V table can include quiescent input currents, or the currents of a 3-stated output, if so desired.

When tabulating data for ECL models, the data in the [Pulldown] table is measured with the output in the “logic low” state. In other words, the data in the table represents the I-V characteristics of the output when the output is at the most negative of its two logic levels. Likewise, the data in the [Pullup] table is measured with the output in the “logic one” state and represents the I-V characteristics when the output is at the most positive logic level. Note that in BOTH of these cases, the data is referenced to the Vcc supply voltage, using the equation:

*Vtable = Vcc - Voutput*

Monotonicity Requirements:

To be monotonic, the I-V table data must meet any one of the following 8 criteria:

1- The CURRENT axis either increases or remains constant as the voltage axis is increased.

2- The CURRENT axis either increases or remains constant as the voltage axis is decreased.

3- The CURRENT axis either decreases or remains constant as the voltage axis is increased.

4- The CURRENT axis either decreases or remains constant as the voltage axis is decreased.

5- The VOLTAGE axis either increases or remains constant as the current axis is increased.

6- The VOLTAGE axis either increases or remains constant as the current axis is decreased.

7- The VOLTAGE axis either decreases or remains constant as the current axis is increased.

8- The VOLTAGE axis either decreases or remains constant as the current axis is decreased.

An IBIS syntax checking program shall test for non-monotonic data and provide a maximum of one warning per I-V table if non-monotonic data is found. For example:

“Warning: Line 300, Pulldown I-V table for model DC040403 is non-monotonic! Most simulators will filter this data to remove the non-monotonic data.”

It is also recognized that the data may be monotonic if currents from both the output stage and the clamp diode are added together as most simulators do. To limit the complexity of the IBIS syntax checking programs, such programs will conduct monotonicity testing only on one I-V table at a time.

It is intended that the [POWER Clamp] and [GND Clamp] tables are summed together and then added to the appropriate [Pullup] or [Pulldown] table when a buffer is driving high or low, respectively.

From this assumption and the nature of 3-statable buffers, it follows that the data in the clamping table sections are handled as constantly present tables and the [Pullup] and [Pulldown] tables are used only when needed in the simulation.

The clamp tables of an Input or I/O buffer can be measured directly with a curve tracer, with the I/O buffer 3-stated. However, sweeping enabled buffers results in tables that are the sum of the clamping tables and the output structures. Based on the assumption outlined above, the [Pullup] and [Pulldown] tables of an IBIS model must represent the difference of the 3-stated and the enabled buffer’s tables. (Note that the resulting difference table can demonstrate a non-monotonic shape.) This requirement enables the simulator to sum the tables, without the danger of double counting, and arrive at an accurate model in both the 3-stated and enabled conditions.

Since in the case of a non 3-statable buffer, this difference table cannot be generated through lab measurements (because the clamping tables cannot be measured alone), the [Pullup] and [Pulldown] tables of an IBIS model can contain the sum of the clamping characteristics and the output structure. In this case, the clamping tables must contain all zeroes, or the keywords must be omitted.

*Example:*

[Pulldown]

| Voltage I(typ) I(min) I(max)

|

-5.0V -40.0m -34.0m -45.0m

-4.0V -39.0m -33.0m -43.0m

| .

0.0V 0.0m 0.0m 0.0m

| .

5.0V 40.0m 34.0m 45.0m

10.0V 45.0m 40.0m 49.0m

|

[Pullup] | Note: Vtable = Vcc - Voutput

|

| Voltage I(typ) I(min) I(max)

|

-5.0V 32.0m 30.0m 35.0m

-4.0V 31.0m 29.0m 33.0m

| .

0.0V 0.0m 0.0m 0.0m

| .

5.0V -32.0m -30.0m -35.0m

10.0V -38.0m -35.0m -40.0m

|

[GND Clamp]

|

| Voltage I(typ) I(min) I(max)

|

-5.0V -3900.0m -3800.0m -4000.0m

-0.7V -80.0m -75.0m -85.0m

-0.6V -22.0m -20.0m -25.0m

-0.5V -2.4m -2.0m -2.9m

-0.4V 0.0m 0.0m 0.0m

5.0V 0.0m 0.0m 0.0m

|

[POWER Clamp] | Note: Vtable = Vcc - Voutput

|

| Voltage I(typ) I(min) I(max)

|

-5.0V 4450.0m NA NA

-0.7V 95.0m NA NA

-0.6V 23.0m NA NA

-0.5V 2.4m NA NA

-0.4V 0.0m NA NA

0.0V 0.0m NA NA

*Keywords:* [ISSO PD], [ISSO PU]

*Required:* No

*Description:* The data points under the keyword [ISSO PD] define the effective current of the pulldown structure of a buffer as a function of the voltage on the pulldown reference node (the ground node), whereas the points under the keyword [ISSO PU] define the effective current of the pullup structure as a function of the voltage on the pullup reference node (the power node).

*Usage Rules:* The first column contains the voltage value at which the currents of the remaining three columns are obtained. The three remaining columns contain the typical, minimum, and maximum effective current values to be defined below of pullup/pulldown stage.

All four columns are required under this keyword. However, data is only required in the typical column. If minimum and/or maximum current values are not available, the reserved word “NA” must be used. “NA” can be used for currents in the typical column, but numeric values MUST be specified for the first and last voltage points in any table. Each table must have at least 2, but not more than 100, rows.

The [ISSO PD] table voltages are relative to the [Pulldown Reference] typ/min/max values (usually ground). The [ISSO PU] table voltages are relative to the [Pullup Reference] typ/min/max values (also usually the [Voltage Range] voltages). In the case of the [ISSO PU] table, the voltages follow the same Vtable = Vcc - Vmeasured convention as the [Pullup] table. Each of the tables are aligned with and span the typical -Vcc to Vcc voltages.

If the [ISSO PD] and [ISSO PU] keywords are not present, the effect of power supply variations on the I-V tables is not explicitly defined by the model.

The effective current table for the Isso\_pd current is extracted by the following process. The buffer is set to “logic zero.” A Vtable voltage source is inserted between the [Pulldown Reference] node and the buffer as shown in Figure 7. This Vtable voltage is swept from -Vcc (typical) to +Vcc (typical) and is relative to the [Pulldown Reference] typ/min/max values for the corresponding columns. The output is connected to the GND (typical) value as shown in Figure 7.



1. - Low State (Logic Zero) Isso\_pd Data Collection

The effective current table for the Isso\_pu current is extracted by the following process. The buffer is set to “logic one”. A Vtable voltage source is inserted between the [Pullup Reference] node and the buffer as shown below. This Vtable voltage is swept from -Vcc (typical) to +Vcc (typical) and is relative to the [Pullup Reference] typ/min/max values for the corresponding columns. The output is connected to the GND (typical) value as shown in Figure 8.



1. - High State (Logic One) Isso\_pu Data Collection

For each of these extractions, the corresponding [GND Clamp] and [POWER Clamp] currents need to be removed. Normally these are negligible. However, if on-die terminators exist, the extra currents that are associated with them should be removed from the [ISSO PD] and [ISSO PU] tables. The process details are not discussed here, but need to be solved by the modeler. Such details may depend upon the contents of the [GND Clamp] and [POWER Clamp] tables and the [GND Clamp Reference] and [POWER Clamp Reference] selections.

Currents are considered positive when their direction is into the component.

*Other Notes:* Simulators can use such tables to calculate modulation coefficients to modulate the original pulldown and pullup currents when a voltage variation on the pullup and pulldown reference nodes is revealed during power and/or ground bounce, and/or SSO simulation events.

To describe the modulation coefficients, a reference algorithm to generate an output response producing Vout(t) for a given load including clamp currents that requires an Iout(t) is shown in terms of pullup table currents Ipu(Vcc-Vout(t)) and pulldown table currents Ipd(Vout(t)). See Figure 9.



1. - Reference Data Collection

When the supplies are modulated during simulation, the modulation coefficients Ksso\_pu(Vtable\_pu) and Ksso\_pd(Vtable\_pd) modify the equations as shown in Figure 10.



1. - Reference Data Collection with Supply Modulation

The Vtable\_pd and Vtable\_pu values may change at each time step. The Ksso\_pd(Vtable\_pd) and Ksso\_pu(Vtable\_pu) values are derived from the dynamic reference voltage variation and [ISSO PD] and [ISSO PU] table entries according to the equations below:

*Ksso\_pd(Vtable\_pd) = Isso\_pd(Vtable\_pd)/Isso\_pd(0)*

*Ksso\_pu(Vtable\_pu) = Isso\_pu(Vtable\_pu)/Isso\_pu(0)*

Note that the extraction setup equates the currents for each column at Vtable = 0 lines to the corresponding pulldown and pullup table currents:

*Isso\_pd(0) = Ipd(Vcc)*

*Isso\_pu(0) = Ipu(Vcc)*

where Vcc are the typ/min/max values for the corresponding typ/min/max columns.

For example, for a typ/min/max [Voltage Range] of 5.0V, 4.5V and 5.5V, and with the negative reference set to GND, the Isso\_pu(0) and Isso\_pd(0) values for typ/min/max should be equal to the column values as shown in Table 3.

Table – Example of Setting Isso\_pu and Isso\_pd Values

|  |  |  |  |
| --- | --- | --- | --- |
|  | **Typ** | **min** | **max** |
| **Isso\_pd(0)** | Ipd(5.0) | Ipd(4.5) | Ipd(5.5) |
| **Isso\_pu(0)** | Ipu(5.0) | Ipu(4.5) | Ipu(5.5) |

With no modulation, Ksso\_pd(0) = 1 and Ksso\_pu(0) = 1. However, if during simulation of the typical corner the Vcc voltage drops from 5.0 to 4.7, then Vtable\_pu = 5.0 - 4.7 = 0.3, and Ksso\_pu(0.3) is calculated. If at the same time the ground reference voltage at the buffer increases to 0.2 V, then Ksso\_pd(0.2) is calculated. These two modulation factors are used in the reference model calculations to account for gate modulation effects associated with both output transistors.

These modulation factors are updated at each time step.

Note that the [ISSO PD] and [ISSO PU] keywords are designed for CMOS technology and may not be appropriate for bipolar or ECL technologies. A single [ISSO PU] or [ISSO PD] keyword table is appropriate for open technologies such as Open\_drain, Open\_source, Open\_sink, etc.

As a minor source of error, actual modulation effects may lag slightly from simulated modulation effects due to internal delays within the physical device.

*Example:*

| Assume [Voltage Range] is 1.8V (typ), 1.7V (min) and 1.95V (max).

|

| The table voltage entries are relative to the typ/min/max of the

| corresponding reference voltage for each table.

[ISSO PD] | Relative to the [Pulldown Reference] voltage

|

| Voltage I(typ) I(min) I(max)

|

-1.8V 10.0m 7.0m 13.0m

| .

| .

-0.5V 24.0m 18.0m 31.0m

-0.2V 27.0m 20.0m 37.0m

0.0V 25.0m 19.0m 34.0m

0.2V 18.0m 13.0m 26.0m

0.5V 10.0m 7.0m 16.0m

0.7V 5.0m 3.0m 9.0m

1.0V 1.0m 0.7m 3.0m

| .

| .

1.8V 0.0m 0.0m 0.0m

|

[ISSO\_PU] | Relative to the [Pullup Reference] voltage)

|

| Voltage I(typ) I(min) I(max)

|

-1.8V -10.0m -9.0m -14.0m

| .

| .

-0.6V -28.0m -19.0m -40.0m

-0.4V -31.0m -22.0m -43.0m

-0.2V -29.0m -21.0m -40.0m

0.0V -27.0m -19.0m -38.0m

0.2V -21.0m -14.0m -31.0m

0.4V -14.0m -9.0m -22.0m

| .

| .

1.8V 0.0m 0.0m 0.0m

*Keywords:* [Rgnd], [Rpower], [Rac], [Cac]

*Required:* Yes, if they exist in the model

*Description:* The data for these keywords define the resistance values of Rgnd and Rpower connected to GND and the POWER pins, respectively, and the resistance and capacitance values for an AC terminator. See Figure 11.

*Usage Rules:* For each of these keywords, the three columns hold the typical, minimum, and maximum resistance values. The three entries for R(typ), R(min), and R(max), or the three entries for C(typ), C(min), and C(max), must be placed on a single line and must be separated by at least one white space. All three columns are required under these keywords. However, data is only required in the typical column. If minimum and/or maximum values are not available, the reserved word “NA” must be used indicating the R(typ) or C(typ) value by default. Note that only one instance of any one of these keywords is permitted within any single [Model]. For example, [Rgnd] may not be used twice under the same [Model] description.

*Other Notes:* [Rpower] is connected to “Vcc” and [Rgnd] is connected to “GND”. However, [GND Clamp Reference] voltages, if defined, apply to [Rgnd]. [POWER Clamp Reference] voltages, if defined, apply to [Rpower]. Either or both [Rgnd] and [Rpower] may be defined and may coexist with [GND Clamp] and [POWER Clamp] tables. If the terminator consists of a series R and C (often referred to as either an AC or RC terminator), then both [Rac] and [Cac] are required. When [Rgnd], [Rpower], or [Rac] and [Cac] are specified, the Model\_type must be Terminator.



1. - [Rgnd], [Rpower], [Rac], [Cac] in Relation to Package and Buffer Data

*Example:*

| variable R(typ) R(min) R(max)

[Rgnd] 330ohm 300ohm 360ohm | Parallel Terminator

[Rpower] 220ohm 200ohm NA

|

[Rac] 30ohm NA NA

|

| variable C(typ) C(min) C(max) | AC terminator

[Cac] 50pF NA NA

*Keywords:* [On], [Off]

*Required:* Yes, both [On] and [Off] for Series\_switch Model\_types only

*Description:* The “On” state electrical models are positioned under [On]. The “Off” state electrical models are positioned under [Off].

*Usage Rules:* These keywords are only valid for Series\_switch Model\_types. Only keywords associated with Series\_switch electrical models are permitted under [On] or [Off]. The Series electrical models describe the path for one state only and do not use the [On] and [Off] keywords.

In Series\_switch models, [On] or [Off] must be positioned before any of the [R Series], [L Series], Rl Series], [C Series], [Lc Series], [Rc Series], [Series Current], and [Series MOSFET] keywords. There is no provision for any of these keywords to be defined once, but to apply to both states.

*Example:*

[On]

| ... On state keywords such as [R Series], [Series Current], [Series MOSFET]

[Off]

| ... Off state keywords such as [R Series], [Series Current]

*Keywords:* [R Series], [L Series], [Rl Series], [C Series], [Lc Series], [Rc Series]

*Required:* Yes, if they exist in the model

*Description:* The data for these keywords allow the definition of Series or Series\_switch R, L or C paths.

*Usage Rules:* For each of these keywords, the three columns hold the typical, minimum, and maximum resistance values. The three entries must be placed on a single line and must be separated by at least one white space. All three columns are required under these keywords. However, data is only required in the typical column. If minimum and/or maximum values are not available, the reserved word “NA” must be used.

Note that only one instance of any one of these keywords is permitted within any single [On] or [Off] keyword for [Model]s of type Series\_switch. For example, [L Series] may not be used twice under the same [Off] description. Similarly, only one instance of any one of these keyword is permitted within any single [Model] of type Series.

*Other Notes:* This series RLC model is defined to allow IBIS to model simple passive models and/or parasitics.

These keywords are valid only for Series or Series\_switch Model\_types.

The model is shown in Figure 12.



1. - Series Element Associations

[Rl Series] shall be defined only if [L Series] exists. [Rl Series] is 0 ohms if it is not defined in the path.

[Rc Series] and [Lc Series] shall be defined only if [C Series] exists. [Rc Series] is 0 ohms if it is not defined in the path. [Lc Series] is 0 henries if it is not defined in the path.

C\_comp values are ignored for series models.

*Example:*

| variable R(typ) R(min) R(max)

[R Series] 8ohm 6ohm 12ohm

|

| variable L(typ) L(min) L(max)

[L Series] 5nH NA NA

| variable R(typ) R(min) R(max)

[Rl Series] 4ohm NA NA

|

| variable C(typ) C(min) C(max) | The other elements

[C Series] 50pF NA NA | are 0 impedance

*Keyword*: [Series Current]

*Required:* Yes, if they exist in the model

*Description:* The data points under this keyword define the I-V tables for voltages measured at Pin 1 with respect to Pin 2. Currents are considered positive if they flow into Pin 1. Pins 1 and 2 are listed under the [Series Pin Mapping] keyword under columns [Series Pin Mapping] and pin\_2, respectively.

*Usage Rules:* The first column contains the voltage value, and the remaining columns hold the typical, minimum, and maximum current values. The four entries, Voltage, I(typ), I(min), and I(max) must be placed on a single line and must be separated by at least one white space.

All four columns are required under these keywords. However, data is only required in the typical column. If minimum and/or maximum current values are not available, the reserved word “NA” must be used. “NA” can be used for currents in the typical column, but numeric values MUST be specified for the first and last voltage points on any I-V table. Each I-V table must have at least 2, but not more than 100 rows.

*Other Notes:* There is no monotonicity requirement. However the model supplier should realize that it may not be possible to derive a behavioral model from non-monotonic data. This keyword is valid only for Series or Series\_switch Model\_types.

The model is shown in Figure 13.



1. - [Series Current] Voltage Polarity and Current Direction

C\_comp values are ignored for [Series Current] models.

*Example:*

[Series Current]

| Voltage I(typ) I(min) I(max)

-5.0V -3900.0m -3800.0m -4000.0m

-0.7V -80.0m -75.0m -85.0m

-0.6V -22.0m -20.0m -25.0m

-0.5V -2.4m -2.0m -2.9m

-0.4V 0.0m 0.0m 0.0m

5.0V 0.0m 0.0m 0.0m

*Keyword:* [Series MOSFET]

*Required:* Yes, for series MOSFET switches

*Description:* The data points under this keyword define the I-V tables for voltages measured at Pin 2 for a given Vds setting. Currents are considered positive if they flow into Pin 1. Pins 1 and 2 are listed under the [Series Pin Mapping] keyword under [Series Pin Mapping] and pin\_2 columns, respectively. See Figure 14.

Sub-Params: Vds

*Usage Rules:* The first column contains the voltage value, and the three remaining columns hold the typical, minimum, and maximum current values. The four entries, Voltage, I(typ), I(min), and I(max) must be placed on a single line and must be separated by at least one white space.

All four columns are required under this keyword. However, data is only required in the typical column. If minimum and/or maximum current values are not available, the reserved word “NA” must be used. “NA” can be used for currents in the typical column, but numeric values MUST be specified for the first and last voltage points on any I-V table. Each I-V table must have at least 2, but not more than 100 rows.

*Other Notes:* There is no monotonicity requirement. However the model supplier should realize that it may not be possible to derive a behavioral model from non-monotonic data.



1. - [Series MOSFET] Voltage Polarities and Current Direction

Either of the FETs could be removed (or have zero current contribution). Thus this model covers all four conditions: off, single NMOS, single PMOS, and parallel NMOS/PMOS.

*Voltage = Table Voltage = Vtable = Vcc - Vs*

*Ids = Table Current for a given Vcc and Vds*

Internal Logic that is generally referenced to the power rail is used to set the NMOS MOSFET switch to its “On” state. Internal logic, likewise referenced to ground, is used to set the PMOS device to its “On” state if the PMOS device is present. Thus, the [Voltage Range] settings provide the assumed gate voltages. If the [POWER Clamp Reference] exists, it overrides the [Voltage Range] value. The table entries are actually Vgs values of the NMOS device and Vcc - Vgs values of the PMOS device, if present. The polarity conventions are identical with those used for other tables that are referenced to power rails. Thus, the voltage column can be viewed as a table defining the source voltages Vs according to the convention: Vtable = Vcc - Vs. This convention remains even without the NMOS device.

If the switch is used in an application such as interfacing between 3.3 V and 5.0 V logic, the Vcc may be biased at a voltage (such as 4.3 V) that is different from a power rail voltage (such as 5.0 V) used to create the model. Just readjust the [Voltage Range] entries (or [POWER Clamp Reference] entries).

One fundamental assumption in the MOSFET switch model is that it operates in a symmetrical manner. The tables and expressions are given assuming that Vd >= Vs. If Vd < Vs, then apply the same relationships under the assumption that the source and drain nodes are interchanged. A consequence of this assumption is that the Vds subparameter is constrained to values Vds > 0. It is assumed that with Vds = 0 the currents will be 0 mA. A further consequence of this assumption that would be embedded in the analysis process is that the voltage table is based on the side of the model with the lowest voltage (and that side is defined as the source). Thus the analysis must allow current to flow in both directions, as would occur due to reflections when the switch is connected in series with an unterminated transmission line.

The model data is used to create an On state relationship between the actual drain to source current, ids, and the actual drain to source voltage, vds:

*ids = f(vds).*

This functional relationship depends on the actual source voltage Vs and can be expressed in terms of the corresponding table currents associated with Vs (and expressed as a function of Vtable).

If only one [Series MOSFET] table is supplied (as a first order approximation), the functional relationship is assumed to be linearly related to the table drain to source current, Ids, for the given Vds subparameter value and located at the existing gate to source voltage value Vtable. This table current is denoted as Ids(Vtable, Vds). The functional relationship becomes:

*ids = Ids(Vtable, Vds) \* vds/Vds.*

More than one [Series MOSFET] table under a [Model] keyword is permitted. However, the usage of this data is simulator dependent. Each table must begin with the [Series MOSFET] keyword and Vds subparameter. Each successive [Series MOSFET] table must have a different subparameter value for Vds. The number of tables for any specific [Model] must not exceed 100.

C\_comp values are ignored for [Series MOSFET] models.

*Examples:*

| An NMOS Example

|

[On]

[Series MOSFET]

Vds = 1.0

| Voltage I(typ) I(min) I(max)

5.0V 257.9m 153.3m 399.5m | Defines the Ids current as a

4.0V 203.0m 119.4m 317.3m | function of Vtable, for Vds = 1.0

3.0V 129.8m 74.7m 205.6m

2.0V 31.2m 16.6m 51.0m

1.0V 52.7p 46.7p 56.7p

0.0V 0.0p 0.0p 0.0p

|

| A PMOS/NMOS Example

|

[On]

[Series MOSFET]

Vds = 0.5

| Voltage I(typ) I(min) I(max)

0.0 48.6ma NA NA

0.1 47.7ma NA NA

0.2 46.5ma NA NA

0.3 46.1ma NA NA

0.4 45.3ma NA NA

0.5 44.4ma NA NA

0.6 42.9ma NA NA

0.7 42.3ma NA NA

0.8 41.2ma NA NA

0.9 39.7ma NA NA

1.0 38.6ma NA NA

1.1 38.1ma NA NA

1.2 38.6ma NA NA

1.3 40.7ma NA NA

1.4 45.0ma NA NA

1.5 49.2ma NA NA

1.6 52.3ma NA NA

1.7 55.1ma NA NA

1.8 57.7ma NA NA

1.9 58.8ma NA NA

2.0 58.9ma NA NA

2.1 59.2ma NA NA

2.2 59.3ma NA NA

2.3 59.4ma NA NA

2.4 59.8ma NA NA

2.5 60.1ma NA NA

2.6 61.8ma NA NA

2.7 62.3ma NA NA

2.8 63.4ma NA NA

2.9 64.4ma NA NA

3.0 65.3ma NA NA

3.1 66.0ma NA NA

3.2 66.8ma NA NA

3.3 68.2ma NA NA

Keyword: [Ramp]

*Required:* Yes, except for inputs, terminators, Series, and Series\_switch model types

*Description:* Defines the rise and fall times of a buffer. The ramp rate does not include packaging but does include the effects of the C\_comp or C\_comp\_\* parameters.

*Sub-Params:* dV/dt\_r, dV/dt\_f, R\_load

*Usage Rules:* The rise and fall time is defined as the time it takes the output to go from 20% to   
80% of its final value. The ramp rate is defined as:

The ramp rate must be specified as an explicit fraction and must not be reduced. The [Ramp] values can use “NA” for the min and max values only. The R\_load subparameter is optional if the default 50 ohm load is used. The R\_load subparameter is required if a non-standard load is used.

*Example:*

[Ramp]

| variable typ min max

dV/dt\_r 2.20/1.06n 1.92/1.28n 2.49/650p

dV/dt\_f 2.46/1.21n 2.21/1.54n 2.70/770p

R\_load = 300ohms

*Keywords:* [Rising Waveform], [Falling Waveform]

*Required:* No

*Description:* Describes the shape of the rising and falling edge waveforms of a driver.

*Sub-Params:* R\_fixture, V\_fixture, V\_fixture\_min, V\_fixture\_max, C\_fixture, L\_fixture, R\_dut, L\_dut, C\_dut

*Usage Rules:* Each [Rising Waveform] and [Falling Waveform] keyword introduces a table of voltage versus time points that describe the shape of an output waveform. These voltage versus time points are taken under the conditions specified by the R/L/C/V\_fixture and R/L/C\_dut subparameters. The table itself consists of one column of time points, then three columns of voltage points in the standard typ, min, and max format. The four entries must be placed on a single line and must be separated by at least one white space. All four columns are required. However, data is only required in the typical column. If minimum or maximum data is not available, use the reserved word “NA”. The first value in the time column need not be “0”. Time values must increase as one parses down the table. The waveform table can contain a maximum of 1000 data rows. A maximum of 100 waveform tables are allowed per model.

Note that for backward compatibility, the existing [Ramp] keyword is still required. The data in the waveform table is taken with the effects of the C\_comp parameter included.

A waveform table must include the entire waveform; i.e., the first entry (or entries) in a voltage column must be the DC voltage of the output before switching and the last entry (or entries) of the column must be the final DC value of the output after switching. Each table must contain at least two entries. Thus, numerical values are required for the first and last entries of any column containing numerical data.

The data in all of the waveform tables should be time correlated. In other words, the edge data in each of the tables (rising and falling) should be entered with respect to a single point in time when the input stimulus is assumed to have initiated a logic transition. All waveform extractions should reference a common input stimulus time in order to provide a sufficiently accurate alignment of waveforms. The first line in each waveform table should be assumed to be the reference point in time corresponding to a logic transition. For example, assume that some internal rising edge logic transition starts at time = 0. Then a rising edge voltage-time table might be created starting at time zero. The first several table entries might be some “lead-in” time caused by some undefined internal buffer delay before the voltage actually starts transitioning. The falling edge stimulus (for the purpose of setting reference time for the voltage-time table) should also start at time = 0. And, the falling edge voltage-time table would be created starting at time zero with a possibly different amount of “lead-in” time caused by a possibly different but corresponding falling edge internal buffer delay. Any actual device differences in internal buffer delay time between rising and falling edges should appear as differing lead-in times between the rising and the falling waveforms in the tables just as any differences in actual device rise and fall times appear as differing voltage-time entries in the tables.

A [Model] specification can contain more than one rising edge or falling edge waveform table. However, each new table must begin with the appropriate keyword and subparameter list as shown below. If more than one rising or falling edge waveform table is present, then the data in each of the respective tables must be time correlated. In other words, the rising (falling) edge data in each of the rising (falling) edge waveform tables must be entered with respect to a common reference point on the input stimulus waveform.

The “fixture” subparameters specify the loading conditions under which the waveform is taken. The R\_dut, C\_dut, and L\_dut subparameters are analogous to the package parameters R\_pkg, C\_pkg, and L\_pkg and are used if the waveform includes the effects of pin inductance/capacitance. Figure 15 shows the interconnection of these elements.



1. - [Rising Waveform] and [Falling Waveform] Fixtures

NOTE: The use of L\_dut, R\_dut, and C\_dut is strongly discouraged in developing waveform data from simulation models. Some simulators may ignore these parameters because they may introduce numerical time constant artifacts.

Only the R\_fixture and V\_fixture subparameters are required; the rest of the subparameters are optional. If a subparameter is not used, its value defaults to zero. The subparameters must appear in the text after the keyword and before the first row of the waveform table.

V\_fixture defines the voltage for typ, min, and max supply conditions. However, when the fixture voltage is related to the power supply voltages, then the subparameters V\_fixture\_min and V\_fixture\_max can be used to further specify the fixture voltage for min and max supply voltages.

NOTE: Test fixtures with R\_fixture and V\_fixture, V\_fixture\_min, and V\_fixture\_max only are strongly encouraged because they provide the BEST set of data needed to produce the best model for simulation. C\_fixture and L\_fixture can be used to produce waveforms which describe the typical test case setups for reference.

NOTE: In most cases two [Rising Waveform] tables and two [Falling Waveform] tables will be necessary for accurate modeling.

All tables assume that the die capacitance is included. Potential numerical problems associated with processing the data using the effective C\_comp (or C\_comp\_\* values as appropriate) for effective die capacitance may be handled differently among simulators.

*Example:*

[Rising Waveform]

R\_fixture = 50

V\_fixture = 0.0

| C\_fixture = 50p | These are shown, but are generally not recommended

| L\_fixture = 2n

| C\_dut = 7p

| R\_dut = 1m

| L\_dut = 1n

| Time V(typ) V(min) V(max)

0.0000s 25.2100mV 15.2200mV 43.5700mV

0.2000ns 2.3325mV -8.5090mV 23.4150mV

0.4000ns 0.1484V 15.9375mV 0.3944V

0.6000ns 0.7799V 0.2673V 1.3400V

0.8000ns 1.2960V 0.6042V 1.9490V

1.0000ns 1.6603V 0.9256V 2.4233V

1.2000ns 1.9460V 1.2050V 2.8130V

1.4000ns 2.1285V 1.3725V 3.0095V

1.6000ns 2.3415V 1.5560V 3.1265V

1.8000ns 2.5135V 1.7015V 3.1600V

2.0000ns 2.6460V 1.8085V 3.1695V

| ...

10.0000ns 2.7780V 2.3600V 3.1670V

|

[Falling Waveform]

R\_fixture = 50

V\_fixture = 5.5

V\_fixture\_min = 4.5

V\_fixture\_max = 5.5

| Time V(typ) V(min) V(max)

0.0000s 5.0000V 4.5000V 5.5000V

0.2000ns 4.7470V 4.4695V 4.8815V

0.4000ns 3.9030V 4.0955V 3.5355V

0.6000ns 2.7313V 3.4533V 1.7770V

0.8000ns 1.8150V 2.8570V 0.8629V

1.0000ns 1.1697V 2.3270V 0.5364V

1.2000ns 0.7539V 1.8470V 0.4524V

1.4000ns 0.5905V 1.5430V 0.4368V

1.6000ns 0.4923V 1.2290V 0.4266V

1.8000ns 0.4639V 0.9906V 0.4207V

2.0000ns 0.4489V 0.8349V 0.4169V

| ...

10.0000ns 0.3950V 0.4935V 0.3841V

*Keyword:* [Composite Current]

*Required:* No

*Description:* Describes the shape of the rising and falling edge current waveforms from the power reference terminal of the buffer.

*Usage Rules:* The [Composite Current] keyword is positioned under the last row of the [Rising Waveform] table (for rising waveform currents) or [Falling Waveform] table (for falling waveform currents). The keywords are followed by a table of current versus time rows (I-T) that describe the shape of a current waveform. These I-T tables inherit the test fixture load of the [Rising Waveform] or [Falling Waveform] R/L/C/V\_fixture and R/L/C\_dut subparameters.

The [Composite Current] keyword is optional. It can be omitted, or it can be positioned under some or all of the rising and falling waveform tables.

The table itself consists of one column of time points, then three columns of current points in the standard typ, min, and max format. The four entries must be placed on a single line and must be separated by at least one white space. All four columns are required. However, data is only required in the typical column. If minimum or maximum data is not available, use the reserved word “NA”. The first value in the time column need not be “0”. Time values must increase as one parses down the table. The waveform table can contain a maximum of 1000 data points.

The I-T table data must be time-correlated with the V-T data above it. That is, the I-T data should be entered with respect to the same point in time that the V-T table above it references and for the given \*\_fixture load. See the [Rising Waveform] and [Falling Waveform] section for more information about the common input stimulus time. Note that additional "lead-in" time may need to be added to all V-T waveforms, as a portion of the I-T waveform data describes pre-driver current that may occur earlier in time than the V-T rising or falling edge transitions.

Figure 16 illustrates a general configuration from which a [Rising Waveform] or [Falling Waveform] is extracted. The DUT die shows all of the available power and ground pin reference voltage terminals. For many buffers, only one power pin and one common ground pin terminal are used. The absolute GND is the reference for the V\_fixture voltage and the package model equivalent network. It can also serve as a reference for C\_comp, unless C\_comp is optionally split into component attached to the other reference voltages.

The [Composite Current] I-T table includes all of the current through the [Pullup Reference] terminal. If the [POWER Clamp Reference] terminal is the same as the [Pullup Reference] terminal (according to the [Pin Mapping] keyword table), the [Composite Current] entries include the currents through both the [POWER Clamp] and [Pullup] sections of the DUT (for example, when an on-die terminator is connected to the power reference terminal). Note that the terminals are shown in terms of separately defined reference voltages, but still exist even if they are defined with default [Voltage Range] or 0 V settings.



1. - [External Reference] - (used only for non-driver modes)

For \*\_ECL model types, the [Pullup] and [Pulldown] sections of the DUT share the same power reference terminal. The [Composite Current] includes the currents through both sections.

*Other Notes:* Figure 17 documents some expected internal paths for a useful special case where only one common power pin (VDDQ) and one common ground exists (GND).



1. - [Composite Current] Internal Current Paths

Other elements in a more detailed typical (per buffer) model are:

I\_byp - Bypass current

I\_pre - Pre-Driver current

I\_cb - Crow-bar current

I\_term - Termination current (optional)

L\_VDDQ - On-die inductance of I/O Power

R\_VDDQ - On-die resistance of I/O Power

L\_GND - On-die inductance of Ground

R\_GND - On-die resistance of Ground

C\_p+b - Bypass + Parasitic Capacitance

ESR - Equivalent Series Resistance for on-die Decap

ESL - Equivalent Series Inductance for on-die Decap

While the [Composite Current] already includes the buffer I\_byp current, some Series model type elements may be used to document an equivalent bypass impedance to improve simulation results. Such an equivalent impedance can be extracted on a per buffer basis, but summed and expressed as a total equivalent impedance between the power and ground pins of the component with the Series model type keywords, including [C Series], [Lc Series], [Rc Series], and [R Series] under a separate [Model]. These elements are connected using the [Series Pin Mapping] keyword. Paths between several voltage rails can be modeled in this manner. The [Pin Mapping] keyword documents what buffers share common and often isolated power rails.

The C\_p+b value might include the detailed distribution of C\_comp when C\_comp\* is attached to several rails. If the C\_comp value and the C\_p+b value are about the same magnitude, the [C Series] value should be adjusted to avoid double counting.

The power reference terminal (VDDQ) is usually the [Pullup Reference], or the default [Voltage Range] terminal. The [Pulldown Reference] terminal is usually at the GND connection.

The [Composite Current] can still be defined for model types without the [Pullup] keywords (such as Open\_drain) because the [Pullup Reference] or [Voltage Range] are still required. Pre-driver and other internal paths still can exist.

In most cases six [Composite Current] tables are recommended for accurate modeling. The first four tables correspond to the recommended fixture conditions for [Rising Waveform] and [Falling Waveform] tables (normally 50 ohm loads to Vdd and GND). Two additional waveforms for no load conditions (such as with an R\_fixure of 1.0 Megaohm) are useful. However, some EDA tools process only the first four waveforms. So the additional open load waveforms for I-T tables should be in [Rising Waveform] and [Falling Waveform] tables that are positioned after the other V-T tables to maintain the best output response simulation accuracy.

For Open\_drain and Open\_source technologies, two tables are often specified (one for the [Rising Waveform] and one for the [Falling Waveform]). The tables should be positioned in front of any other optional waveform tables because some EDA tools process just the first two tables. Also, the open load tables may not yield meaningful simulations unless internal on-die terminators exist.

When the [Model] is configured for differential operation with the [Diff Pin] keyword, the individual I-T currents for each [Model] are used as an approximation, and may not accurately conform to the measured currents under actual differential operation.

The [Composite Current] table can be derived from currents measured at the [Pulldown Reference] (GND) node, but adjusted for the current flowing through the output pin and at other terminals.

The [Pin Mapping] keyword is used to document how buffers with common voltage rails are connected. The effective impedances for each buffer between the [Pullup Reference] and [Pulldown Reference] are then combined to form the total effective impedance between the voltage rails.

The [Composite Current] keyword does not accurately document the effects of controlled switching buffers such as those with [Submodel] or [Driver Schedule] keywords. The currents associated with [Submodel] switching under specified test load conditions can occur at different times under other load conditions. The scheduled models under the [Driver Schedule] keyword can be attached to different voltage rails in an undocumented manner.

*Example:*

[Rising Waveform]

R\_fixture = 50.0

V\_fixture = 0.0

| ...

| ... | Rising Waveform table

| ...

[Composite Current]

|

| Time I(typ) I(min) I(max)

0 4.243E-05 NA NA

4.00E-11 4.244E-05 NA NA

8.00E-11 4.242E-05 NA NA

1.20E-10 4.265E-05 NA NA

1.60E-10 3.610E-05 NA NA

2.00E-10 3.903E-03 NA NA

..

..

..

3.80E-09 2.012E-02 NA NA

3.84E-09 2.012E-02 NA NA

3.88E-09 2.012E-02 NA NA

3.92E-09 2.012E-02 NA NA

3.96E-09 2.012E-02 NA NA

4.00E-09 2.012E-02 NA NA

|

[Falling Waveform]

R\_fixture = 50.0

V\_fixture = 1.8

| ...

| ... | Falling Waveform table

| ...

[Composite Current]

|

| Time I(typ) I(min) I(max)

0 4.302E-05 NA NA

4.00E-11 4.299E-05 NA NA

8.00E-11 4.304E-05 NA NA

1.20E-10 4.287E-05 NA NA

1.60E-10 4.782E-05 NA NA

2.00E-10 1.459E-04 NA NA

..

..

..

3.80E-09 4.933E-05 NA NA

3.84E-09 5.211E-05 NA NA

3.88E-09 5.490E-05 NA NA

3.92E-09 5.441E-05 NA NA

3.96E-09 4.842E-05 NA NA

4.00E-09 4.244E-05 NA NA

|

| ... etc.

1. Add Submodel Description

The [Add Submodel] keyword can be used under a top-level [Model] keyword to add special-purpose functionality to the existing top-level model. This section describes the structure of the top-level model and the submodel.

Top-Level Model:

When special-purpose functional detail is needed, the top-level model can call one or more submodels. The [Add Submodel] keyword is positioned after the initial set of required and optional subparameters of the [Model] keyword and among the keywords under [Model].

The [Add Submodel] keyword lists of name of each submodel and the permitted mode (Driving, Non-Driving or All) under which each added submodel is used.

Submodel:

A submodel is defined using the [Submodel] keyword. It contains a subset of keywords and subparameters used for the [Model] keyword along with other keywords and subparameters that are needed for the added functionality.

The [Submodel] and [Submodel Spec] keywords are defined first since they are used for all submodels.

The only required subparameter in [Submodel] is Submodel\_type to define the list of submodel types. No subparameters under [Model] are permitted under the [Submodel] keyword.

The following keywords that are defined under the [Model] keyword are supported by the [Submodel] keyword:

[Pulldown]

[Pullup]

[GND Clamp]

[POWER Clamp]

[Ramp]

[Rising Waveform]

[Falling Waveform]

The [Voltage Range], [Pullup Reference], [Pulldown Reference], [GND Clamp Reference], and [POWER Clamp Reference] keywords are not permitted. The voltage settings are inherited from the top-level model. The following additional keywords are used only for the [Submodel] and are documented in this section:

[Submodel Spec]

[GND Pulse Table]

[POWER Pulse Table]

The application of these keywords depends upon the Submodel\_type entries listed below:

Dynamic\_clamp

Bus\_hold

Fall\_back

Permitted keywords that are not defined for any of these submodel types are ignored. The rules for what set of keywords are required are found under the Dynamic Clamp, Bus Hold, and Fall Back headings of this section.

*Keyword:* [Submodel]

*Required:* No

*Description:* Used to define a submodel, and its attributes.

*Sub-Params:* Submodel\_type

*Usage Rules:* Each submodel must begin with the keyword [Submodel]. The submodel name must match the one that is listed under an [Add Submodel] keyword and must not contain more than 20 characters. A .ibs file must contain enough [Submodel] keywords to cover all of the model names specified under the [Add Submodel] keyword.

Submodel\_type subparameter is required and must be one of the following:  
Dynamic\_clamp, Bus\_hold, Fall\_back

The C\_comp subparameter is not permitted under the [Submodel] keyword. The total effective die capacitance including the submodel contributions are provided in the top-level model.

*Other Notes:* The following list of keywords that are defined under the [Model] keyword can be used under [Submodel]:  
[Pulldown], [Pullup], [GND Clamp], [POWER Clamp], [Ramp], [Rising Waveform], and [Falling Waveform].

The following list of additional keywords can be used:  
[Submodel Spec], [GND Pulse Table], and [POWER Pulse Table].

*Example:*

[Submodel] Dynamic\_clamp1

Submodel\_type Dynamic\_clamp

*Keyword:* [Submodel Spec]

*Required:* No

*Description:* The [Submodel Spec] keyword defines four columns under which specification and information subparameters are defined for submodels.

*Sub-Params:* V\_trigger\_r, V\_trigger\_f, Off\_delay

*Usage Rules:* The [Submodel Spec] is to be used only with submodels.

The following subparameters are used:

V\_trigger\_r Rising edge trigger voltage

V\_trigger\_f Falling edge trigger voltage

Off\_delay Turn-off delay from V\_trigger\_r or V\_trigger\_f

For each subparameter contained in the first column, the remaining three hold its typical, minimum and maximum values. The entries of typical, minimum, and maximum be must be placed on a single line and must be separated by at least one white space. All four columns are required under the [Submodel Spec] keyword. However, data is required only in the typical column. If minimum and/or maximum values are not available, the reserved word “NA” must be used to indicate the typical value by default.

The values in the minimum and maximum columns usually correspond to the values in the same columns for the inherited top-level voltage range or reference voltages in the top-level model. The V\_trigger\_r and V\_trigger\_f subparameters should hold values in the minimum and maximum columns that correspond to the voltage range or reference voltages of the top-level model. The Off\_delay subparameter, however, is an exception to this rule because in some cases it may be completely or partially independent from supply voltages and/or manufacturing process variations. Therefore the minimum and maximum entries for the Off\_delay subparameter should be ordered simply by their magnitude.

Unless noted, each [Submodel Spec] subparameter is independent of any other subparameter.

V\_trigger\_r, V\_trigger\_f rules:

The voltage trigger values for the rising and falling edges provide the starting time when an action is initiated.

Off\_delay rules:

The functionality of the Off\_delay subparameter is to provide an additional time related mechanism to turn off circuit elements.

*Example:*

| Dynamic Clamp Example:

|

[Submodel Spec]

| Subparameter typ min max

|

V\_trigger\_r 3.6 2.9 4.3 | Starts power pulse table

V\_trigger\_f 1.4 1.2 1.6 | Starts gnd pulse table

|

| Bus Hold Example:

|

[Submodel Spec]

| Subparameter typ min max

V\_trigger\_r 3.1 2.4 3.7 | Starts low to high

| bus hold transition

V\_trigger\_f 1.8 1.6 2.0 | Starts high to low

| bus hold transition

|

| Bus\_hold application with pullup structure triggered on and then clocked

| off:

|

[Submodel Spec]

| Subparameter typ min max

V\_trigger\_r 3.1 2.4 3.7 | Low to high transition

| triggers the turn on

| process of the pullup

V\_trigger\_f -10.0 -10.0 -10.0 | Not used, so trigger

| voltages are set out

| of range

Off\_delay 5n 4n 6n | Time from rising edge

| trigger at which the

| pullup turned off

Dynamic Clamp:

When the Submodel\_type subparameter under the [Submodel] keyword is set to Dynamic\_clamp, the submodel describes the dynamic clamp functionality.

The [GND Pulse Table] and [POWER Pulse Table] keywords are defined. An example for a complete dynamic clamp model is provided below.

*Keywords:* [GND Pulse Table], [POWER Pulse Table]

*Required:* No

*Description:* Used to specify the offset voltage versus time of [GND Clamp] and [POWER Clamp] tables within submodels.

*Usage Rules:* Each [GND Pulse Table] and [POWER Pulse Table] keyword introduces a table of voltage vs. time points that describe the shape of an offset voltage from the [GND Clamp Reference] voltage (or default ground) or the [POWER Clamp Reference] voltage (or default [Voltage Range] voltage). Note that these voltage values are inherited from the top-level model.

The table itself consists of one column of time points, then three columns of voltage points in the standard typ, min, and max format. The four entries must be placed on a single line and must be separated by at least one white space. All four columns are required. However, data is only required in the typical column. If minimum or maximum data is not available, use the reserved word “NA”. Time values must increase as one parses down the table. The waveform table can contain of maximum of 100 rows.

Each table must contain at least two entries. Thus, numerical values are required for the first and last entries of any column containing numerical data.

The voltage entries in both the [Gnd Pulse Table] and [POWER Pulse Table] tables are directly measured offsets. At each instance, the [Gnd Pulse Table] voltage is ADDED to the [GND Clamp] table voltages to provide the shifted table voltages. At each instance, the [POWER Pulse Table] voltage is SUBTRACTED (because of polarity conventions) from the [POWER Clamp] table voltages to provide the shifted table voltages.

Only one [GND Pulse Table] and one [POWER Pulse Table] are allowed per model.

The [GND Pulse Table] and [POWER Pulse Table] interact with [Submodel Spec] subparameters V\_trigger\_f and V\_trigger\_r. Several modes of operation exist based on whether a pulse table and its corresponding trigger subparameter are given. These modes are classified as triggered and static.

Triggered Mode:

For triggered mode, a pulse table must exist and include the entire waveform; i.e., the first entry (or entries) in a voltage column must be equal to the last entry.

Also, a corresponding [Submodel Spec] V\_trigger\_\* subparameter must exist. The triggered interaction is described:

The V\_trigger\_f subparameter under [Submodel Spec] is used to detect when the falling edge waveform at the die passes the trigger voltage. At that time, the [Gnd Pulse Table] operation starts. Similarly, the V\_trigger\_r subparameter is used to detect when the rising edge waveform at the die passes the trigger voltage. At that time, [POWER Pulse Table] operation starts. The [GND Pulse Table] dependency is shown in Figure 18.



1. – [GND Pulse Table] Waveforms at Die

The V\_trigger\_r and [POWER Pulse Table] operate in a similar manner. When the V\_trigger\_r voltage value is reached on the rising edge, the [POWER Pulse Table] is started. Normally the offset voltage entries in the [POWER Pulse Table] are negative.

Static Mode:

When the [GND Pulse Table] keyword does not exist, but the added model [GND Clamp] table does exist, the added model [GND Clamp] is used directly. Similarly, when the [POWER Pulse Table] keyword does not exist, but the added model [POWER Clamp] table does exist, the added model [POWER Clamp] is used directly.

This mode provides additional fixed clamping to an I/O\_\* buffer or a 3-state buffer when it is used as a driver.

*Example:*

| Dynamic\_clamp Model with both dynamic GND and POWER clamps

|

[Submodel] Dynamic\_Clamp\_1

Submodel\_type Dynamic\_clamp

|

[Submodel Spec]

| Subparameter typ min max

|

V\_trigger\_f 1.4 1.2 1.6 | Falling edge trigger

V\_trigger\_r 3.6 2.9 4.3 | Rising edge trigger

|

| typ min max

| [Voltage Range] 5.0 4.5 5.5

| Note, the actual voltage range and reference voltages are inherited from

| the top-level model.

|

[GND Pulse Table] | GND Clamp offset table

|

| Time V(typ) V(min) V(max)

|

0 0 0 0

1e-9 0 0 0

2e-9 0.9 0.8 1.0

10e-9 0.9 0.8 1.0

11e-9 0 0 0

|

[GND Clamp] | Table to be offset

|

| Voltage I(typ) I(min) I(max)

|

-5.000 -3.300e+01 -3.000e+01 -3.500e+01

-4.000 -2.300e+01 -2.200e+01 -2.400e+01

-3.000 -1.300e+01 -1.200e+01 -1.400e+01

-2.000 -3.000e+00 -2.300e+00 -3.700e+00

-1.900 -2.100e+00 -1.500e+00 -2.800e+00

-1.800 -1.300e+00 -8.600e-01 -1.900e+00

-1.700 -6.800e-01 -4.000e-01 -1.100e+00

-1.600 -2.800e-01 -1.800e-01 -5.100e-01

-1.500 -1.200e-01 -9.800e-02 -1.800e-01

-1.400 -7.500e-02 -7.100e-02 -8.300e-02

-1.300 -5.750e-02 -5.700e-02 -5.900e-02

-1.200 -4.600e-02 -4.650e-02 -4.550e-02

-1.100 -3.550e-02 -3.700e-02 -3.450e-02

-1.000 -2.650e-02 -2.850e-02 -2.500e-02

-0.900 -1.850e-02 -2.100e-02 -1.650e-02

-0.800 -1.200e-02 -1.400e-02 -9.750e-03

-0.700 -6.700e-03 -8.800e-03 -4.700e-03

-0.600 -3.000e-03 -4.650e-03 -1.600e-03

-0.500 -9.450e-04 -1.950e-03 -3.650e-04

-0.400 -5.700e-05 -2.700e-04 -5.550e-06

-0.300 -1.200e-06 -1.200e-05 -5.500e-08

-0.200 -3.000e-08 -5.000e-07 0.000e+00

-0.100 0.000e+00 0.000e+00 0.000e+00

0.000 0.000e+00 0.000e+00 0.000e+00

5.000 0.000e+00 0.000e+00 0.000e+00

|

[POWER Pulse Table] | POWER Clamp offset table

|

| Time V(typ) V(min) V(max)

|

0 0 0 0

1e-9 0 0 0

2e-9 -0.9 -1.0 -0.8

10e-9 -0.9 -1.0 -0.8

11e-9 0 0 0

|

[POWER Clamp] | Table to be offset

|

| Voltage I(typ) I(min) I(max)

|

-5.000 1.150e+01 1.100e+01 1.150e+01

-4.000 7.800e+00 7.500e+00 8.150e+00

-3.000 4.350e+00 4.100e+00 4.700e+00

-2.000 1.100e+00 8.750e-01 1.300e+00

-1.900 8.000e-01 6.050e-01 1.000e+00

-1.800 5.300e-01 3.700e-01 7.250e-01

-1.700 2.900e-01 1.800e-01 4.500e-01

-1.600 1.200e-01 6.850e-02 2.200e-01

-1.500 3.650e-02 2.400e-02 6.900e-02

-1.400 1.200e-02 1.100e-02 1.600e-02

-1.300 6.300e-03 6.650e-03 6.100e-03

-1.200 4.200e-03 4.750e-03 3.650e-03

-1.100 2.900e-03 3.500e-03 2.350e-03

-1.000 1.900e-03 2.450e-03 1.400e-03

-0.900 1.150e-03 1.600e-03 7.100e-04

-0.800 5.500e-04 9.150e-04 2.600e-04

-0.700 1.200e-04 4.400e-04 5.600e-05

-0.600 5.400e-05 1.550e-04 1.200e-05

-0.500 1.350e-05 5.400e-05 1.300e-06

-0.400 8.650e-07 7.450e-06 4.950e-08

-0.300 6.250e-08 7.550e-07 0.000e+00

-0.200 0.000e+00 8.400e-08 0.000e+00

-0.100 0.000e+00 0.000e-08 0.000e+00

0.000 0.000e+00 0.000e+00 0.000e+00

|

Bus Hold:

When the Submodel\_type subparameter under the [Submodel] keyword is set to Bus\_hold, the added model describes the bus hold functionality. However, while described in terms of bus hold functionality, active terminators can also be modeled.

Existing keywords and subparameters are used to describe bus hold models. The [Pullup] and [Pulldown] tables both are used to define an internal buffer that is triggered to switch to its opposite state. This switching transition is specified by a [Ramp] keyword or by the [Rising Waveform] and [Falling Waveform] keywords. The usage rules for these keywords are the same as under the [Model] keyword. In particular, at least either the [Pullup] or [Pulldown] keyword is required. Also, the [Ramp] keyword is required, even if the [Rising Waveform] and [Falling Waveform] tables exist. However, the voltage ranges and reference voltages are inherited from the top-level model.

For bus hold submodels, the [Submodel Spec] keyword, V\_trigger\_r, and V\_trigger\_f are required. The Off\_delay subparameter is optional, and can only be used if the submodel consists of a pullup or a pulldown structure only, and not both. Devices which have both pullup and pulldown structures controlled in this fashion can be modeled using two submodels, one for each half of the circuit.

The transition is triggered by action at the die using the [Submodel Spec] V\_trigger\_r and V\_trigger\_f subparameters as described next. In all subsequent discussions, “low” means the pulldown structure is on or active, and the pullup structure is off or inactive if either or both exist. The opposite settings are referred to as “high”.

If the starting voltage is below V\_trigger\_f, then the bus hold model is set to the low state causing additional pulldown current. If the starting voltage is above V\_trigger\_r, the bus hold model is set to the high state for additional pullup current.

Under some unusual cases, the above conditions can be both met or not met at all. To resolve this, the EDA tool should compute the starting voltage with the bus hold model set to low. If the starting voltage is equal to or less than the average of V\_trigger\_r and V\_trigger\_f, keep the bus hold model in the low state. Otherwise, set the bus hold model to the high state.

When the input passes through V\_trigger\_f during a high-to-low transition at the die, the bus hold output switches to the low state. Similarly, when the input passes though V\_trigger\_r during a low-to-high transition at the die, the bus hold output switches to the high state.

If the bus hold submodel has a pullup structure only, V\_trigger\_r provides the time when its pullup is turned on and V\_trigger\_f or Off\_delay provides the time when it is turned off, whichever occurs first. Similarly, if the submodel has a pulldown structure only, V\_trigger\_f provides the time when its pulldown is turned on and V\_trigger\_r or Off\_delay provides the time when it is turned off, whichever occurs first. The required V\_trigger\_r and V\_trigger\_f voltage entries can be set to values outside of the input signal range if the pullup or pulldown structures are to be held on until the Off\_delay turns them off.

The starting mode for each of the submodels which include the Off\_delay subparameter of the [Submodel Spec] keyword is the off state. Also, while two submodels provide the desired operation, either of the submodels may exist without the other to simulate turning on and off only a pullup or a pulldown current.

Table 4 through Table 7 summarizes the bus hold initializations and switching transitions:

Table – Bus Hold without Off\_Delay – Initialization

|  |  |
| --- | --- |
| **Initial Vdie Value** | **Initial Bus Hold Submodel State** |
| <= V\_trigger\_r & < V\_trigger\_f | low |
| => V\_trigger\_f & > V\_trigger\_r | high |
| *Recommendations if neither or both conditions above are satisfied* | |
| <= (V\_trigger\_f + V\_trigger\_r)/2 | low |
| > (V\_trigger\_f + V\_trigger\_r)/2 | high |

Table – Bus Hold without Off\_Delay - Transitions

|  |  |  |
| --- | --- | --- |
| **Prior Bus Hold Submodel State** | **Vdie transition through V\_trigger\_r/f** | **Bus Hold Transition** |
| Low | V\_trigger\_r | low-to-high |
| Low | V\_trigger\_f | no change |
| High | V\_trigger\_r | no change |
| High | V\_trigger\_f | high-to-low |

Table – Bus Hold with Off\_Delay (Requires Either [Pullup] or [Pulldown] Only) - Initialization

|  |  |
| --- | --- |
| **[Pullup] or [Pulldown] Table** | **Initial Bus Hold Submodel State (Off Mode)** |
| [Pullup] | low |
| [Pulldown] | high |

Table – Bus Hold with Off\_Delay (Requires Either [Pullup] or [Pulldown] Only) - Transitions

| **Prior Bus Hold Submodel State** | **Vdie transition through V\_trigger\_r/f** | **Bus Hold Transition** | **Off\_delay Transition** |
| --- | --- | --- | --- |
| Low | V\_trigger\_r | low-to-high | high-to-low |
| Low | V\_trigger\_f | no change | no change |
| High | V\_trigger\_r | no change | no change |
| High | V\_trigger\_f | high-to-low | low-to-high |
| Note: if Vdie passes again through the V\_trigger\_r/f thresholds before the Off\_delay time is reached, the bus hold state follows the change documented in the first table, overriding the Off\_delay transition. | | | |

No additional keywords are needed for this functionality.

*Examples:*

| Complete Bus Hold Model Example:

|

[Submodel] Bus\_hold\_1

Submodel\_type Bus\_hold

|

[Submodel Spec]

| Subparameter typ min max

|

V\_trigger\_f 1.3 1.2 1.4 | Falling edge trigger

V\_trigger\_r 3.1 2.6 4.6 | Rising edge trigger

|

| typ min max

| [Voltage Range] 5.0 4.5 5.5

| Note, the actual voltage range and reference voltages are inherited from

| the top-level model.

|

[Pulldown]

|

-5V -100uA -80uA -120uA

-1V -30uA -25uA -40uA

0V 0 0 0

1V 30uA 25uA 40uA

3V 50uA 45uA 50uA

5V 100uA 80uA 120uA

10v 120uA 90uA 150uA

|

[Pullup]

|

-5V 100uA 80uA 120uA

-1V 30uA 25uA 40uA

0V 0 0 0

1V -30uA -25uA -40uA

3V -50uA -45uA -50uA

5V -100uA -80uA -120uA

10v -120uA -90uA -150uA

|

|-----------------------------------------------------------------------------

|

[Ramp]

| typ min max

dV/dt\_r 2.0/0.50n 2.0/0.75n 2.0/0.35n

dV/dt\_f 2.0/0.50n 2.0/0.75n 2.0/0.35n

R\_load = 500

|

|-----------------------------------------------------------------------------

| Complete Pulldown Timed Latch Example:

|

[Submodel] Timed\_pulldown\_latch

Submodel\_type Bus\_hold

|

[Submodel Spec]

| Subparameter typ min max

|

V\_trigger\_r 3.1 2.6 4.6 | Rising edge trigger

| Values could be set out

| of range to disable the

| trigger

V\_trigger\_f 1.3 1.2 1.4 | Falling edge trigger

Off\_delay 3n 2n 5n | Delay to turn off the

| pulldown table

|

| Note that if the input signal goes above the V\_trigger\_r value, the

| pulldown structure will turn off even if the timer didn't expire yet.

|

| typ min max

| [Voltage Range] 5.0 4.5 5.5

| Note, the actual voltage range and reference voltages are inherited from

| the top-level model.

|

[Pulldown]

|

-5V -100uA -80uA -120uA

-1V -30uA -25uA -40uA

0V 0 0 0

1V 30uA 25uA 40uA

3V 50uA 45uA 50uA

5V 100uA 80uA 120uA

10v 120uA 90uA 150uA

|

| [Pullup] table is omitted to signal Open\_drain functionality.

|

|-----------------------------------------------------------------------------

|

[Ramp]

| typ min max

dV/dt\_r 2.0/0.50n 2.0/0.75n 2.0/0.35n

dV/dt\_f 2.0/0.50n 2.0/0.75n 2.0/0.35n

R\_load = 500

|

|=============================================================================

|

Fall Back:

When the Submodel\_type subparameter under the [Submodel] keyword is set to Fall\_back, the added model describes the fall back functionality. This submodel can be used to model drivers that reduce their strengths and increase their output impedances during their transitions. The fall back submodel is specified in a restrictive manner consistent with its intended use with a driver model operating only in Driving mode. In a Non-Driving mode, no action is specified. For example, a fall back submodel added to an Input or Terminator model would be inactive.

Existing keywords and subparameters are used to describe fall back models. However, only one [Pullup] or [Pulldown] table, but not both, is allowed. The switching transition is specified by a [Ramp] keyword or by the [Rising Waveform] and [Falling Waveform] keywords. The [Ramp] keyword is required, even if the [Rising Waveform] and [Falling Waveform] tables exist. However, the voltage ranges and reference voltages are inherited from the top-level model.

For fall back submodels, the [Submodel Spec] keyword, V\_trigger\_r, and V\_trigger\_f are required. Unlike the bus hold model, the Off\_delay subparameter is not permitted. Devices which have both pullup and pulldown structures can be modeled using two submodels, one for the rising cycle and one for the falling cycle.

In all following discussion, “low” means the pulldown structure is on or active, and the pullup structure is off or inactive. The opposite settings are referred to as “high”.

The transition is triggered by action at the die using the [Submodel Spec] V\_trigger\_r and V\_trigger\_f subparameters. The initialization and transitions are shown in Table 8 through Table 10.

Table – Fall Back, Initial State

|  |  |
| --- | --- |
| **[Pullup] or [Pulldown] Table** | **Initial Fall Back Submodel State (Off Mode)** |
| [Pullup] | Low |
| [Pulldown] | High |

Table 9 – Fall Back, Driver Rising Cycle

|  |  |  |  |
| --- | --- | --- | --- |
| **Prior State** | **Vdie** | **Rising Edge Transition** | **Vdie > V\_trigger\_r Transition** |
| Low | <= V\_trigger\_r | low-to-high | high-to-low |
| > V\_trigger\_r | stays low | stays low |
| High | <= V\_trigger\_r | stays high | high-to-low |
| > V\_trigger\_r | stays high | stays high |

Table – Fall Back, Driver Falling Cycle

| **Prior State** | **Vdie** | **Falling Edge Transition** | **Vdie < V\_trigger\_f Transition** |
| --- | --- | --- | --- |
| High | => V\_trigger\_f | high-to-low | low-to-high |
| < V\_trigger\_f | stays high | stays high |
| Low | => V\_trigger\_f | stays low | low-to-high |
| < V\_trigger\_f | stays low | stays low |

One application is to configure the submodel with only a pullup structure. At the beginning of the rising edge cycle, the pullup is turned on to the high state. When the die voltage passes V\_trigger\_r, the pullup structure is turned off. Because only the pullup structure is used, the off state is low corresponding to a high-Z state. During the falling transition, the pullup remains in the high-Z state if the V\_trigger\_f is set out of range to avoid setting the submodel to the high state. So a temporary boost in drive occurs only during the first part of the rising cycle.

A similar submodel consisting of only a pulldown structure could be constructed to provide added drive strength only at the beginning of the falling cycle. The complete IBIS model would have both submodels to give added drive strength for both the start of the rising and the start of the falling cycles.

No additional keywords are needed for this functionality.

*Examples:*

| Complete Dynamic Output Model Example Using Two Submodels:

|

[Submodel] Dynamic\_Output\_r

Submodel\_type Fall\_back

|

[Submodel Spec]

| Subparameter typ min max

|

V\_trigger\_f -10.0 -10.0 -10.0 | Falling edge trigger

| set out of range to

| disable trigger

V\_trigger\_r 3.1 2.6 4.6 | Rising edge trigger

|

| typ min max

| [Voltage Range] 5.0 4.5 5.5

| Note, the actual voltage range and reference voltages are inherited from

| the top-level model.

|

[Pullup]

|

-5V 100mA 80mA 120mA

0V 0 0 0

10v -200mA -160mA -240mA

|

| [Pulldown] table is omitted to signify Open\_source functionality.

|

|-----------------------------------------------------------------------------

|

[Ramp]

| typ min max

dV/dt\_r 1.5/0.50n 1.43/0.75n 1.58/0.35n

dV/dt\_f 1.5/0.50n 1.43/0.75n 1.58/0.35n

R\_load = 50

|

|-----------------------------------------------------------------------------

[Submodel] Dynamic\_Output\_f

Submodel\_type Fall\_back

|

[Submodel Spec]

| Subparameter typ min max

|

V\_trigger\_r 10.0 10.0 10.0 | Rising edge trigger

| set out of range to

| disable trigger

V\_trigger\_f 1.3 1.2 1.4 | Falling edge trigger

|

| typ min max

| [Voltage Range] 5.0 4.5 5.5

| Note, the actual voltage range and reference voltages are inherited from

| the top-level model.

|

[Pulldown]

|

-5V -100mA -80mA -120mA

0V 0 0 0

10v 200mA 160mA 240mA

|

| [Pullup] table is omitted to signify Open\_drain functionality.

|

|-----------------------------------------------------------------------------

|

[Ramp]

| typ min max

dV/dt\_r 1.5/0.50n 1.43/0.75n 1.58/0.35n

dV/dt\_f 1.5/0.50n 1.43/0.75n 1.58/0.35n

R\_load = 50

|

1. Multi-Lingual Model Extensions

INTRODUCTION:

The SPICE, IBIS-ISS, VHDL-AMS and Verilog-AMS languages are supported by IBIS. This chapter describes how models written in these languages can be referenced and used by .ibs files.

Table 11 shows the keywords used by the language extensions within the IBIS framework.

Table – Language Extension Keywords

|  |  |
| --- | --- |
| **Keyword** | **Description** |
| [External Circuit]  [End External Circuit] | References enhanced descriptions of structures on the die, including digital and/or analog, active and/or passive circuits |
| [External Model]  [End External Model] | Same as [External Circuit], except limited to the connection format and usage of the [Model] keyword, with one additional feature added: support for true differential buffers |
| [Node Declarations]  [End Node Declarations] | Lists on-die connection points related to the [Circuit Call] keyword |
| [Circuit Call]  [End Circuit Call] | Instantiates [External Circuit]s and connects them to each other and/or die pads |

The placement of these keywords within the hierarchy of IBIS is shown below:

├── **[Component]**

│ │

│ ├── **[Node Declarations]**

│ │ └── **[End Node Declarations]**

│ │

│ ├── **[Circuit Call]**

│ │ └── **[End Circuit Call]**

│ │

│

├── **[Model]**

│ │

│ ├── **[External Model]**

│ │ └── **[End External Model]**

│

├── **[External Circuit]**

│ └── **[End External Circuit]**

Languages Supported:

.ibs files can reference other files which are written using the SPICE, IBIS-ISS, VHDL-AMS, or Verilog-AMS languages. In this document, these languages are defined as follows:

“SPICE” refers to SPICE 3, Version 3F5 developed by the University of California at Berkeley, California. Many vendor-specific EDA tools are compatible with most or all of this version.

"IBIS-ISS" refers to the "IBIS Interconnect SPICE Subcircuits Specification (IBIS-ISS)", developed by the members of the IBIS Open Forum.

“VHDL-AMS” refers to “IEEE Standard VHDL Analog and Mixed-Signal Extensions”, approved March 18, 1999 by the IEEE-SA Standards Board and designated IEEE Std. 1076.1-1999, or later.

“Verilog-AMS” refers to the Analog and Mixed-Signal Extensions to Verilog-HDL as documented in the Verilog-AMS Language Reference, Version 2.0, or later. This document is maintained by Accellera (formerly Open Verilog International), an independent organization. Verilog-AMS is a superset that includes Verilog-A and the Verilog Hardware Description Language IEEE 1364-2001, or later.

“VHDL-A(MS)” refers to the analog subset of VHDL-AMS described above.

“Verilog-A(MS)” refers to the analog subset of Verilog-AMS described above.

In addition, the “IEEE Standard Multivalue Logic System for VHDL Model Interoperability (Std\_logic\_1164)”, designated IEEE Std. 1164-1993 or later, is required to promote common digital data types for .ibs files referencing VHDL-AMS. Also, the Accellera Verilog-AMS Language Reference Manual Version 2.2 or later, is required to promote common digital data types for .ibs files referencing Verilog-AMS.

Note that, for the purposes of this section, keywords, subparameters and other data used without reference to the external languages just described are referred to collectively as “native” IBIS.

Overview:

The four keyword pairs discussed in this chapter can be separated into two groups based on their functionalities. The [External Model], [End External Model], [External Circuit], and [End External Circuit] keywords are used as pointers to the models described by one of the external languages. The [Node Declarations], [End Node Declarations], [Circuit Call], and [End Circuit Call] keywords are used to describe how [External Circuit]s are connected to each other and/or to the die pads.

The [External Model] and [External Circuit] keywords are very similar in that they both support the same external languages, and they can both be used to describe passive and/or active circuitry. The key difference between the two keywords is that [External Model] can only be placed under the [Model] keyword, while [External Circuit] can only be placed outside the [Model] keyword, as illustrated in the portion of the keyword hierarchy, shown above.

The intent behind [External Model] is to provide an upgrade path from native IBIS [Model]s to the external languages (one exception to this is the support for true differential buffers). Thus, the [External Model] keyword can be used to replace the usual I-V and V-T tables, C\_comp, C\_comp\_pullup, C\_comp\_pulldown, C\_comp\_power\_clamp, C\_comp\_gnd\_clamp subparameters, [Ramp], [Driver Schedule], [Submodel] keywords, etc. of a [Model] by any modeling technique that the external languages allow. For [External Model]s, the connectivity, test load and specification parameters (such as Vinh and Vinl) are preserved from the [Model] keyword and the simulator is expected to carry out the same type of connections and measurements as is usually done with the [Model] keyword. The only difference is that the model itself is described by an external language.

In the case of the [External Circuit], however, one can model a circuit having any number of ports (see definitions below). For example, the ports may include impedance or buffer strength selection controls in addition to the usual signal and supply connections. The connectivity of an [External Circuit] is defined by the [Node Declarations] and [Circuit Call] keywords. Currently, the test loads and measurement parameters for an [External Circuit] can only be defined inside the model description itself. The results of measurements can be reported to the user or tool via other means.

The [Circuit Call] keyword acts similarly to subcircuit calls in SPICE, instantiating the various [External Circuit]s and connecting them together. Please note that models described by the [External Model] keyword are connected according to the rules and assumptions of the [Model] keyword. [Circuit Call] is not necessary for these cases and must not be used.

Definitions:

For the purposes of this document, several general terms are defined below.

circuit - any arbitrary collection of active or passive electrical elements treated as a unit

node - any electrical connection point; also called die node (may be digital or analog; may be a connection internal to a circuit or between circuits)

pad - a special case of a node. A pad connects a buffer or other circuitry to a package; also called die pad.

port - access point in an [External Model] or [External Circuit] definition for digital or analog signals

pseudo-differential circuits - combination of two single-ended circuits which drive and/or receive complementary signals, but where no internal current relationship exists between them

true differential circuits - circuits where a current relationship exists between two outputs or inputs which drive or receive complementary signals

General Assumptions:

Ports under [Model]s:

The use of ports under native IBIS must be understood before the multi-lingual extensions can be correctly applied. The [Model] keyword assumes, but does not explicitly require, naming ports on circuits. These ports are automatically connected by IBIS-compliant tools without action by the user. For example, the [Voltage Reference] keyword implies the existence of power supply rails which are connected to the power supply ports of the circuit described by the [Model] keyword.

For multi-lingual modeling, ports must be explicitly named in the [External Model] or [External Circuit]; the ports are no longer assumed by EDA tools. To preserve compatibility with the assumptions of [Model], a list of pre-defined port names has been created where the ports are reserved with fixed functionality. These reserved ports are defined in Table 12.

Table – Port Names in Multi-Lingual Modeling

| **Port** | **Name** | **Description** |
| --- | --- | --- |
| 1 | D\_drive | Digital input to a model unit |
| 2 | D\_enable | Digital enable for a model unit |
| 3 | D\_receive | Digital receive port of a model unit, based on data on A\_signal (and/or A\_signal\_pos and A\_signal\_neg) |
| 4 | A\_puref | Voltage reference port for pullup structure |
| 5 | A\_pcref | Voltage reference port for power clamp structure |
| 6 | A\_pdref | Voltage reference port for pulldown structure |
| 7 | A\_gcref | Voltage reference port for ground clamp structure |
| 8 | A\_signal | I/O signal port for a model unit |
| 9 | A\_extref | External reference voltage port |
| 10 | D\_switch | Digital input for control of a series switch model |
| 11 | A\_gnd | Global reference voltage port |
| 12 | A\_pos | Non-inverting port for series or series switch models |
| 13 | A\_neg | Inverting port for series or series switch models |
| 14 | A\_signal\_pos | Non-inverting port of a differential model |
| 15 | A\_signal\_neg | Inverting port of a differential model |

The first letter of the port name designates it as either digital (“D”) or analog (“A”). Reserved ports 1 through 13 are assumed or implied under the native IBIS [Model] keyword. Again, for multi-lingual models, these ports must be explicitly assigned by the user in the model if their functions are to be used. A\_gnd is a universal reference node, similar to SPICE ideal node “0.” Ports 14 and 15 are only available under [External Model] for support of true differential buffers.

Under the [Model] description, power and ground reference ports are created and connected by IBIS-compliant tools as defined by the [Power Clamp Reference], [GND Clamp Reference], [Pullup Reference], [Pulldown Reference] and/or [Voltage Range] keywords. The A\_signal port is connected to the die pad, to drive or receive an analog signal.

Ports under [External Model]s:

The [External Model] keyword may only appear under the [Model] keyword and it may only use the same ports as assumed with the native IBIS [Model] keyword. However, [External Model] requires that reserved ports be explicitly declared in the referenced language(s); tools will continue to assume the connections to these ports.

For [External Model], reserved analog ports are usually assumed to be die pads. These ports would be connected to the component pins through [Package Model]s or [Pin] parasitics. Digital ports under [External Model] would connect to other internal digital circuitry.

Two standard [Model] structures—an I/O buffer and a Series Switch—are shown, with their associated port names, in Figure 19 and Figure 20.



1. - Port Names for I/O Buffer



1. - Port Names for Series Switch

Ports under [External Circuit]s:

The [External Circuit] keyword allows the user to define any number of ports and port functions on a circuit. The [Circuit Call] keyword instantiates [External Circuit]s and connects their ports to specific die nodes (this can include pads). In this way, the ports of an [External Circuit] declaration become specific component die nodes. Note that, if reserved digital port names are used with an [External Circuit], those ports will be connected automatically as defined in the port list above (under [External Circuit], reserved analog port names do not retain particular meanings).

Figure 21 illustrates the use of [External Circuit]. Buffer A is an instance of [External Circuit] “X”. Similarly, Buffer B is an instance of [External Circuit] “Z”. These instances are created through [Circuit Call]s. [External Circuit] “Y” defines an on-die interconnect circuit. Nodes “a” through “e” and nodes “f” through “j” are specific instances of the ports defined for [External Circuit]s “X” and “Z”. These ports become the internal nodes of the die and must be explicitly declared with the [Node Declarations] keyword. The “On-die Interconnect” [Circuit Call] creates an instance of the [External Circuit] “Y” and connects the instance with the appropriate power, signal, and ground die pads. The “A” and “B” [Circuit Call]s connect the individual ports of each buffer instance to the “On-die Interconnect” [Circuit Call].

Note that the “Analog Buffer Control” signal is connected directly to the pad for pin 3. This connection is also made through an entry under the [Circuit Call] keyword.



1. - Example Showing [External Circuit] Ports

The [Model], [External Model] and [External Circuit] keywords (with [Circuit Call]s and [Node Declarations] as appropriate) may be combined together in the same .ibs file or even within the same [Component] description.

Port types and states:

The intent of native IBIS is to model the circuit block between the region where analog signals are of interest, and the digital logic domain internal to the component. For the purposes of this discussion, the IBIS circuit block is called a “model unit” in Figure 22 and Figure 23 and the document text below.

The multi-lingual modeling extensions maintain and expand this approach, assuming that both digital signals and/or analog signals can move to and from the model unit. All VHDL-AMS and Verilog-AMS models, therefore, must have digital ports and analog ports. In certain cases, digital ports may not be required, as in the case of interconnects; see [External Circuit] below. Routines to convert signals from one format to the other are the responsibility of the model author.

Digital ports under AMS languages must follow certain constraints on type and state. In VHDL-AMS models, analog ports must have type “electrical”. Digital ports must have type “std\_logic” as defined in IEEE Standard Multivalue Logic System for VHDL Model Interoperability (Std\_logic\_1164), or later. In Verilog-AMS models, analog ports must be of discipline “electrical” or a subdiscipline thereof. Digital ports must be of discipline “logic” as defined in the Accellera Verilog-AMS Language Reference Manual Version 2.2, or later and be constrained to states as defined in IEEE Std. 1164-1993, or later.

The digital ports delivering signals to the AMS model, D\_drive, D\_enable, and D\_switch, must be limited to the ‘1’ or ‘0’ states for VHDL-AMS, or, equivalently, to the 1 or 0 states for Verilog-AMS. The D\_receive digital port may only have the ‘1’, ‘0’, or ‘X’ states in VHDL-AMS, or, equivalently, the 1, 0, or X states in Verilog-AMS. All digital ports other than the foregoing predefined ports may use any of the logic states allowed by IEEE Std. 1164-1993, or later.

SPICE, IBIS-ISS, VHDL-A(MS), Verilog-A(MS) versus VHDL-AMS and VERILOG-AMS:

SPICE, IBIS-ISS, VHDL-A(MS), Verilog-A(MS) cannot process digital signals. All SPICE, IBIS-ISS, VHDL-A(MS), Verilog-A(MS) input and output signals must be in analog format. Consequently, IBIS multi-lingual models using SPICE, IBIS-ISS, VHDL-A(MS) or Verilog-A(MS) require analog-to-digital (A\_to\_D) and/or digital-to-analog (D\_to\_A) converters to be provided by the EDA tool. The converter subparameters are declared by the user, as part of the [External Model] or [External Circuit] syntax, with user-defined names for the ports which connect the converters to the analog ports of the SPICE, IBIS-ISS, VHDL-A(MS), or Verilog-A(MS) model. The details behind these declarations are explained in the keyword definitions below.

The electrical output characteristics of D\_to\_A converters are equivalent to ideal voltage sources having a zero ohm output impedance, and the electrical input characteristics of A\_to\_D converters are equivalent to ideal voltage probes, having an infinite input impedance.

To summarize, Verilog-AMS and VHDL-AMS contain all the capability needed to ensure that a model unit consists of only digital ports and/or analog ports. SPICE, IBIS-ISS, VHDL-A(MS) and Verilog-A(MS), however, need extra data conversion, provided by the EDA tool, to ensure that any digital signals can be correctly processed.



1. - AMS Model Unit, Using an I/O Buffer as an Example



1. - An Analog-Only Model Unit, Using an I/O Buffer as an Example

KEYWORD DEFINITIONS:

*Keywords:* [External Model], [End External Model]

*Required:* No

*Description:* Used to reference an external file written in one of the supported languages containing an arbitrary circuit definition, but having ports that are compatible with the [Model] keyword, or having ports that are compatible with the [Model] keyword plus an additional signal port for true differential buffers.

*Sub-Params:* Language, Corner, Parameters, Converter\_Parameters, Ports, D\_to\_A, A\_to\_D

*Usage Rules:* The [External Model] keyword must be positioned within a [Model] section and it may only appear once for each [Model] keyword in a .ibs file. It is not permitted under the [Submodel] keyword.

[Circuit Call] may not be used to connect an [External Model].

A native IBIS [Model]’s data may be incomplete if the [Model] correctly references an [External Model]. Any native IBIS keywords that are used in such a case must contain syntactically correct data and subparameters according to native IBIS rules. In all cases, [Model]s which reference [External Model]s must include the following keywords and subparameters:

Model\_type

Vinh, Vinl (as appropriate to Model\_type)

[Voltage Range] and/or [Pullup Reference], [Pulldown Reference], [POWER Clamp Reference], [GND Clamp Reference], [External Reference]

[Ramp]

In models without the [External Model] keyword, data for [Ramp] should be measured using a load that conforms to the recommendations in Section 9, "NOTES ON DATA DERIVATION METHOD". However, when used within the scope of [External Model], the [Ramp] keyword is intended strictly to provide EDA tools with a quick first-order estimate of driver switching characteristics. When using [External Model], therefore, data for [Ramp] may be measured using a different load, if it results in data that better represent the driver’s behavior in standard operation. Also in this case, the R\_load subparameter is optional, regardless of its value, and will be ignored by EDA simulators. For example, the 20% to 80% voltage and time intervals for a differential buffer may be measured using the typical differential operating load appropriate to that buffer’s technology. Note that voltage and time intervals must always be recorded explicitly rather than as a reduced fraction, in accordance with [Ramp] usage rules.

The following keywords and subparameters may be omitted, regardless of Model\_type, from a [Model] using [External Model]:

C\_comp, C\_comp\_pullup, C\_comp\_pulldown, C\_comp\_power\_clamp, C\_comp\_gnd\_clamp

[Pulldown], [Pullup], [POWER Clamp], [GND Clamp]

Subparameter Definitions:

Language:

Accepts “SPICE”, “IBIS-ISS”, “VHDL-AMS”, “Verilog-AMS”, “VHDL-A(MS)” or “Verilog-A(MS)” as arguments. The Language subparameter is required and must appear only once.

Corner:

Three entries follow the Corner subparameter on each line:

corner\_name file\_name circuit\_name

The corner\_name entry is “Typ”, “Min”, or “Max”. The file\_name entry points to the referenced file in the same directory as the .ibs file.

Up to three Corner lines are permitted. A “Typ” line is required. If “Min” and/or “Max” data is missing, the tool may use “Typ” data in its place. However, the tool should notify the user of this action.

Models instantiated by corner\_name "Min" describe slow, weak performance, and models instantiated by corner\_name "Max" describe fast, strong performance.

The circuit\_name entry provides the name of the circuit to be simulated within the referenced file. For SPICE and IBIS-ISS files, this is normally a “.subckt” name. For VHDL-AMS files, this is normally an “entity(architecture)” name pair. For Verilog-AMS files, this is normally a “module” name.

No character limits, case-sensitivity limits or extension conventions are required or enforced for file\_name and circuit\_name entries. However, the total number of characters in each Corner line must comply with the rules in Section 3. Furthermore, lower-case file\_name entries are recommended to avoid possible conflicts with file naming conventions under different operating systems. Case differences between otherwise identical file\_name entries or circuit\_name entries should be avoided. External languages may not support case-sensitive distinctions.

Parameters:

Lists names of parameters that can be passed into an external model file. Each Parameters entry must match a name or keyword in the external file or language. The list of Parameters may span several lines by using the word Parameters at the start of each line. The Parameters subparameter is optional, and the external model must operate with default settings without any Parameters assignments.

Parameter passing is not supported in SPICE. VHDL-AMS and VHDL-A(MS) parameters are supported using “generic” names, and Verilog-AMS and Verilog-A(MS) parameters are supported using “parameter” names. IBIS-ISS parameters are supported for all IBIS-ISS parameters which are defined on the subcircuit definition line.

Parameters are locally scoped under each [External Model] keyword, i.e., the same parameter under two different [External Model] will have independent values.

The parameter(s) listed under the Parameters subparameter may optionally be followed by an equal sign and a numeric, Boolean or string literal or a reference to a parameter name which is located in a parameter tree. The reference must begin with a file name, followed by an open parentheses and a the tree root name, a new open parentheses for any branch names (including the Reserved\_Parameters or Model\_Specific branch names if present in the tree) and the parameter name, and a matching set of closing parentheses. The file reference may point to any file which contains one or more parameter trees. The files referenced must be located in the same directory as the .ibs file containing the reference. The file names of parameter files must follow the rules for file names given in Section 3, GENERAL SYNTAX RULES AND GUIDELINES. Parameter files may only contain parameter trees using the tree syntax described in IBIS in section 10A with the following exceptions and additions:

When the extension of the external parameter’s file name ends with “.ami”:

a) only Usage In or Usage Info are allowed for parameters which are to be passed into models instantiated by the [External Model] or the [External Circuit] keywords

When the extension of the external parameter’s file name does not end with “.ami”:

a) the parameter tree must not contain the Reserved\_Parameters branch but must contain the Model\_Specific branch

b) only Usage Info is allowed

Note that in the case when a parameter is located in an .ami file and it is of Usage In, the parameter value will be passed into the AMI executable model but this does not mean that the same parameter couldn’t be used by other model(s) which are instantiated through [External Model] or [External Circuit].

Multiple parameters may only be listed on a single line if no value assignments are made. When the Parameters line includes a parameter value assignment, each parameter must be listed on a new line. String literals must be enclosed in double quotes.

The EDA tool may provide additional means to the user to assign values to Parameters. This may include the option to override the values provided in the .ibs file, to allow the user to make selections for multi-valued parameters in the parameter tree, or to provide values for uninitialized Parameters.

Converter\_Parameters:

This optional subparameter lists and initializes parameter names to be used as arguments for the A\_to\_D and/or D\_to\_A converter(s) of the [External Model] keyword under which it appears. The list of Converter\_Parameters may span several lines by using the word Converter\_Parameters at the start of each line. Any A\_to\_D or D\_to\_A argument which is entered as a parameter must be declared and initialized with the Converter\_Parameters subparameter.

Converter\_Parameters are locally scoped under each [External Model] keyword, i.e., the same converter parameter under two different [External Model]s will have independent values.

The Converter\_Parameters subparameter must contain one parameter name per line, which must be followed by an equal sign and a constant numeric literal or a reference to a parameter name which is located in a parameter tree. The reference must begin with a file name, followed by an open parentheses and a the tree root name, a new open parentheses for any branch names (including the Reserved\_Parameters or Model\_Specific branch names if present in the tree) and the parameter name, and a matching set of closing parentheses. The file reference may point to any file which contains one or more parameter trees. The files referenced must be located in the same directory as the .ibs file containing the reference. The file names of parameter files must follow the rules for file names given in Section 3, GENERAL SYNTAX RULES AND GUIDELINES. Parameter files may only contain parameter trees using the tree syntax described in IBIS in section 10A with the following exceptions and additions:

When the extension of the external parameter’s file name ends with “.ami”:

a) only Usage In or Usage Info are allowed for parameters which are to be passed into models instantiated by the [External Model] or the [External Circuit] keywords

When the extension of the external parameter’s file name does not end with “.ami”:

a) the parameter tree must not contain the Reserved\_Parameters branch but must contain the Model\_Specific branch

b) only Usage Info is allowed

Note that in the case when a parameter is located in an .ami file and it is of Usage In, the parameter value will be passed into the AMI executable model but this does not mean that the same parameter couldn’t be used by other model(s) which are instantiated through [External Model] or [External Circuit].

The EDA tool may provide additional means to the user to make assignments to Converter\_Parameters. This may include the option to override the values provided in the .ibs file, or to allow the user to make selections for multi-valued parameters in the parameter tree.

Ports:

Ports are interfaces to the [External Model] which are available to the user and tool at the IBIS level. They are used to connect the [External Model] to die pads. The Ports parameter is used to identify the ports of the [External Model] to the simulation tool. The port assignment is by position and the port names do not have to match exactly the names inside the external file. The list of port names may span several lines if the word Ports is used at the start of each line.

Model units under [External Model] may only use reserved ports. The reserved, pre-defined port names are listed in the General Assumptions heading above. As noted earlier, digital and analog reserved port functions will be assumed by the tool and connections made accordingly. All the ports appropriate to the particular Model\_type subparameter entry must be explicitly listed (see below). Note that the user may connect SPICE, IBIS-ISS, Verilog-A(MS) and VHDL-A(MS) models to A\_to\_D and D\_to\_A converters using custom names for analog ports within the model unit, as long as the digital ports of the converters use the digital reserved port names.

The rules for pad connections with [External Model] are identical to those for [Model]. The [Pin Mapping] keyword may be used with [External Model]s but is not required. If used, the [External Model] specific voltage supply ports—A\_puref, A\_pdref, A\_gcref, A\_pcref, and A\_extref—are connected as defined under the [Pin Mapping] keyword. In all cases, the voltage levels connected on the reserved supply ports are defined by the [Power Clamp Reference], [GND Clamp Reference], [Pullup Reference], [Pulldown Reference], and/or [Voltage Range] keywords, as in the case of [Model].

Digital-to-Analog/Analog-to-Digital Conversions:

These subparameters define all digital-to-analog and analog-to-digital converters needed to properly connect digital signals with the analog ports of referenced external SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) models. These subparameters must be used when [External Model] references a file written in the SPICE, IBIS-ISS, Verilog-A(MS), or VHDL-A(MS) languages. They are not permitted with Verilog-AMS or VHDL-AMS external files.

D\_to\_A:

As assumed in [Model], some interface ports of [External Model] circuits expect digital input signals. As SPICE, IBIS-ISS, Verilog-A(MS), or VHDL-A(MS) models understand only analog signals, some conversion from digital to analog format is required. For example, input logical states such as “0” or “1”, implied in [Model], must be converted to actual input voltage stimuli, such as a voltage ramp, for SPICE simulation.

The D\_to\_A subparameter provides information for converting a digital stimulus, such as “0” or “1”, into an analog voltage ramp (a digital “X” input is ignored by D\_to\_A converters). Each digital port which carries data for conversion to analog format must have its own D\_to\_A line.

The D\_to\_A subparameter is followed by eight or optionally nine arguments:

d\_port port1 port2 vlow vhigh trise tfall corner\_name polarity

The d\_port entry holds the name of the digital port. This entry is used for the reserved port names D\_drive, D\_enable, and D\_switch. The port1 and port2 entries hold the SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) analog input port names across which voltages are specified. These entries are used for the user-defined port names, together with another port name, used as a reference.

Normally port1 accepts an input signal and port2 is the reference for port1. However, for an opposite polarity stimulus, port1 could be connected to a reference port and port2 could serve as the input. In some situations, such as in the case of a true differential buffer model, it might be desirable to provide two D\_to\_A converters, one to drive the Non-Inverting input and the other one to drive the Inverting input. In this case the D\_to\_A converters may be defined with the polarity argument, one with the value Non-Inverting and the other with the value Inverting.

The vlow and vhigh entries accept analog voltage values which must correspond to the digital off and on states, where the vhigh value must be greater than the vlow value. When polarity is Non-Inverting, vlow corresponds to the digital off state '0', vhigh corresponds to the digital on state '1', trise corresponds to the analog edge rate going from the digital off to on state, and tfall corresponds to the analog edge rate going from the digital on to off state. When polarity is Inverting, the analog behavior corresponds to the opposite digital states. For example, a 3.3 V ground-referenced buffer would list vlow as 0 V and vhigh as 3.3 V. For a Non-Inverting D\_to\_A converter, a rising edge in D\_drive would result in a transition from 0 V to 3.3 V, and for an Inverting D\_to\_A converter, a rising edge in D\_drive would result in a transition from 3.3 V to 0 V. The trise and tfall entries are times, must be positive, and define input ramp rise and fall times between 0 and 100 percent.

The vlow, vhigh, trise and tfall arguments may be defined by parameter names, which must be declared and initialized by one or more Converter\_Parameters subparameter.

The corner\_name entry holds the name of the external model corner being referenced, as listed under the Corner subparameter.

The last argument, polarity, is optional. If present, its value must be "Inverting" or "Non-Inverting". If the argument is not present, "Non-Inverting" is in effect. The polarity argument may only be used with D\_to\_A converters which are connected to the d\_port name D\_drive. If the polarity argument is used, two D\_to\_A converter lines are required, one defined as Non-Inverting and another defined as Inverting.

At least one D\_to\_A line must be present, corresponding to the “Typ” corner model, for each digital line to be converted. Additional D\_to\_A lines for other corners may be omitted. In this case, the typical corner D\_to\_A entries will apply to all model corners and the “Typ” corner\_name entry may be omitted if the polarity argument is not present. When the polarity argument is present, the corner\_name argument must also be present.

A\_to\_D:

The A\_to\_D subparameter is used to generate a digital state (“0”, “1”, or “X”) based on analog voltages generated by the SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) model or analog voltages present at the pad/pin. This allows an analog signal from the external SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) circuit or pad/pin to be read as a digital signal by the simulation tool.

The A\_to\_D subparameter is followed by six arguments:

d\_port port1 port2 vlow vhigh corner\_name

The d\_port entry lists the reserved port name D\_receive. As with D\_to\_A, the port1 entry would normally contain the reserved name A\_signal (see below) or a user-defined port name, while port2 may list any other analog reserved port name, used as a reference. The voltage measurements are taken in this example from the port1 entry with respect to the port2 entry. These ports must also be named by the Ports subparameter.

The vlow and vhigh entries list the low and high analog threshold voltage values. The reported digital state on D\_receive will be “0” if the measured voltage is lower than the vlow value, “1” if above the vhigh value, and “X” otherwise.

The vlow and vhigh arguments may be defined by parameter names, which must be declared and initialized by one or more Converter\_Parameters subparameter.

The corner\_name entry holds the name of the external model corner being referenced, as listed under the Corner subparameter.

At least one A\_to\_D line must be supplied corresponding to the “Typ” corner model. Other A\_to\_D lines for other corners may be omitted. In this case, the typical corner A\_to\_D entries will apply to all model corners.

IMPORTANT: measurements for receivers in IBIS are normally assumed to be conducted at the die pads/pins. In such cases, the electrical input model data comprises a “load” which affects the waveform seen at the pads. However, for models measure the analog input response at the die pads or inside the circuit (this does not preclude tools from reporting digital D\_receive and/or analog port responses in addition to at-pad A\_signal response). If at-pad measurements are desired, the A\_signal port would be named in the A\_to\_D line under port1. The A\_to\_D converter then effectively acts “in parallel” with the load of the circuit. If internal measurements are desired (e.g., if the user wishes to view the signal after processing by the receiver), the user-defined signal port would be named in the A\_to\_D line under port1. The A\_to\_D converter is effectively “in series” with the receiver model. The vhigh and vlow parameters should be adjusted as appropriate to the measurement point of interest.

Note that, while the port assignments and SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) model must be provided by the user, the D\_to\_A and A\_to\_D converters will be provided automatically by the tool (the converter parameters must still be declared by the user). There is no need for the user to develop external SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) code specifically for these functions.

A conceptual diagram of the port connections of a SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) [External Model] is shown in Figure 24. The example illustrates an I/O buffer. Note that the drawing implies that the D\_receive state changes in response to the analog signal my\_receive, not A\_signal:



1. - Example of an [External Model] I/O Buffer Using SPICE,  
   Verilog-A(MS), or VHDL-A(MS)

Pseudo-Differential Buffers:

Pseudo-differential buffers may be described using a pair of [External Model]s which may or may not be identical. Each of the analog I/O signal ports (usually A\_signal) is connected to a specific pad through the [Pin] list in the usual fashion, and the two ports are linked together as a differential pair through the [Diff Pin] keyword.

The reserved signal name A\_signal is required for the I/O signal ports of [External Model]s connected to pads used in a pseudo-differential configuration.

Users should note that, in pseudo-differential buffers, only one formal signal port is used to stimulate the two [External Model] digital inputs (D\_drive). One of these inputs will reflect the timing and polarity of the formal signal port named by the user, while the other input is inverted and (potentially) delayed with respect to the formal port as defined under the [Diff Pin] keyword. THIS SECOND PORT IS AUTOMATICALLY CREATED BY THE SIMULATION TOOL. Users do not have to create special structures to invert or delay the driven digital signal. Simulation tools will correctly implement the two input ports once the [Diff Pin] keyword has been detected in the .ibs file. This approach is identical to that used in native IBIS.

The D\_to\_A adapters used for SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) files can be set up to control ports on pseudo-differential buffers. If SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) is used as an external language, the [Diff Pin] vdiff subparameter overrides the contents of vlow and vhigh under A\_to\_D.

IMPORTANT: For pseudo-differential buffers under [External Model], the analog input response may only be measured at the die pads. The [Diff Pin] parameter is required, and controls both the polarity and the differential thresholds used to determine the D\_receive port response (the D\_receive port will follow the state of the non-inverting pin/pad as referenced to the inverting pin/pad). For SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) models, the A\_to\_D line must name the A\_signal port under either port1 or port2, as with a single-ended buffer. The A\_to\_D converter then effectively acts “in parallel” with the load of the buffer circuit. The vhigh and vlow parameters will be overridden by the [Diff Pin] vdiff declarations.

The port relationships are shown in Figure 25.



1. -Example SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) Implementation

Figure 26 illustrates the same concepts with a \*-AMS model. Note that the state of D\_receive is determined by the tool automatically by observing the A\_signal ports. The outputs of the actual receiver circuits in the \*-AMS models are not used for determining D\_receive.



1. - Example \*-AMS Implementation

Two additional differential timing test loads are available:

Rref\_diff, Cref\_diff

These subparameters are also available under the [Model Spec] keyword for typical, minimum, and maximum corners.

These timing test loads require both sides of the differential model to be operated. They can be used with the existing timing test loads Rref, Cref, and Vref. The existing timing test loads and Vmeas are used if Rref\_diff and Cref\_diff are NOT given.

True Differential Models:

True differential buffers may be described using [External Model]. In a true differential [External Model], the differential I/O ports which connect to die pads use the reserved names A\_signal\_pos and A\_signal\_neg, as shown in Figure 27.



1. - Port Names for True Differential I/O Buffer

IMPORTANT: All true differential models under [External Model] assume single-ended digital port connections (D\_drive, D\_enable, D\_receive).

The [Diff Pin] keyword is still required within the same [Component] definition when [External Model] describes a true differential buffer. The [Model] names or [Model Selector] names referenced by the pair of pins listed in an entry of the [Diff Pin] MUST be the same.

The D\_to\_A or A\_to\_D adapters used for SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) files may be set up to control or respond to true differential ports. An example is shown in Figure 28.



1. - Example SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) Implementation of a  
   True Differential Buffer

If at-pad or at-pin measurement using a SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) [External Model] is desired, the vlow and vhigh entries under the A\_to\_D subparameter must be consistent with the values of the [Diff Pin] vdiff subparameter entry (the vlow value must match -vdiff, and the vhigh value must match +vdiff). The logic states produced by the A\_to\_D conversion follow the same rules as for single-ended buffers, listed above. An example is shown at the end of this section.

IMPORTANT: For true-differential buffers under [External Model], the user can choose whether to measure the analog input response at the die pads or internal to the circuit (this does not preclude tools from reporting digital D\_receive and/or analog responses in addition to at-pad A\_signal response). If at-pad measurements for a SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) model are desired, the A\_signal\_pos port would be named in the A\_to\_D line under port1 and A\_signal\_neg under port2. The A\_to\_D converter then effectively acts “in parallel” with the load of the buffer circuit. If internal measurements are desired (e.g., if the user wishes to view the signal after processing by the input buffer), the user-defined analog signal port would be named in the A\_to\_D line under port1. The A\_to\_D converter is “in series” with the receiver buffer model. The vhigh and vlow parameters should be adjusted appropriate to the measurement point of interest, so long as they as they are consistent with the [Diff Pin] vdiff declarations.

Note that the thresholds refer to the state of the non-inverting signal, using the inverting signal as a reference. Therefore, the output signal is considered high when, for example, the non-inverting input is +200 mV above the inverting input. Similarly, the output signal is considered low when the same non-inverting input is -200 mV “above” the inverting input.

EDA tools will report the state of the D\_receive port for true differential \*-AMS [External Model]s according to the AMS code written by the model author; the use of [Diff Pin] does not affect the reporting of D\_receive in this case. EDA tools are free to additionally report the state of the I/O pads according to the [Diff Pin] vdiff subparameter.

For SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) and \*-AMS true differential [External Model]s, the EDA tool must not override or change the model author’s connection of the D\_receive port.

Four additional Model\_type arguments are available under the [Model] keyword. One of these must be used when an [External Model] describes a true differential model:

I/O\_diff, Output\_diff, 3-state\_diff, Input\_diff

Two additional differential timing test loads are available:

Rref\_diff, Cref\_diff

These subparameters are also available under the [Model Spec] keyword for the typical, minimum, and maximum corner cases.

These timing test loads require that both the inverting and non-inverting ports of the differential model refer to valid buffer model data (not terminations, supply rails, etc.). The differential test loads may also be combined with the single-ended timing test loads Rref, Cref, and Vref. Note that the single-ended timing test loads plus Vmeas are used if Rref\_diff and Cref\_diff are NOT supplied.

Series and Series Switch Models:

Native IBIS did not define the transition characteristics of digital switch controls. Switches were assumed to either be on or off during a simulation and I-V characteristics could be defined for either or both states. The [External Model] format allows users to control the state of a switch through the D\_switch port. As with other digital ports, the use of SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) in an [External Model] requires the user to declare D\_to\_A ports, to convert the D\_switch signal to an analog input to the SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) model (whether the port’s state may actually change during a simulation is determined by the EDA tool used).

Series and Series\_switch devices both are described under the [External Model] keyword using the reserved port names A\_pos and A\_neg. Note that the [Series Pin Mapping] keyword must be present and correctly used elsewhere in the file, in order to properly set the logic state of the switch. The A\_pos port is defined in the first entry of the [Series Pin Mapping] keyword, and the A\_neg port is defined in the pin2 entry. For series switches, the [Series Switch Groups] keyword is required.

Ports required for various Model\_types:

As [External Model] makes use of the [Model] keyword’s Model\_type subparameter, not all digital and analog reserved ports may be needed for all Model\_types. Table 13 and Table 14 below define which reserved port names are required for various Model\_types.

Table – Required Port Names for Single-ended Model\_type Assignments

|  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- |
| **Model\_type** | **D\_drive** | **D\_enable** | **D\_receive** | **A\_signal** | **D\_switch** | **A\_pos** | **A\_neg** |
| I/O\* | X | X | X | X |  |  |  |
| 3-state\* | X | X |  | X |  |  |  |
| Output\*, Open\* | X |  |  | X |  |  |  |
| Input |  |  | X | X |  |  |  |
| Terminator |  |  |  | X |  |  |  |
| Series |  |  |  |  |  | X | X |
| Series\_switch |  |  |  |  | X | X | X |

Table – Required Port Names for Differential Model\_type Assignments

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Model\_type** | **D\_drive** | **D\_enable** | **D\_receive** | **A\_signal\_pos** | **A\_signal\_neg** |
| I/O\_diff | X | X | X | X | X |
| 3-state\_diff | X | X |  | X | X |
| Output\_diff | X |  |  | X | X |
| Input\_diff |  |  | X | X | X |

*Examples:*

Example [External Model] using SPICE:

[Model] ExBufferSPICE

Model\_type I/O

Vinh = 2.0

Vinl = 0.8

|

| Other model subparameters are optional

|

| typ min max

[Voltage Range] 3.3 3.0 3.6

|

[Ramp]

dV/dt\_r 1.57/0.36n 1.44/0.57n 1.73/0.28n

dV/dt\_f 1.57/0.35n 1.46/0.44n 1.68/0.28n

|

[External Model]

Language SPICE

|

| Corner corner\_name file\_name circuit\_name (.subckt name)

Corner Typ buffer\_typ.spi buffer\_io\_typ

Corner Min buffer\_min.spi buffer\_io\_min

Corner Max buffer\_max.spi buffer\_io\_max

|

| Parameters - Not supported in SPICE

|

| Ports List of port names (in same order as in SPICE)

Ports A\_signal my\_drive my\_enable my\_receive my\_ref

Ports A\_puref A\_pdref A\_pcref A\_gcref A\_extref

|

| D\_to\_A d\_port port1 port2 vlow vhigh trise tfall corner\_name

D\_to\_A D\_drive my\_drive my\_ref 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_enable my\_enable A\_gcref 0.0 3.3 0.5n 0.3n Typ

|

| A\_to\_D d\_port port1 port2 vlow vhigh corner\_name

A\_to\_D D\_receive my\_receive my\_ref 0.8 2.0 Typ

|

| Note: A\_signal might also be used instead of a user-defined interface port

| for measurements taken at the die pads

|

[End External Model]

Example [External Model] using IBIS-ISS:

[Model] ExBufferISS

Model\_type I/O

Vinh = 2.0

Vinl = 0.8

|

| Other model subparameters are optional

|

| typ min max

[Voltage Range] 3.3 3.0 3.6

|

[Ramp]

dV/dt\_r 1.57/0.36n 1.44/0.57n 1.73/0.28n

dV/dt\_f 1.57/0.35n 1.46/0.44n 1.68/0.28n

|

[External Model]

Language IBIS-ISS

|

| Corner corner\_name file\_name circuit\_name (.subckt name)

Corner Typ buffer\_typ.spi buffer\_io\_typ

Corner Min buffer\_min.spi buffer\_io\_min

Corner Max buffer\_max.spi buffer\_io\_max

|

| List of parameters

Parameters sp\_file\_name = paramfile.par(TreeRootName(Model\_Specific(TstoneFile)))

Parameters C1\_value

Parameters R1\_value = paramfile.par(TreeRootName(Model\_Specific(R1)))

|

| List of converter parameters

Converter\_Parameters MyVlow = 0.0

Converter\_Parameters MyVHigh = 3.3

Converter\_Parameters MyVinl = paramfile.par(TreeRootName(Model\_Specific(Vinl)))

Converter\_Parameters MyVinh = paramfile.par(TreeRootName(Model\_Specific(Vinh)))

Converter\_Parameters MyTrise = paramfile.par(TreeRootName(Model\_Specific(Trf)))

Converter\_Parameters MyTfall = paramfile.par(TreeRootName(Model\_Specific(Trf)))

|

| Ports List of port names (in same order as in ISS)

Ports A\_signal my\_drive my\_enable my\_receive my\_ref

Ports A\_puref A\_pdref A\_pcref A\_gcref A\_extref

|

| D\_to\_A d\_port port1 port2 vlow vhigh trise tfall corner\_name

D\_to\_A D\_drive my\_drive my\_ref MyVlow MyVhigh MyTfall MyTrise Typ

D\_to\_A D\_enable my\_enable A\_gcref 0.0 3.3 0.5n 0.3n Typ

|

| A\_to\_D d\_port port1 port2 vlow vhigh corner\_name

A\_to\_D D\_receive my\_receive my\_ref MyVinl MyVinh Typ

|

| Note: A\_signal might also be used instead of a user-defined interface port

| for measurements taken at the die pads

|

[End External Model]

Example [External Model] using VHDL-AMS:

[Model] ExBufferVHDL

Model\_type I/O

Vinh = 2.0

Vinl = 0.8

|

| Other model subparameters are optional

|

| typ min max

[Voltage Range] 3.3 3.0 3.6

|

[Ramp]

dV/dt\_r 1.57/0.36n 1.44/0.57n 1.73/0.28n

dV/dt\_f 1.57/0.35n 1.46/0.44n 1.68/0.28n

|

[External Model]

Language VHDL-AMS

|

| Corner corner\_name file\_name entity(architecture)

Corner Typ buffer\_typ.vhd buffer(buffer\_io\_typ)

Corner Min buffer\_min.vhd buffer(buffer\_io\_min)

Corner Max buffer\_max.vhd buffer(buffer\_io\_max)

|

| Parameters List of parameters

Parameters delay rate

Parameters preemphasis

| Ports List of port names (in same order as in VHDL-AMS)

Ports A\_signal A\_puref A\_pdref A\_pcref A\_gcref

Ports D\_drive D\_enable D\_receive

|

[End External Model]

Example [External Model] using Verilog-AMS:

[Model] ExBufferVerilog

Model\_type I/O

Vinh = 2.0

Vinl = 0.8

|

| Other model subparameters are optional

|

| typ min max

[Voltage Range] 3.3 3.0 3.6

|

[Ramp]

dV/dt\_r 1.57/0.36n 1.44/0.57n 1.73/0.28n

dV/dt\_f 1.57/0.35n 1.46/0.44n 1.68/0.28n

|

[External Model]

Language Verilog-AMS

|

| Corner corner\_name file\_name circuit\_name (module)

Corner Typ buffer\_typ.v buffer\_io\_typ

Corner Min buffer\_min.v buffer\_io\_min

Corner Max buffer\_max.v buffer\_io\_max

|

| Parameters List of parameters

Parameters delay rate

Parameters preemphasis

|

| Ports List of port names (in same order as in Verilog-AMS)

Ports A\_signal A\_puref A\_pdref A\_pcref A\_gcref

Ports D\_drive D\_enable D\_receive

|

[End External Model]

Example [External Model] using VHDL-A(MS):

[Model] ExBufferVHDL\_analog

Model\_type I/O

Vinh = 2.0

Vinl = 0.8

|

| Other model subparameters are optional

|

| typ min max

[Voltage Range] 3.3 3.0 3.6

|

[Ramp]

dV/dt\_r 1.57/0.36n 1.44/0.57n 1.73/0.28n

dV/dt\_f 1.57/0.35n 1.46/0.44n 1.68/0.28n

|

[External Model]

Language VHDL-A(MS)

|

| Corner corner\_name file\_name circuit\_name entity(architecture)

Corner Typ buffer\_typ.vhd buffer(buffer\_io\_typ)

Corner Min buffer\_min.vhd buffer(buffer\_io\_min)

Corner Max buffer\_max.vhd buffer(buffer\_io\_max)

|

| Parameters List of parameters

Parameters delay rate

Parameters preemphasis

|

| Ports List of port names (in same order as in VHDL-A(MS))

Ports A\_signal my\_drive my\_enable my\_receive my\_ref

Ports A\_puref A\_pdref A\_pcref A\_gcref A\_extref

|

| D\_to\_A d\_port port1 port2 vlow vhigh trise tfall corner\_name

D\_to\_A D\_drive my\_drive my\_ref 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_enable my\_enable A\_gcref 0.0 3.3 0.5n 0.3n Typ

|

| A\_to\_D d\_port port1 port2 vlow vhigh corner\_name

A\_to\_D D\_receive my\_receive my\_ref 0.8 2.0 Typ

|

| Note: A\_signal might also be used instead of a user-defined interface port

| for measurements taken at the die pads

Example [External Model] using Verilog-A(MS):

[Model] ExBufferVerilog\_analog

Model\_type I/O

Vinh = 2.0

Vinl = 0.8

|

| Other model subparameters are optional

|

| typ min max

[Voltage Range] 3.3 3.0 3.6

|

[Ramp]

dV/dt\_r 1.57/0.36n 1.44/0.57n 1.73/0.28n

dV/dt\_f 1.57/0.35n 1.46/0.44n 1.68/0.28n

|

[External Model]

Language Verilog-A(MS)

|

| Corner corner\_name file\_name circuit\_name (module)

Corner Typ buffer\_typ.va buffer\_io\_typ

Corner Min buffer\_min.va buffer\_io\_min

Corner Max buffer\_max.va buffer\_io\_max

| Parameters List of parameters

Parameters delay rate

Parameters preemphasis

|

| Ports List of port names (in same order as in Verilog-A(MS))

Ports A\_signal my\_drive my\_enable my\_receive my\_ref

Ports A\_puref A\_pdref A\_pcref A\_gcref A\_extref

|

| D\_to\_A d\_port port1 port2 vlow vhigh trise tfall corner\_name

D\_to\_A D\_drive my\_drive my\_ref 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_enable my\_enable A\_gcref 0.0 3.3 0.5n 0.3n Typ

|

| A\_to\_D d\_port port1 port2 vlow vhigh corner\_name

A\_to\_D D\_receive my\_receive my\_ref 0.8 2.0 Typ

|

| Note: A\_signal might also be used instead of a user-defined interface port

| for measurements taken at the die pads

|

[End External Model]

Example of True Differential [External Model] using SPICE:

[Model] Ext\_SPICE\_Diff\_Buff

Model\_type I/O\_diff

Rref\_diff = 100

|

| Other model subparameters are optional

|

| typ min max

[Voltage Range] 3.3 3.0 3.6

|

[Ramp]

dV/dt\_r 1.57/0.36n 1.44/0.57n 1.73/0.28n

dV/dt\_f 1.57/0.35n 1.46/0.44n 1.68/0.28n

|

[External Model]

Language SPICE

|

| Corner corner\_name file\_name circuit\_name (.subckt name)

Corner Typ diffio.spi diff\_io\_typ

Corner Min diffio.spi diff\_io\_min

Corner Max diffio.spi diff\_io\_max

|

| Ports List of port names (in same order as in SPICE)

Ports A\_signal\_pos A\_signal\_neg my\_receive my\_drive my\_enable

Ports A\_puref A\_pdref A\_pcref A\_gcref A\_extref my\_ref A\_gnd

|

| D\_to\_A d\_port port1 port2 vlow vhigh trise tfall corner\_name

D\_to\_A D\_drive my\_drive my\_ref 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_drive my\_drive my\_ref 0.0 3.0 0.6n 0.3n Min

D\_to\_A D\_drive my\_drive my\_ref 0.0 3.6 0.4n 0.3n Max

D\_to\_A D\_enable my\_enable my\_ref 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_enable my\_enable my\_ref 0.0 3.0 0.6n 0.3n Min

D\_to\_A D\_enable my\_enable my\_ref 0.0 3.6 0.4n 0.3n Max

|

| A\_to\_D d\_port port1 port2 vlow vhigh corner\_name

A\_to\_D D\_receive A\_signal\_pos A\_signal\_neg -200m 200m Typ

A\_to\_D D\_receive A\_signal\_pos A\_signal\_neg -200m 200m Min

A\_to\_D D\_receive A\_signal\_pos A\_signal\_neg -200m 200m Max

|

[End External Model]

Example of True Differential [External Model] using IBIS-ISS:

[Model] Ext\_ISS\_Diff\_Buff

Model\_type I/O\_diff

Rref\_diff = 100

|

| Other model subparameters are optional

|

| typ min max

[Voltage Range] 3.3 3.0 3.6

|

[Ramp]

dV/dt\_r 1.57/0.36n 1.44/0.57n 1.73/0.28n

dV/dt\_f 1.57/0.35n 1.46/0.44n 1.68/0.28n

|

[External Model]

Language IBIS-ISS

|

| Corner corner\_name file\_name circuit\_name (.subckt name)

Corner Typ diffio.spi diff\_io\_typ

Corner Min diffio.spi diff\_io\_min

Corner Max diffio.spi diff\_io\_max

|

| List of parameters

Parameters sp\_file\_name

Parameters c\_diff r\_diff

|

|

| List of converter parameters

Converter\_Parameters MyVlow = 0.0

Converter\_Parameters MyVHigh = 3.3

|

| Ports List of port names (in same order as in IBIS-ISS)

Ports A\_signal\_pos A\_signal\_neg my\_receive my\_driveP my\_driveN my\_enable

Ports A\_puref A\_pdref A\_pcref A\_gcref A\_extref my\_ref A\_gnd

|

| D\_to\_A d\_port port1 port2 vlow vhigh trise tfall corner\_name polarity

D\_to\_A D\_drive my\_driveP my\_ref MyVlow MyVHigh 0.5n 0.3n Typ Non-Inverting

D\_to\_A D\_drive my\_driveN my\_ref MyVlow MyVHigh 0.5n 0.3n Typ Inverting

D\_to\_A D\_enable my\_enable my\_ref 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_enable my\_enable my\_ref 0.0 3.0 0.6n 0.3n Min

D\_to\_A D\_enable my\_enable my\_ref 0.0 3.6 0.4n 0.3n Max

|

| A\_to\_D d\_port port1 port2 vlow vhigh corner\_name

A\_to\_D D\_receive A\_signal\_pos A\_signal\_neg -200m 200m Typ

A\_to\_D D\_receive A\_signal\_pos A\_signal\_neg -200m 200m Min

A\_to\_D D\_receive A\_signal\_pos A\_signal\_neg -200m 200m Max

|

[End External Model]

Example of True Differential [External Model] using VHDL-AMS:

[Model] Ext\_VHDL\_Diff\_Buff

Model\_type I/O\_diff

Rref\_diff = 100

|

| typ min max

[Voltage Range] 3.3 3.0 3.6

|

[Ramp]

dV/dt\_r 1.57/0.36n 1.44/0.57n 1.73/0.28n

dV/dt\_f 1.57/0.35n 1.46/0.44n 1.68/0.28n

|

| Other model subparameters are optional

|

[External Model]

Language VHDL-AMS

|

| Corner corner\_name file\_name entity(architecture)

Corner Typ diffio\_typ.vhd buffer(diff\_io\_typ)

Corner Min diffio\_min.vhd buffer(diff\_io\_min)

Corner Max diffio\_max.vhd buffer(diff\_io\_max)

|

| Parameters List of parameters

Parameters delay rate

Parameters preemphasis

|

| Ports List of port names (in same order as in VHDL-AMS)

Ports A\_signal\_pos A\_signal\_neg D\_receive D\_drive D\_enable

Ports A\_puref A\_pdref A\_pcref A\_gcref

|

[End External Model]

Example of Pseudo-Differential [External Model] using SPICE:

| Note that [Pin] and [Diff Pin] declarations are shown for clarity

|

|

[Pin] signal\_name model\_name R\_pin L\_pin C\_pin

1 Example\_pos Ext\_SPICE\_PDiff\_Buff

2 Example\_neg Ext\_SPICE\_PDiff\_Buff

|

| ...

|

[Diff Pin] inv\_pin vdiff tdelay\_typ tdelay\_min tdelay\_max

1 2 200mV 0ns 0ns 0ns

|

| ...

|

[Model] Ext\_SPICE\_PDiff\_Buff

Model\_type I/O

|

| Other model subparameters are optional

|

| typ min max

[Voltage Range] 3.3 3.0 3.6

|

[Ramp]

dV/dt\_r 1.57/0.36n 1.44/0.57n 1.73/0.28n

dV/dt\_f 1.57/0.35n 1.46/0.44n 1.68/0.28n

|

[External Model]

Language SPICE

|

| Corner corner\_name file\_name circuit\_name (.subckt name)

Corner Typ diffio.spi diff\_io\_typ

Corner Min diffio.spi diff\_io\_min

Corner Max diffio.spi diff\_io\_max

|

| Ports List of port names (in same order as in SPICE)

Ports A\_signal my\_drive my\_enable my\_ref

Ports A\_puref A\_pdref A\_pcref A\_gcref A\_gnd A\_extref

|

| D\_to\_A d\_port port1 port2 vlow vhigh trise tfall corner\_name

D\_to\_A D\_drive my\_drive my\_ref 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_drive my\_drive my\_ref 0.0 3.0 0.6n 0.3n Min

D\_to\_A D\_drive my\_drive my\_ref 0.0 3.6 0.4n 0.3n Max

D\_to\_A D\_enable my\_enable A\_pcref 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_enable my\_enable A\_pcref 0.0 3.0 0.6n 0.3n Min

D\_to\_A D\_enable my\_enable A\_pcref 0.0 3.6 0.4n 0.3n Max

|

| A\_to\_D d\_port port1 port2 vlow vhigh corner\_name

A\_to\_D D\_receive A\_signal my\_ref 0.8 2.0 Typ

A\_to\_D D\_receive A\_signal my\_ref 0.8 2.0 Min

A\_to\_D D\_receive A\_signal my\_ref 0.8 2.0 Max

|

| This example shows the evaluation of the received signals at the die

| pads. [Diff Pin] defines the interpretation of the A\_to\_D output

| polarity and levels and overrides the A\_to\_D settings shown above.

|

[End External Model]

*Keywords:* [External Circuit], [End External Circuit]

*Required:* No

*Description:* Used to reference an external file containing an arbitrary circuit description using one of the supported languages.

*Sub-Params:* Language, Corner, Parameters, Converter\_Parameters, Ports, D\_to\_A, A\_to\_D

*Usage Rules:* Each [External Circuit] keyword must be followed by a unique name that differs from any name used for any [Model] or [Submodel] keyword.

The [External Circuit] keyword may appear multiple times. It is not scoped by any other keyword.

Each instance of an [External Circuit] is referenced by one or more [Circuit Call] keywords discussed later. (The [Circuit Call] keyword cannot be used to reference a [Model] keyword.)

The [External Circuit] keyword and contents may be placed anywhere in the file, outside of any [Component] keyword group or [Model] keyword group, in a manner similar to that of the [Model] keyword.

Subparameter Definitions:

Language:

Accepts “SPICE”, “IBIS-ISS”, “VHDL-AMS”, “Verilog-AMS”, “VHDL-A(MS)” or “Verilog-A(MS)” as arguments. The Language subparameter is required and must appear only once.

Corner:

Three entries follow the Corner subparameter on each line:

corner\_name file\_name circuit\_name

The corner\_name entry is “Typ”, “Min”, or “Max”. The file\_name entry points to the referenced file in the same directory as the .ibs file.

Up to three Corner lines are permitted. A “Typ” line is required. If “Min” and/or “Max” data is missing, the tool may use “Typ” data in its place. However, the tool should notify the user of this action.

The circuit\_name entry provides the name of the circuit to be simulated within the referenced file. For SPICE and IBIS-ISS files, this is normally a “.subckt” name. For VHDL-AMS files, this is normally an “entity(architecture)” name pair. For Verilog-AMS files, this is normally a “module” name.

No character limits, case-sensitivity limits or extension conventions are required or enforced for file\_name and circuit\_name entries. However, the total number of characters in each Corner line must comply with Section 3. Furthermore, lower-case file\_name entries are recommended to avoid possible conflicts with file naming conventions under different operating systems. Case differences between otherwise identical file\_name entries or circuit\_name entries should be avoided. External languages may not support case-sensitive distinctions.

Parameters:

Lists names of parameters that may be passed into an external circuit file. Each Parameters entry must match a name or keyword in the external file or language. The list of Parameters can span several lines by using the word Parameters at the start of each line. The Parameters subparameter is optional, and the external circuit must operate with default settings without any Parameters assignments.

Parameter passing is not supported in SPICE. VHDL-AMS and VHDL-A(MS) parameters are supported using “generic” names, and Verilog-AMS and Verilog-A(MS) parameters are supported using “parameter” names. IBIS-ISS parameters are supported for all IBIS-ISS parameters which are defined on the subcircuit definition line.

Parameters are locally scoped under each [External Circuit] keyword, i.e., the same parameter under two different [External Circuit] will have independent values.

The parameter(s) listed under the Parameters subparameter may optionally be followed by an equal sign and a numeric, Boolean or string literal or a reference to a parameter name which is located in a parameter tree. The reference must begin with a file name, followed by an open parentheses and a the tree root name, a new open parentheses for any branch names (including the Reserved\_Parameters or Model\_Specific branch names if present in the tree) and the parameter name, and a matching set of closing parentheses. The file reference may point to any file which contains one or more parameter trees. The files referenced must be located in the same directory as the .ibs file containing the reference. The file names of parameter files must follow the rules for file names given in Section 3, GENERAL SYNTAX RULES AND GUIDELINES. Parameter files may only contain parameter trees using the tree syntax described in IBIS in section 10A with the following exceptions and additions:

When the extension of the external parameter’s file name ends with “.ami”:

a) only Usage In or Usage Info are allowed for parameters which are to be passed into models instantiated by the [External Model] or the [External Circuit] keywords

When the extension of the external parameter’s file name does not end with “.ami”:

a) the parameter tree must not contain the Reserved\_Parameters branch but must contain the Model\_Specific branch

b) only Usage Info is allowed

Note that in the case when a parameter is located in an .ami file and it is of Usage In, the parameter value will be passed into the AMI executable model but this does not mean that the same parameter couldn’t be used by other model(s) which are instantiated through [External Model] or [External Circuit].

Multiple parameters may only be listed on a single line if no value assignments are made. When the Parameters line includes a parameter value assignment, each parameter must be listed on a new line. String literals must be enclosed in double quotes.

The EDA tool may provide additional means to the user to assign values to Parameters. This may include the option to override the values provided in the .ibs file, to allow the user to make selections for multi-valued parameters in the parameter tree, or to provide values for uninitialized Parameters.

Converter\_Parameters:

This optional subparameter lists and initializes parameter names to be used as arguments in the A\_to\_D and/or D\_to\_A converter(s) of the [External Circuit] keyword under which it appears. The list of Converter\_Parameters may span several lines by using the word Converter\_Parameters at the start of each line. Any A\_to\_D or D\_to\_A argument which is entered as a parameter must be declared and initialized with the Converter\_Parameters subparameter.

Converter\_Parameters are locally scoped under each [External Circuit] keyword, i.e., the same converter parameter under two different [External Circuit]s will have independent values.

The Converter\_Parameters subparameter must contain one parameter name per line, which must be followed by an equal sign and a constant numeric literal or a reference to a parameter name which is located in a parameter tree. The reference must begin with a file name, followed by an open parentheses and a the tree root name, a new open parentheses for any branch names (including the Reserved\_Parameters or Model\_Specific branch names if present in the tree) and the parameter name, and a matching set of closing parentheses. The file reference may point to any file which contains one or more parameter trees. The files referenced must be located in the same directory as the .ibs file containing the reference. The file names of parameter files must follow the rules for file names given in Section 3, GENERAL SYNTAX RULES AND GUIDELINES. Parameter files may only contain parameter trees using the tree syntax described in IBIS in section 10A with the following exceptions and additions:

When the extension of the external parameter’s file name ends with “.ami”:

a) only Usage In or Usage Info are allowed for parameters which are to be passed into models instantiated by the [External Model] or the [External Circuit] keywords

When the extension of the external parameter’s file name does not end with “.ami”:

a) the parameter tree must not contain the Reserved\_Parameters branch but must contain the Model\_Specific branch

b) only Usage Info is allowed

Note that in the case when a parameter is located in an .ami file and it is of Usage In, the parameter value will be passed into the AMI executable model but this does not mean that the same parameter couldn’t be used by other model(s) which are instantiated through [External Model] or [External Circuit].

The EDA tool may provide additional means to the user to make assignments to Converter\_Parameters. This may include the option to override the values provided in the .ibs file, or to allow the user to make selections for multi-valued parameters in the parameter tree.

Ports:

Ports are interfaces to the [External Circuit] which are available to the user and tool at the IBIS level. They are used to connect the [External Circuit] to die pads. The Ports parameter is used to identify the ports of the [External Circuit] to the simulation tool. The port assignment is by position and the port names do not have to match exactly the names inside the external file. The list of port names may span several lines if the word Ports is used at the start of each line.

The Ports parameter is used to identify the ports of the [External Circuit] to the simulation tool. The port assignment is by position and the port names do not have to match exactly the port names in the external file. The list of port names may span several lines if the word Ports is used at the start of each line.

[External Circuit] allows any number of ports to be defined, with any names which comply with Section 3 format requirements. Reserved port names may be used, but ONLY DIGITAL PORTS will have the pre-defined functions listed in the General Assumptions heading above. User-defined and reserved port names may be combined within the same [External Circuit].

The [Pin Mapping] keyword cannot be used with [External Circuit] in the same [Component] description.

Digital-to-Analog/Analog-to-Digital Conversions:

These subparameters define all digital-to-analog and analog-to-digital converters needed to properly connect digital signals with the analog ports of referenced external SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) models. These subparameters must be used when [External Circuit] references a file written in the SPICE, IBIS-ISS,Verilog-A(MS) or VHDL-A(MS) language. They are not permitted with Verilog-AMS or VHDL-AMS external files.

D\_to\_A:

As assumed in [Model] and [External Model], some interface ports of [External Circuit]s expect digital input signals. As SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) models understand only analog signals, some conversion from digital to analog format is required. For example, input logical states such as “0” or “1” must be converted to actual input voltage stimuli, such as a voltage ramp, for SPICE simulation.

The D\_to\_A subparameter provides information for converting a digital stimulus, such as “0” or “1”, into an analog voltage ramp (a digital “X” input is ignored by D\_to\_A converters). Each digital port which carries data for conversion to analog format must have its own D\_to\_A declaration.

The D\_to\_A subparameter is followed by eight or optionally nine arguments:

d\_port port1 port2 vlow vhigh trise tfall corner\_name polarity

The d\_port entry holds the name of the digital port. This entry may contain user-defined port names or the reserved port names D\_drive, D\_enable, and D\_switch. he port1 and port2 entries hold the SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) analog input port names across which voltages are specified. These entries contain user-defined port names. One of these port entries must name a reference for the other port (for example, A\_gnd).

Normally, port1 accepts an input signal and port2 is the reference for port1. However, for an opposite polarity stimulus, port1 could be connected to a voltage reference and port2 could serve as the input. In some situations, such as in the case of a true differential buffer model, it might be desirable to provide two D\_to\_A converters, one to drive the Non-Inverting input and the other one to drive the Inverting input. In this case the D\_to\_A converters may be defined with the polarity argument, one with the value Non-Inverting and the other with the value Inverting.

The vlow and vhigh entries accept voltage values which correspond to fully-off and fully-on states, where the vhigh value must be greater than the vlow value. When polarity is Non-Inverting, vlow corresponds to the digital off state '0', vhigh corresponds to the digital on state '1', trise corresponds to the analog edge rate going from the digital off to on state, and tfall corresponds to the analog edge rate going from the digital on to off state. When polarity is Inverting, the analog behavior corresponds to the opposite digital states. For example, a 3.3 V ground-referenced buffer would list vlow as 0 V and vhigh as 3.3 V. For a Non-Inverting D\_to\_A converter, a rising edge in D\_drive would result in a transition from 0 V to 3.3 V, and for an Inverting D\_to\_A converter, a rising edge in D\_drive would result in a transition from 3.3 V to 0 V. The trise and tfall entries are times, must be positive and define input ramp rise and fall times between 0 and 100 percent.

The vlow, vhigh, trise and tfall arguments may be defined by parameter names, which must be declared and initialized by one or more Converter\_Parameters subparameter.

The corner\_name entry holds the name of the external circuit corner being referenced, as listed under the Corner subparameter.

The last argument, polarity, is optional. If present, its value must be "Inverting" or "Non-Inverting". If the argument is not present, "Non-Inverting" is in effect. The polarity argument may only be used with D\_to\_A converters which are connected to the d\_port name D\_drive. If the polarity argument is used, two D\_to\_A converter lines are required, one defined as Non-Inverting and another defined as Inverting. Any number of D\_to\_A subparameter lines is allowed, so long as each contains a unique port name entry and at least one unique port1 or port2 entry (i.e., several D\_to\_A declarations may use the same reference node under port1 or port2). At least one D\_to\_A line must be present, corresponding to the “Typ” corner model, for each digital line to be converted. Additional D\_to\_A lines for other corners may be omitted. In this case, the typical corner D\_to\_A entries will apply to all model corners and the “Typ” corner\_name entry may be omitted if the polarity argument is not present. When the polarity argument is present, the corner\_name argument must also be present.

A\_to\_D:

The A\_to\_D subparameter is used to generate a digital state (“0”, “1”, or “X”) based on analog voltages from the SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) model or from the pad/pin. This allows an analog signal from the external SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) circuit to be read as a digital signal by the simulation tool.

The A\_to\_D subparameter is followed by six arguments:

d\_port port1 port2 vlow vhigh corner\_name

The d\_port entry lists port names to be used for digital signals going. As with D\_to\_A, the port1 entry would contain a user-defined analog signal. Port2 would list another port name to be used as a reference. The voltage measurements are taken from the port1 entry with respect to the port2 entry. These ports must also be named by the Ports subparameter.

The vlow and vhigh entries list the low and high analog threshold voltage values. The reported digital state on D\_receive will be “0” if the measured voltage is lower than the vlow value, “1” if above the vhigh value, and “X” otherwise.

The vlow and vhigh arguments may be defined by parameter names, which must be declared and initialized by one or more Converter\_Parameters subparameter.

The corner\_name entry holds the name of the external model corner being referenced, as listed under the Corner subparameter.

Any number of A\_to\_D subparameter lines is allowed, so long as each line contains at least one column entry which is distinct from the column entries of all other lines. In practice, this means that A\_to\_D subparameter lines describing different corners will have identical port names. Other kinds of variations described through A\_to\_D subparameter lines should use unique port names. For example, a user may wish to create additional A\_to\_D converters for individual analog signals to monitor common mode behaviors on differential buffers.

At least one A\_to\_D line must be supplied corresponding to the “Typ” corner model. Other A\_to\_D lines for other corners may be omitted. In this case, the typical corner D\_to\_A entries will apply to all model corners.

IMPORTANT: measurements for receivers in IBIS may be conducted at the die pads or the pins. In such cases, the electrical input model data comprises a “load” which affects the waveform seen. However, for [External Circuit]s, the user may choose whether to measure the analog input response in the usual fashion or internal to the circuit (this does not preclude tools from reporting digital D\_receive and/or analog responses in addition to normal A\_signal response). If native IBIS measurements are desired, the A\_signal port would be named in the A\_to\_D line under port1. The A\_to\_D converter then effectively acts “in parallel” with the load of the circuit. If internal measurements are desired (e.g., if the user wishes to view the signal after processing by the receiver), the user-defined analog signal port would be named in the A\_to\_D line under port1. The A\_to\_D converter is effectively “in series” with the receiver model. The vhigh and vlow parameters should be adjusted appropriate to the measurement point of interest.

Note that, while the port assignments and SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) model data must be provided by the user, the D\_to\_A and A\_to\_D converters will be provided automatically by the tool. There is no need for the user to develop external SPICE, IBIS-ISS, Verilog-A(MS) or VHDL-A(MS) code specifically for these functions.

The [Diff Pin] keyword is NOT required for true differential [External Circuit] descriptions.

Pseudo-differential buffers are not supported under [External Circuit]. Use the existing [Model] and [External Model] keywords to describe these structures.

Note that the EDA tool is responsible for determining the specific measurement points for reporting timing and signal quality for [External Circuit]s.

In all other respects, [External Circuit] behaves exactly as [External Model].

*Examples:*

Example of Model B as an [External Circuit] using SPICE:

[External Circuit] BUFF-SPICE

Language SPICE

|

| Corner corner\_name file\_name circuit\_name (.subckt name)

Corner Typ buffer\_typ.spi bufferb\_io\_typ

Corner Min buffer\_min.spi bufferb\_io\_min

Corner Max buffer\_max.spi bufferb\_io\_max

|

| Parameters - Not supported in SPICE

|

| Ports List of port names (in same order as in SPICE)

Ports A\_signal int\_in int\_en int\_out A\_control

Ports A\_puref A\_pdref A\_pcref A\_gcref

|

| D\_to\_A d\_port port1 port2 vlow vhigh trise tfall corner\_name

D\_to\_A D\_drive int\_in my\_gcref 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_drive int\_in my\_gcref 0.0 3.0 0.6n 0.3n Min

D\_to\_A D\_drive int\_in my\_gcref 0.0 3.6 0.4n 0.3n Max

D\_to\_A D\_enable int\_en my\_gnd 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_enable int\_en my\_gnd 0.0 3.0 0.6n 0.3n Min

D\_to\_A D\_enable int\_en my\_gnd 0.0 3.6 0.4n 0.3n Max

|

| A\_to\_D d\_port port1 port2 vlow vhigh corner\_name

A\_to\_D D\_receive int\_out my\_gcref 0.8 2.0 Typ

A\_to\_D D\_receive int\_out my\_gcref 0.8 2.0 Min

A\_to\_D D\_receive int\_out my\_gcref 0.8 2.0 Max

|

| Note, the A\_signal port might also be used and int\_out not defined in

| a modified .subckt.

|

[End External Circuit]

Example [External Circuit] using IBIS-ISS:

[External Circuit] BUFF-ISS

Language IBIS-ISS

|

| Corner corner\_name file\_name circuit\_name (.subckt name)

Corner Typ buffer\_typ.spi bufferb\_io\_typ

Corner Min buffer\_min.spi bufferb\_io\_min

Corner Max buffer\_max.spi bufferb\_io\_max

|

| List of parameters

Parameters sp\_file\_name = paramfile.par(TreeRootName(Model\_Specific(TstoneFile)))

Parameters C1\_value

Parameters R1\_value = paramfile.par(TreeRootName(Model\_Specific(R1)))

|

Converter\_Parameters MyVlow = 0.0

Converter\_Parameters MyVHigh = 3.3

Converter\_Parameters MyVinl = paramfile.par(TreeRootName(Model\_Specific(Vinl)))

Converter\_Parameters MyVinh = paramfile.par(TreeRootName(Model\_Specific(Vinh)))

Converter\_Parameters MyTrise = paramfile.par(TreeRootName(Model\_Specific(Trf)))

Converter\_Parameters MyTfall = paramfile.par(TreeRootName(Model\_Specific(Trf)))

|

| Ports List of port names (in same order as in ISS)

Ports A\_signal int\_in int\_en int\_out A\_control

Ports A\_puref A\_pdref A\_pcref A\_gcref

|

| D\_to\_A d\_port port1 port2 vlow vhigh trise tfall corner\_name

D\_to\_A D\_drive int\_in my\_gcref MyVlow MyVhigh MyTfall MyTrise Typ

D\_to\_A D\_enable int\_en my\_gnd 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_enable int\_en my\_gnd 0.0 3.0 0.6n 0.3n Min

D\_to\_A D\_enable int\_en my\_gnd 0.0 3.6 0.4n 0.3n Max

|

| A\_to\_D d\_port port1 port2 vlow vhigh corner\_name

A\_to\_D D\_receive int\_out my\_gcref MyVinl MyVinh Typ

|

| Note, the A\_signal port might also be used and int\_out not defined in

| a modified .subckt.

|

[End External Circuit]

Example [External Circuit] using VHDL-AMS:

[External Circuit] BUFF-VHDL

Language VHDL-AMS

|

| Corner corner\_name file\_name entity(architecture)

Corner Typ buffer\_typ.vhd bufferb(buffer\_io\_typ)

Corner Min buffer\_min.vhd bufferb(buffer\_io\_min)

Corner Max buffer\_max.vhd bufferb(buffer\_io\_max)

|

| Parameters List of parameters

Parameters delay rate

Parameters preemphasis

|

| Ports List of port names (in same order as in VHDL-AMS)

Ports A\_signal A\_puref A\_pdref A\_pcref A\_gcref A\_control

Ports D\_drive D\_enable D\_receive

|

[End External Circuit]

Example [External Circuit] using Verilog-AMS:

[External Circuit] BUFF-VERILOG

Language Verilog-AMS

|

| Corner corner\_name file\_name circuit\_name (module)

Corner Typ buffer\_typ.v bufferb\_io\_typ

Corner Min buffer\_min.v bufferb\_io\_min

Corner Max buffer\_max.v bufferb\_io\_max

|

| Parameters List of parameters

Parameters delay rate

Parameters preemphasis

|

| Ports List of port names (in same order as in Verilog-AMS)

Ports A\_signal A\_puref A\_pdref A\_pcref A\_gcref A\_control

Ports D\_drive D\_enable D\_receive

|

[End External Circuit]

Example [External Circuit] using SPICE:

| Interconnect Structure as an [External Circuit]

|

|

[External Circuit] BUS\_SPI

Language SPICE

|

| Corner corner\_name file\_name circuit\_name (.subckt name)

Corner Typ bus\_typ.spi Bus\_typ

Corner Min bus\_min.spi Bus\_min

Corner Max bus\_max.spi Bus\_max

|

| Parameters - Not supported in SPICE

|

| Ports are in same order as defined in SPICE

Ports vcc gnd io1 io2

Ports int\_ioa vcca1 vcca2 vssa1 vssa2

Ports int\_iob vccb1 vccb2 vssb1 vssb2

|

| No A\_to\_D or D\_to\_A required, as no digital ports are used

|

[End External Circuit]

Example [External Circuit] using IBIS-ISS:

| Interconnect Structure as an [External Circuit]

|

|

[External Circuit] BUS\_SPI

Language IBIS-ISS

|

| Corner corner\_name file\_name circuit\_name (.subckt name)

Corner Typ bus\_typ.spi Bus\_typ

Corner Min bus\_min.spi Bus\_min

Corner Max bus\_max.spi Bus\_max

|

| List of parameters

Parameters sp\_file\_name

Parameters C1\_value R1\_value

|

| Ports are in same order as defined in IBIS-ISS

Ports vcc gnd io1 io2

Ports int\_ioa vcca1 vcca2 vssa1 vssa2

Ports int\_iob vccb1 vccb2 vssb1 vssb2

|

| No A\_to\_D or D\_to\_A required, as no digital ports are used

|

[End External Circuit]

Example [External Circuit] using VHDL-AMS:

[External Circuit] BUS\_VHD

Language VHDL-AMS

|

| Corner corner\_name file\_name entity(architecture)

Corner Typ bus.vhd Bus(Bus\_typ)

Corner Min bus.vhd Bus(Bus\_min)

Corner Max bus.vhd Bus(Bus\_max)

|

| Parameters List of parameters

Parameters r1 l1

Parameters r2 l2 temp

|

| Ports are in the same order as defined in VHDL-AMS

Ports vcc gnd io1 io2

Ports int\_ioa vcca1 vcca2 vssa1 vssa2

Ports int\_iob vccb1 vccb2 vssb1 vssb2

Example [External Circuit] using Verilog-AMS:

[External Circuit] BUS\_V

Language Verilog-AMS

|

| Corner corner\_name file\_name circuit\_name (module)

Corner Typ bus.v Bus\_typ

Corner Min bus.v Bus\_min

Corner Max bus.v Bus\_max

|

| Parameters List of parameters

Parameters r1 l1

Parameters r2 l2 temp

|

| Ports are in the same order as defined in Verilog-AMS

Ports vcc gnd io1 io2

Ports int\_ioa vcca1 vcca2 vssa1 vssa2

Ports int\_iob vccb1 vccb2 vssb1 vssb2

|

[End External Circuit]

The scope of the following keywords is limited to the [Component] keyword. They apply to the specific set of pin numbers and internal nodes only within that [Component].

*Keywords*: [Node Declarations], [End Node Declarations]

*Required:* Yes, if any internal nodes exist on the die as listed in [Circuit Call], and/or if any die pads need to be explicitly defined.

*Description:* Provides a list of internal die nodes and/or die pads for a [Component] to make unambiguous interconnection descriptions possible.

*Usage Rules*: All die node and die pad names that appear under any [Circuit Call] keyword within the same [Component] must be listed under the [Node Declarations] keyword.

If used, the [Node Declarations] keyword must appear before any [Circuit Call] keyword(s) under the [Component] keyword. Only one [Node Declarations] keyword is permitted for each [Component] keyword. Since the [Node Declarations] keyword is part of the [Component] keyword, all internal node or pad references apply only to that [Component] (i.e., they are local).

The internal die node and/or die pad names within [Node Declarations] must be unique and therefore different from the pin names used in the [Pin] keyword. Each node and/or pad name must be separated by at least one white space. The list may span several lines and is terminated by the [End Node Declarations] keyword.

The names of die nodes and die pads can be composed of any combination of the legal characters outlined in Section 3.

*Example:*

[Node Declarations] | Must appear before any [Circuit Call] keyword

|

| Die nodes:

a b c d e | List of die nodes

f g h nd1

|

| Die pads:

pad\_2a pad\_2b pad\_4 pad\_11 | List of die pads

|

[End Node Declarations]

*Keywords:* [Circuit Call], [End Circuit Call]

*Required:* Yes, if any [External Circuit]s are present in a [Component].

*Description:* This keyword is used to instantiate [External Circuit]s and to connect their ports to the die nodes or die pads.

*Sub-Params:* Signal\_pin, Diff\_signal\_pins, Series\_pins, Port\_map

*Usage Rules:* The [Circuit Call] keyword must be followed by the name of an [External Circuit] that exists in the same [Component].

When a [Circuit Call] keyword defines any connections that involve one or more die pads (and consequently pins), the corresponding pins on the [Pin] list must use the reserved word “CIRCUITCALL” in the third column instead of a model name.

Each [External Circuit] must have at least one corresponding [Circuit Call] keyword. Multiple [Circuit Call] keywords may appear under a [Component] using the same [External Circuit] name, if multiple instantiations of an [External Circuit] are needed.

Signal\_pin, Diff\_signal\_pins, or Series\_pins:

The purpose of these subparameters is to identify which [External Circuit] needs to be stimulated in order to obtain a signal on a certain pin. These subparameters must be used only when the [External Circuit] that is referenced by the [Circuit Call] keyword makes use of the stimulus signal of the simulator. Any given [Circuit Call] keyword must contain no more than one instance of only one of these three subparameters. The subparameter is followed by one or two pin names which must be defined by the [Pin] keyword.

Signal\_pin is used when the referenced [External Circuit] has a single analog signal port (I/O) connection to one pin. The subparameter is followed by a pin name that must match one of the pin names under the [Pin] keyword.

Diff\_signal\_pins is used when the referenced [External Circuit] describes a true differential model which has two analog signal port (I/O) connections, each to a separate pin. The subparameter is followed by two pin names, each of which must match one of the pin names under the [Pin] keyword. The first and second pin names correspond to the non-inverting and inverting signals of the differential model, respectively. The two pin names must not be identical.

Series\_pins is used when the referenced [External Circuit] describes a Series or Series\_switch model which has two analog signal port (I/O) connections to two pins. The subparameter is followed by two pin names, each of which must match one of the pin names under the [Pin] keyword. The first and second pin names correspond to the positive and negative ports of the Series or Series\_switch model, respectively. However, the polarity order matters only when the model is polarity sensitive (as with the [Series Current] keyword). The two pin names must not be identical.

Port\_map:

The Port\_map subparameter is used to connect the ports of an [External Circuit] to die nodes or die pads.

Every occurrence of the Port\_map subparameter must begin on a new line and must be followed by two arguments, the first being a port name, and the second being a die node, die pad, or a pin name.

The first argument of Port\_map must contain a port name that matches one of the port names in the corresponding [External Circuit] definition. No port name may be listed more than once within a [Circuit Call] statement. Only those port names need to be listed with the Port\_map subparameter which are connected to a die node or a die pad. This includes reserved and/or user-defined port names.

The second argument of the Port\_map subparameter contains the name of a die node, die pad, or a pin. The names of die nodes, die pads, and pins may appear multiple times as Port\_map subparameter arguments within the same [Circuit Call] statement to signify a common connection between multiple ports, such as common voltage supply.

Please note that a pin name in the second argument does not mean that the connection is made directly to the pin. Since native IBIS does not have a mechanism to declare die pads explicitly, connections to die pads are made through their corresponding pin names (listed under the [Pin] keyword). This convention must only be used with native IBIS package models where a one-to-one path between the die pads and pins is assumed. When a package model other than native IBIS is used with a [Component], the second argument of Port\_map must have a die pad or die node name. These names are matched to the corresponding port name of the non-native package model by name (not by position). In this case, the package model may have an arbitrary circuit topology between the die pads and the pins. A one-to-one mapping is not required.

*Examples:*

NOTE REGARDING THIS EXAMPLE:

The pad\_\* to pin connections in Figure 29 and in the example lines with the comment, "explicit pad connection", are shown for reference. The connection syntax has not yet been defined. Therefore, the connections for pad\_\* to pin are not supported in this specification.

For the examples below please refer to Figure 29 and the example provided for the [Node Declarations] keyword.



1. - Reference Example for [Node Declarations] Keyword

[Circuit Call] A | Instantiates [External Circuit] named "A"

|

Signal\_pin 1

|

| mapping port pad/node

|

Port\_map A\_mypcr a | Port to internal node connection

Port\_map A\_mypur b | Port to internal node connection

Port\_map A\_mysig c | Port to internal node connection

Port\_map A\_mypdr d | Port to internal node connection

Port\_map A\_mygcr e | Port to internal node connection

|

[End Circuit Call]

|

|

[Circuit Call] B | Instantiates [External Circuit] named "B"

|

Signal\_pin 2

|

| mapping port pad/node

|

Port\_map A\_mypur f | Port to internal node connection

Port\_map A\_mysig g | Port to internal node connection

Port\_map A\_mypdr h | Port to internal node connection

Port\_map A\_mycnt pad\_2b | Port to explicit pad connection

|

[End Circuit Call]

|

|

[Circuit Call] C | Instantiates [External Circuit] named "C"

|

Signal\_pin 3

|

| mapping port pad/node

|

Port\_map A\_mypcr 10 | Port to implicit pad connection

Port\_map A\_mypur 10 | Port to implicit pad connection

Port\_map A\_mysig 3 | Port to implicit pad connection

Port\_map A\_mypdr pad\_11 | Port to explicit pad connection

Port\_map A\_mygcr pad\_11 | Port to explicit pad connection

Port\_map D\_mydrv nd1 | Port to internal node connection

|

[End Circuit Call]

|

|

[Circuit Call] D | Instantiates [External Circuit] named "D"

|

Signal\_pin 4a

|

| mapping port pad/node

|

Port\_map A\_my\_pcref 10 | Port to implicit pad connection

Port\_map A\_my\_signal pad\_4 | Port to explicit pad connection

Port\_map A\_my\_gcref pad\_11 | Port to explicit pad connection

Port\_map D\_receive nd1 | Port to internal node connection

|

[End Circuit Call]

|

|

[Circuit Call] Die\_Interconnect | Instantiates [External Circuit] named

| "Die\_Interconnect"

|

| mapping port pad/node

|

Port\_map vcc 10 | Port to implicit pad connection

Port\_map gnd pad\_11 | Port to explicit pad connection

Port\_map io1 1 | Port to implicit pad connection

Port\_map o2 pad\_2a | Port to explicit pad connection

Port\_map vcca1 a | Port to internal node connection

Port\_map vcca2 b | Port to internal node connection

Port\_map int\_ioa c | Port to internal node connection

Port\_map vssa1 d | Port to internal node connection

Port\_map vssa2 e | Port to internal node connection

Port\_map vccb1 f | Port to internal node connection

Port\_map int\_ob g | Port to internal node connection

Port\_map vssb1 h | Port to internal node connection

|

[End Circuit Call]

1. Algorithmic Modeling Interface (AMI)

INTRODUCTION:

Algorithmic modeling of advanced Serializer-Deserializer (SERDES) devices is supported by IBIS, through the Algorithmic Modeling Interface (AMI). The AMI approach breaks SERDES device modeling into two parts – electrical and algorithmic. The combination of the transmitter’s analog back-end, the serial channel and the receiver’s analog front-end are assumed to be linear and time invariant. There is no limitation that the equalization has to be linear and time invariant. The “analog” portion of the channel is characterized by means of an impulse response leveraging the IBIS constructs for device models defined in Sections 6, 6A and 6B.

The transmitter equalization, receiver equalization and clock recovery circuits are assumed to have a high-impedance (electrically isolated) connection to the analog portion of the channel. This makes it possible to model these circuits based on a characterization of the analog channel. The behavior of these circuits is modeled algorithmically through two files:

* an executable model file, which processes the waveforms that characterize the channel
* a parameter definition file, which defines key parameters and parameter ranges used by the executable model file and/or the EDA tool itself for algorithmic modeling

Both of these files are provided by the SERDES device vendor.

This section defines how the components of an algorithmic model are specified in an .ibs file. The structure of the executable model file, methods for passing data to and from the executable model file and how the executable model file is called from the EDA tool are described in Section 10. Section 10A describes the parameter definition file syntax and usage.

References to algorithmic models may be included in .ibs files using the following keywords:

[Algorithmic Model]

[End Algorithmic Model]

The placement of these keywords within the hierarchy of IBIS is shown below:

├── **[Component]**

│

├── **[Model]**

│ │

│ ├── **[Algorithmic Model]**

│ │ └── **[End Algorithmic Model]**

│ │

KEYWORD DEFINITIONS:

*Keywords:* [Algorithmic Model], [End Algorithmic Model]

*Required:* No

*Description:* Used to reference an executable model file and accompanying parameter definition file. This executable model file encapsulates signal processing functions, while the parameter definition file includes configuration information for the model and EDA tool. In the case of a receiver, the executable model file may additionally include clock and data recovery functions. The executable model file can receive and modify waveforms with the analog channel, where the analog channel consists of the transmitter output stage, the transmission channel itself and the receiver input stage. This data exchange is implemented through a set of software functions. The signature of these functions is elaborated in Section 10 of this document. The function interface must comply with the ANSI "C" language.

Note that, while the file is described here as an “executable model file”, the file is a compiled library of functions that may or may not be itself executable.

*Sub-Params:*  Executable

*Usage Rules:* The [Algorithmic Model] keyword must be positioned within a [Model] section and it may appear only once for each [Model] keyword in a .ibs file. It is not permitted under the [Submodel] keyword or in [Model]s which are of Model\_type Terminator, Series or Series\_switch.

The [Algorithmic Model] always processes a single waveform regardless whether the model is single ended or differential. When the model is differential, the waveform passed to the [Algorithmic Model] must be a difference waveform.

[Algorithmic Model], [End Algorithmic Model]:

Begins and ends an algorithmic model section, respectively.

Executable:

Three entries follow the Executable subparameter on each line:

Platform\_Compiler\_Bits File\_Name Parameter\_File

The Platform\_Compiler\_Bits entry provides the name of the operating system, compiler and its version and the number of bits the executable model file is compiled for. It is a string without white spaces, consisting of three fields separated by an underscore (“\_”). The first field consists of the name of the operating system followed optionally by its version. The second field consists of the name of the compiler followed by optionally by its version. The third field is an integer indicating the platform architecture. If the version for either the operating system or the compiler contains an underscore, it must be converted to a hyphen “-”. This is so that an underscore is only present as a separation character in the entry.

The architecture entry can be either “32” or “64”. Examples of Platform\_Compiler\_Bits:

Linux\_gcc3.2.3\_32

Solaris5.10\_gcc4.1.1\_64

Solaris\_cc5.7\_32

Windows\_VisualStudio7.1.3088\_32

HP-UX\_accA.03.52\_32

The EDA tool will check for the compiler information and verify if the executable model file is compatible with the operating system and platform.

Multiple occurrences, without duplication, of Executable are permitted to allow for providing executable model files for as many combinations of operating system platforms and compilers for the same algorithmic model.

The File\_Name provides the name of the executable model file. The executable model file should be in the same directory as the.ibs file.

The Parameter\_File entry provides the name of the parameter definition file, which shall have an extension of .ami. This must be an external file and should reside in the same directory as the .ibs file and the executable model file. See Section 10A for details.

*Examples:*

Example of Receiver Model in [Algorithmic Model]:

[Algorithmic Model]

|

Executable Windows\_VisualStudio\_32 example\_rx.dll example\_rx\_params.ami

|

[End Algorithmic Model]

Example of Transmitter Model in [Algorithmic Model]:

[Algorithmic Model]

|

Executable Windows\_VisualStudio\_32 tx\_getwave.dll tx\_getwave\_params.ami

Executable Solaris\_cc\_32 libtx\_getwave.so tx\_getwave\_params.ami

|

[End Algorithmic Model]

1. Test Load and Data Description

INTRODUCTION:

The [Test Load] and [Test Data] keywords are top-level keywords to provide reference waveforms against which IBIS model simulation results can be compared to determine the accuracy of the IBIS data and simulator implementation.

KEYWORD DEFINITIONS:

*Keyword:* [Test Data]

*Required:* No

*Description:* Indicates the beginning of a set of Golden Waveforms and references the conditions under which they were derived. A .ibs file may contain any number of [Test Data] sections representing different driver and load combinations. Golden Waveforms are a set of waveforms simulated using known ideal test loads. They are useful in verifying the accuracy of behavioral simulation results against the transistor level circuit model from which the IBIS model parameters originated.

*Sub-Params:* Test\_data\_type, Driver\_model, Driver\_model\_inv, Test\_load

*Usage Rules:* The name following the [Test Data] keyword is required. It allows a tool to select which data to analyze.

The Test\_data\_type subparameter is required, and its value must be either “Single\_ended” or “Differential.” The value of Test\_data\_type must match the value of Test\_load\_type found in the load called by Test\_load.

The Driver\_model subparameter is required. Its value specifies the “device-under-test” and must be a valid [Model] name. Driver\_model\_inv is only legal if Test\_data\_type is Differential. Driver\_model\_inv is not required but may be used in the case in which a differential driver uses two different models for the inverting and non-inverting pins.

The Test\_load subparameter is required and indicates which [Test Load] was used to derive the Golden Waveforms. It must reference a valid [Test Load] name.

*Example:*

[Test Data] Data1

Test\_data\_type Single\_ended

Driver\_model Buffer1

Test\_load Load1

*Keywords:* [Rising Waveform Near], [Falling Waveform Near], [Rising Waveform Far], [Falling Waveform Far], [Diff Rising Waveform Near], [Diff Falling Waveform Near],   
[Diff Rising Waveform Far], [Diff Falling Waveform Far]

*Required:* At least one Rising/Falling waveform is required under the scope of the [Test Data] keyword.

*Description:* Describes the shape of the rising and falling Golden Waveforms of a given driver and a given [Test Load] measured at the driver I/O pad (near) or receiver I/O pad (far). A model developer may use the [Rising Waveform Near/Far] and [Falling Waveform Near/Far] keywords to document Golden Waveforms whose purpose is to facilitate the correlation of reference waveforms and behavioral simulations.

*Usage Rules:* The process, temperature, and voltage conditions under which the Golden Waveforms are generated must be identical to those used to generate the I-V and V-T tables. The Golden Waveforms must be generated using unpackaged driver and receiver models. The simulator must NOT use the Golden Waveform tables in the construction of its internal stimulus function.

The tables must conform to the format described under the [Rising Waveform] and [Falling Waveform] keywords.

Both differential and single-ended waveforms are allowed regardless of the value of Test\_data\_type. If Test\_data\_type is Single\_ended then differential waveforms will be ignored. If Test\_data\_type is Differential, a single-ended waveform refers to the model specified by Driver\_model and the non-inverting driver output.

*Example:*

[Rising Waveform Far]

| Time V(typ) V(min) V(max)

0.0000s 25.2100mV 15.2200mV 43.5700mV

0.2000ns 2.3325mV -8.5090mV 23.4150mV

0.4000ns 0.1484V 15.9375mV 0.3944V

0.6000ns 0.7799V 0.2673V 1.3400V

0.8000ns 1.2960V 0.6042V 1.9490V

1.0000ns 1.6603V 0.9256V 2.4233V

1.2000ns 1.9460V 1.2050V 2.8130V

1.4000ns 2.1285V 1.3725V 3.0095V

1.6000ns 2.3415V 1.5560V 3.1265V

1.8000ns 2.5135V 1.7015V 3.1600V

2.0000ns 2.6460V 1.8085V 3.1695V

| ...

10.0000ns 2.7780V 2.3600V 3.1670V

|

[Falling Waveform Far]

| Time V(typ) V(min) V(max)

0.0000s 5.0000V 4.5000V 5.5000V

0.2000ns 4.7470V 4.4695V 4.8815V

0.4000ns 3.9030V 4.0955V 3.5355V

0.6000ns 2.7313V 3.4533V 1.7770V

0.8000ns 1.8150V 2.8570V 0.8629V

1.0000ns 1.1697V 2.3270V 0.5364V

1.2000ns 0.7539V 1.8470V 0.4524V

1.4000ns 0.5905V 1.5430V 0.4368V

1.6000ns 0.4923V 1.2290V 0.4266V

1.8000ns 0.4639V 0.9906V 0.4207V

2.0000ns 0.4489V 0.8349V 0.4169V

| ...

10.0000ns 0.3950V 0.4935V 0.3841V

*Keyword:* [Test Load]

*Required:* No

*Description:* Defines a generic test load network and its associated electrical parameters for reference by Golden Waveforms under the [Test Data] keyword. The Golden Waveform tables correspond to a given [Test Load] which is specified by the Test\_load subparameter under the [Test Data] keyword.

*Sub-Params:* Test\_load\_type, C1\_near, Rs\_near, Ls\_near, C2\_near, Rp1\_near, Rp2\_near, Td, Zo, Rp1\_far, Rp2\_far, C2\_far, Ls\_far, Rs\_far, C1\_far, V\_term1, V\_term2, Receiver\_model, Receiver\_model\_inv, R\_diff\_near, R\_diff\_far.

*Usage Rules:* The Test\_load\_type subparameter is required, and its value must be either “Single\_ended” or “Differential.”

The subparameters specify the electrical parameters associated with a fixed generic test load. Figure 30 describes the single\_ended test load.

All subparameters except Test\_load\_type are optional. If omitted, series elements are shorted and shunt elements are opened by default.



1. - [Test Load] Elements and Placement

If the Td subparameter is present, then the Zo subparameter must also be present. If the Td subparameter is not present, then the simulator must remove the transmission line from the network and short the two nodes to which it was connected.

V\_term1 defines the termination voltage for parallel termination resistors Rp1\_near and Rp1\_far. This voltage is not related to the [Voltage Range] keyword. If either Rp1\_near or Rp1\_far is used, then V\_term1 must also be used.

V\_term2 defines the termination voltage for parallel termination resistors Rp2\_near and Rp2\_far. If either Rp2\_near or Rp2\_far is used, then V\_term2 must also be used.

Receiver\_model is optional and indicates which, if any, receiver is connected to the far end node. If not used, the network defaults to no receiver.

Receiver\_model\_inv is not required but may be used in the case in which a differential receiver uses two different models for the inverting and non-inverting pins. Receiver\_model\_inv is ignored if Test\_load\_type is Single-ended.

If Test\_load\_type is Differential, then the test load is a pair of the above circuits. If the R\_diff\_near or R\_diff\_far subparameter is used, a resistor is connected between the near or far nodes of the two circuits. If Test\_load\_type is Single\_ended, R\_diff\_near and R\_diff\_far are ignored.

*Example:*

[Test Load] Load1

Test\_load\_type Single\_ended

C1\_near = 1p

Rs\_near = 10

Ls\_near = 1n

C2\_near = 1p

Rp1\_near = 100

Rp2\_near = 100

Td = 1ns

Zo = 50

Rp1\_far = 100

Rp2\_far = 100

C2\_far = 1p

Ls\_far = 1n

Rs\_far = 10

C1\_far = 1p

R\_diff\_far = 100

Receiver\_model Input1

| variable typ min max

|

V\_term1 1.5 1.4 1.6

V\_term2 0.0 0.0 0.0

|

| Example of a transmission line and receiver test load

|

[Test Load] Tline\_rcv

Td = 1n

Zo = 50

Receiver\_model Input1

# Package Modeling

The [Package Model] keyword is optional. If more than the default RLC package model is desired, use the [Define Package Model] keyword.

Use the [Package Model] keyword within a [Component] to indicate the package model for that component. The specification permits .ibs files to contain the following additional list of package model keywords. Note that the actual package models can be in a separate <package\_file\_name>.pkg file or can exist in the .ibs files between the [Define Package Model] ... [End Package Model] keywords for each package model that is defined. For reference, these keywords are listed in Table 15. Full descriptions follow. EDA tools that do not support these keywords will ignore all entries between the [Define Package Model] and [End Package Model] keywords.

Table – Package Modeling Keywords

| **Keyword** | **Notes** |
| --- | --- |
| [Define Package Model] | Required if the [Package Model] keyword is used |
| [Manufacturer] | (note 1) |
| [OEM] | (note 1) |
| [Description] | (note 1) |
| [Number Of Sections] | (note 2) |
| [Number Of Pins] | (note 1) |
| [Pin Numbers] | (note 1) |
| [Model Data] | (note 2) |
| [Resistance Matrix] | Optional when [Model Data] is used |
| [Inductance Matrix] | (note 3) |
| [Capacitance Matrix] | (note 3) |
| [Bandwidth] | Required (for Banded\_matrix matrices only) |
| [Row] | (note 3) |
| [End Model Data] | (note 2) |
| [End Package Model] | (note 1) |
| Note 1 Required when the [Define Package Model] keyword is used  Note 2 Either the [Number Of Sections] or the [Model Data]/[End Model Data] keywords are required. Note that [Number of Sections] and the [Model Data]/[End Model Data] keywords are mutually exclusive.  Note 3 Required when the [Define Package Model] keyword is used and the [Number Of Sections] keyword is not used. | |

When package model definitions occur within a .ibs file, their scope is “local”—they are known only within that .ibs file and no other. In addition, within that .ibs file, they override any globally defined package models that have the same name.

Usage Rules for the .Pkg File:

Package models are stored in a file whose name looks like:

<filename>.pkg.

The <filename> provided must adhere to the rules given in Section 3, "GENERAL SYNTAX RULES AND GUIDELINES". Use the “.pkg” extension to identify files containing package models. The .pkg file must contain all of the required elements of a normal .ibs file, including [IBIS Ver], [File Name], [File Rev], and the [End] keywords. Optional elements include the [Date], [Source], [Notes], [Disclaimer], [Copyright], and [Comment Char] keywords. All of the elements follow the same rules as those for a normal .ibs file.

Note that the [Component] and [Model] keywords are not allowed in the .pkg file. The .pkg file is for package models only.

*Keyword:* [Define Package Model]

*Required:* Yes

*Description:* Marks the beginning of a package model description.

*Usage Rules:* If the .pkg file contains data for more than one package, each section must begin with a new [Define Package Model] keyword. The length of the package model name must not exceed 40 characters in length. Blank characters are allowed. For every package model name defined under the [Package Model] keyword, there must be a matching [Define Package Model] keyword.

*Example:*

[Define Package Model] QS-SMT-cer-8-pin-pkgs

*Keyword:* [Manufacturer]

*Required:* Yes

*Description:* Declares the manufacturer of the component(s) that use this package model.

*Usage Rules:* The length of the manufacturer’s name must not exceed 40 characters (blank characters are allowed, e.g., Texas Instruments). In addition, each manufacturer must use a consistent name in all .ibs and .pkg files.

*Example:*

[Manufacturer] Quality Semiconductors Ltd.

Keyword: [OEM]

*Required:* Yes

*Description:* Declares the manufacturer of the package.

*Usage Rules:* The length of the manufacturer’s name must not exceed 40 characters (blank characters are allowed). In addition, each manufacturer must use a consistent name in all .ibs and .pkg files.

Other Notes: This keyword is useful if the semiconductor vendor sells a single IC in packages from different manufacturers.

*Example:*

[OEM] Acme Packaging Co.

*Keyword:* [Description]

*Required:* Yes

*Description:* Provides a concise yet easily human-readable description of what kind of package the [Package Model] is representing.

*Usage Rules:* The description must be less than 60 characters in length, must fit on a single line, and may contain spaces.

*Example:*

[Description] 220-Pin Quad Ceramic Flat Pack

*Keyword:* [Number Of Sections]

*Required:* No

*Description:* Defines the maximum number of sections that make up a “package stub”. A package stub is defined as the connection between the die pad and the corresponding package pin; it can include (but is not limited to) the bondwire, the connection between the bondwire and pin, and the pin itself. This keyword must be used if a modeler wishes to describe any package stub as other than a single, lumped L/R/C. The sections of a package stub are assumed to connect to each other in a series fashion.

*Usage Rules:* The argument is a positive integer greater than zero. This keyword, if used, must appear in the specification before the [Pin Numbers] keyword. The maximum number of sections includes sections between the Fork and Endfork subparameters.

*Example:*

[Number Of Sections] 3

*Keyword:* [Number Of Pins]

*Required:* Yes

*Description:* Tells the parser how many pins to expect.

*Usage Rules:* The field must be a positive decimal integer. The [Number Of Pins] keyword must be positioned before the [Pin Numbers] keyword.

*Example:*

[Number Of Pins] 128

*Keyword:* [Pin Numbers]

*Required:* Yes

*Description:* Tells the parser the set of names that are used for the package pins and also defines pin ordering. If the [Number Of Sections] keyword is present it also lists the elements for each section of a pin’s die to pin connection.

*Sub-Params:* Len, L, R, C, Fork, Endfork

*Usage Rules:* Following the [Pin Numbers] keyword, the names of the pins are listed. There must be as many names listed as there are pins (as given by the preceding [Number Of Pins] keyword). Pin names cannot exceed 5 characters in length. The first pin name given is the “lowest” pin, and the last pin given is the “highest.” If the [Number Of Sections] keyword is used then each pin name must be followed by one or more of the legal subparameter combinations listed below. If the [Number Of Sections] keyword is not present then subparameter usage is NOT allowed.

Subparameters:

The Len, L, R, and C subparameters specify the length, inductance, capacitance and resistance of each section of each stub on a package.

The Fork and Endfork subparameters are used to denote branches from the main package stub.

Len The length of a package stub section. Lengths are given in terms of arbitrary “units”.

L The inductance of a package stub section, in terms of henries/unit length. For example, if the total inductance of a section is 3.0nH and the length of the section is 2 “units”, the inductance would be listed as L = 1.5nH (i.e., 3.0 / 2).

C The capacitance of a package stub section, in terms of farads/unit length.

R The DC (ohmic) resistance of a package stub section, in terms of ohms/unit length.

Fork This subparameter indicates that the sections following (up to the Endfork subparameter) are part of a branch off of the main package stub. This subparameter has no arguments.

Endfork This subparameter indicates the end point of a branch. For every Fork subparameter there must be a corresponding Endfork subparameter. As with the Fork subparameter, the Endfork subparameter has no arguments.

Specifying a Len or L/R/C value of zero is allowed. If Len = 0 is specified, then the L/R/C values are the total for that section. If a non-zero length is specified, then the total L/R/C for a section is calculated by multiplying the value of the Len subparameter by the value of the L, R, or C subparameter. However, if a non-zero length section is specified, the L and C for that section should be treated as distributed elements.

Using The Subparameters to Describe Package Stub Sections:

A section description begins with the Len subparameter and ends with the slash (/) character. The value of the Len, L, R, and C subparameters and the subparameter itself are separated by an equals sign (=); white space around the equals sign is optional. The Fork and Endfork subparameters are placed between section descriptions (i.e., between the concluding slash of one section and the “Len” parameter that starts another). A particular section description can contain no data (i.e., the description is given as “Len = 0 /”).

Legal Subparameter Combinations for Section Descriptions:

A) A single Len = 0 subparameter, followed by a slash. This is used to describe a section with no data.

B) Len, and one or more of the L, R, and C subparameters. If the Len subparameter is given as zero, then the L/R/C subparameters represent lumped elements. If the Len subparameter is non-zero, then the L/R/C subparameters represent distributed elements.

C) Single Fork or Endfork subparameter. Normally, a package stub is described as several sections, with the Fork and Endfork subparameters surrounding a group of sections in the middle of the complete package stub description. However, it is legal for the Fork/Endfork subparameters to appear at the end of a section description. The package pin is connected to the last section of a package stub description not surrounded by a Fork/Endfork statements. See the examples below.

Package Stub Boundaries:

A package stub description starts at the connection to the die and ends at the point at which the package pin interfaces with the board or substrate the IC package is mounted on. Note that in the case of a component with through-hole pins, the package stub description should include only the portion of the pin not physically inserted into the board or socket. However, it is legal for a package stub description to include both the component and socket together if this is how the component is intended to be used.

*Examples:*

| A three-section package stub description that includes a bond wire (lumped

| inductance), a trace (treated as a transmission line with DC resistance),

| and a pin modeled as a lumped L/C element.

|

[Pin Numbers]

A1 Len=0 L=1.2n/ Len=1.2 L=2.0n C=0.5p R=0.05/ Len=0 L=2.0n C=1.0p/

|

| Pin A2 below has a section with no data

|

A2 Len=0 L=1.2n/ Len=0/ Len=1.2 L=2.0n C=0.5p R=0.05/ Len=0 L=2.0n C=1.0p/

|

| A section description using the Fork and Endfork subparameters. Note that

| the indentation of the Fork and Endfork subparameters are for readability

| are not required.

|

A1 Len=0 L=2.3n / | bondwire

Len=1.2 L=1.0n C=2.5p / | first section

Fork | indicates the starting of a branch

Len=1.0 L=2.0n C=1.5p / | section

Endfork | ending of the branch

Len=0.5 L=1.0 C=2.5p/ | second section

Len=0.0 L=1.5n / | pin

|

| Here is an example where the Fork/Endfork subparameters are at the end of a

| package stub description.

|

B13 Len=0 L=2.3n / | bondwire

Len=1.2 L=1.0n C=2.5p / | first section

Len=0.5 L=1.0 C=2.5/ | second section, pin connects here

Fork | indicates the starting of a branch

Len=1.0 L=2.0n C=1.5p / | section

Endfork | ending of the branch

*Keyword:* [Model Data]

*Required:* Yes

*Description:* Indicates the beginning of the formatted package model data, that can include the [Resistance Matrix], [Inductance Matrix], [Capacitance Matrix], [Bandwidth], and [Row] keywords.

*Example:*

[Model Data]

*Keyword:* [End Model Data]

*Required:* Yes

*Description:* Indicates the end of the formatted model data.

*Other Notes:* In between the [Model Data] and [End Model Data] keywords is the package model data itself. The data is a set of three matrices: the resistance (R), inductance (L), and capacitance (C) matrices. Each matrix can be formatted differently (see below). Use one of the matrix keywords below to mark the beginning of each new matrix.

*Example:*

[End Model Data]

*Keywords:* [Resistance Matrix], [Inductance Matrix], [Capacitance Matrix]

*Required:* [Resistance Matrix] is optional. If it is not present, its entries are assumed to be zero. [Inductance Matrix] and [Capacitance Matrix] are required.

*Sub-Params:* Banded\_matrix, Sparse\_matrix, or Full\_matrix

*Description:* The subparameters mark the beginning of a matrix, and specify how the matrix data is formatted. See Figure 31.

*Usage Rules:* For each matrix keyword, use only one of the subparameters. After each of these subparameters, insert the matrix data in the appropriate format (these formats are described in detail below).

*Other Notes:* The resistance, inductance, and capacitance matrices are also referred to as “RLC matrices” within this specification.

When measuring the entries of the RLC matrices, either with laboratory equipment or field-solver software, currents are defined as ENTERING the pins of the package from the board (General Syntax Rule #11). The corresponding voltage drops are to be measured with the current pointing “in” to the “+” sign and “out” of the “-” sign.



1. - Package Matrix Voltage Polarities and Current Directions

It is important to observe this convention in order to get the correct signs for the mutual inductances and resistances.

*Example:*

[Resistance Matrix] Banded\_matrix

[Inductance Matrix] Sparse\_matrix

[Capacitance Matrix] Full\_matrix

RLC Matrix Notes:

For each [Resistance Matrix], [Inductance Matrix], or [Capacitance Matrix], a different format can be used for the data. The choice of formats is provided to satisfy different simulation accuracy and speed requirements.

Also, there are many packages in which the resistance matrix can have no coupling terms at all. In this case, the most concise format (Banded\_matrix) can be used.

There are two different ways to extract the coefficients that are reported in the capacitance and inductance matrices. For the purposes of this specification, the coefficients reported in the capacitance matrices shall be the “electrostatic induction coefficients” or “Maxwell’s capacitances”. The Maxwell capacitance Kij is defined as the charge induced on conductor “j” when conductor “i” is held at 1 volt and all other conductors are held at zero volts. Note that Kij (when i /= j) will be a negative number and should be entered as such. Likewise, for the inductance matrix the coefficients for Lij are defined as the voltage induced on conductor “j” when conductor “i”’s current is changed by 1 amp/sec and all other conductors have no current change.

One common aspect of all the different formats is that they exploit the symmetry of the matrices they describe. This means that the entries below the main diagonal of the matrix are identical to the corresponding entries above the main diagonal. Therefore, only roughly one-half of the matrix needs to be described. By convention, the main diagonal and the UPPER half of the matrix are provided.

In the following text, we use the notation [I, J] to refer to the entry in row I and column J of the matrix. Note that I and J are allowed to be alphanumeric strings as well as integers. An ordering of these strings is defined in the [Pin Numbers] section. In the following text, “Row 1” means the row corresponding to the first pin.

Also note that the numeric entries of the RLC matrices are standard IBIS floating point numbers. As such, it is permissible to use multiplier “suffix” notation. Thus, an entry of the C matrix could be given as 1.23e-12 or as 1.23p or 1.23pF.

Full\_matrix:

When the Full\_matrix format is used, the couplings between every pair of elements are specified explicitly. Assume that the matrix has N rows and N columns. The Full\_matrix is specified one row at a time, starting with Row 1 and continuing down to Row N.

Each new row is identified with the Row keyword.

Keyword: [Row]

*Required:* Yes

*Description:* Indicates the beginning of a new row of the matrix.

*Usage Rules:* The argument must be one of the pin names listed under the [Pin Numbers] keyword.

*Example:*

[Row] 3

Following a [Row] keyword is a block of numbers that represent the entries for that row. Suppose that the current row is number M. Then the first number listed is the diagonal entry, [M,M]. Following this number are the entries of the upper half of the matrix that belong to row M: [M, M+1], [M, M+2], ... up to [M,N].

For even a modest-sized package, this data will not all fit on one line. You can break the data up with new-line characters so that the 120 character line length limit is observed.

An example: suppose the package has 40 pins and that we are currently working on Row 19. There is 1 diagonal entry, plus 40 - 19 = 21 entries in the upper half of the matrix to be specified, for 22 entries total. The data might be formatted as follows:

[Row] 19

5.67e-9 1.1e-9 0.8e-9 0.6e-9 0.4e-9 0.2e-9 0.1e-9 0.09e-9

8e-10 7e-10 6e-10 5e-10 4e-10 3e-10 2e-10 1e-10

9e-11 8e-11 7e-11 6e-11 5e-11 4e-11

In the above example, the entry 5.67e-9 is on the diagonal of row 19.

Observe that Row 1 always has the most entries, and that each successive row has one fewer entry than the last; the last row always has just a single entry.

Banded\_matrix:

A Banded\_matrix is one whose entries are guaranteed to be zero if they are farther away from the main diagonal than a certain distance, known as the “bandwidth.” Let the matrix size be N x M, and let the bandwidth be B. An entry [I,J] of the matrix is zero if:

| I - J | > B

where |.| denotes the absolute value.

The Banded\_matrix is used to specify the coupling effects up to B pins on either side. Two variations are supported. One allows for the coupling to circle back on itself. This is technically a simple form of a bordered block diagonal matrix. However, its data can be completely specified in terms of a Banded\_matrix for an N x M matrix consisting of N rows and M = N + B columns. The second variation is just in terms of an N x N matrix where no circle back coupling needs to be specified.

The bandwidth for a Banded\_matrix must be specified using the [Bandwidth] keyword.

*Keyword:* [Bandwidth]

*Required:* Yes (for Banded\_matrix matrices only)

*Description:* Indicates the bandwidth of the matrix.

*Usage Rules:* The bandwidth field must be a non-negative integer. This keyword must occur after the [Resistance Matrix], etc., keywords, and before the matrix data is given.

*Example:*

[Bandwidth] 10

Specify the banded matrix one row at a time, starting with row 1 and working up to higher rows. Mark each row with the [Row] keyword, as above. As before, symmetry is exploited: do not provide entries below the main diagonal.

For the case where coupling can circle back on itself, consider a matrix of N pins organized into N rows, 1 ... N, and M columns, 1 ... N, 1 ... B. The first row only needs to specify the entries [1,1] through [1,1+B] since all other entries are guaranteed to be zero. The second row will need to specify the entries [2,2] through [2,2+B], and so on. For row K, the entries [K,K] through [K,K+B] are given when K + B is less than or equal to the size of the matrix N. When K + B exceeds N, the entries in the last columns, 1 ... B, specify the coupling to the first rows. For row K, the entries [K,K] ... [K,N] [K,1] ... [K,R] are given where R = mod(K + B - 1, N) + 1. All rows will contain B + 1 entries. To avoid redundant entries, the bandwidth is limited to B <= int((N - 1) / 2).

For the case where coupling does not circle back on itself, the process is modified. Only N columns need to be considered. When K + B finally exceeds the size of the matrix N, the number of entries in each row starts to decrease; the last row (row N) has only 1 entry. This construction constrains the bandwidth to B < N.

As in the Full\_matrix, if all the entries for a particular row do not fit into a single 120-character line, the entries can be broken across several lines.

It is possible to use a bandwidth of 0 to specify a diagonal matrix (a matrix with no coupling terms.) This is sometimes useful for resistance matrices.

Sparse\_matrix:

A Sparse\_matrix is expected to consist mostly of zero-valued entries, except for a few nonzeros. Unlike the Banded\_matrix, there is no restriction on where the nonzero entries can occur. This feature is useful in certain situations, such as for Pin Grid Arrays (PGAs).

As usual, symmetry can be exploited to reduce the amount of data by eliminating from the matrix any entries below the main diagonal.

An N x N Sparse\_matrix is specified one row at a time, starting with row 1 and continuing down to row N. Each new row is marked with the [Row] keyword, as in the other matrix formats.

Data for the entries of a row is given in a slightly different format, however. For the entry [I, J] of a row, it is necessary to explicitly list the name of pin J before the value of the entry is given. This specification serves to indicate to the parser where the entry is put into the matrix.

The proper location is not otherwise obvious because of the lack of restrictions on where nonzeros can occur. Each (Index, Value) pair is listed upon a separate line. An example follows. Suppose that row 10 has nonzero entries [10,10], [10,11], [10,15], and [10,25]. The following row data would be provided:

[Row] 10

| Index Value

10 5.7e-9

11 1.1e-9

15 1.1e-9

25 1.1e-9

Note that each of the column indices listed for any row must be greater than or equal to the row index, because they always come from the upper half of the matrix. When alphanumeric pin names are used, special care must be taken to ensure that the ordering defined in the [Pin Numbers] section is observed.

With this convention, please note that the Nth row of an N x N matrix has just a single entry (the diagonal entry).

*Keyword:* [End Package Model]

*Required:* Yes

*Description:* Marks the end of a package model description.

*Usage Rules:* This keyword must come at the end of each complete package model description.

Optionally, add a comment after the [End Package Model] keyword to clarify which package model has just ended. For example,

[Define Package Model] My\_Model

|

| ... content of model ...

|

[End Package Model] | end of My\_Model

*Example:*

[End Package Model]

Package Model Example

The following is an example of a package model file following the package modeling specifications. For the sake of brevity, an 8-pin package has been described. For purposes of illustration, each of the matrices is specified using a different format.

*Example:*

[IBIS Ver] 5.1

[File Name] example.pkg

[File Rev] 0.1

[Date] August 24, 2012

[Source] Quality Semiconductors. Data derived from Helmholtz Inc.'s

field solver using 3-D model from Acme Packaging.

[Notes] Example of couplings in packaging

[Disclaimer] The models given below may not represent any physically

realizable 8-pin package. They are provided solely for the

purpose of illustrating the .pkg file format.

|

|=============================================================================

|

[Define Package Model] QS-SMT-cer-8-pin-pkgs

[Manufacturer] Quality Semiconductors Ltd.

[OEM] Acme Package Co.

[Description] 8-Pin ceramic SMT package

[Number Of Pins] 8

|

[Pin Numbers]

1

2

3

4

5

6

7

8

|

[Model Data]

|

| The resistance matrix for this package has no coupling

|

[Resistance Matrix] Banded\_matrix

[Bandwidth] 0

[Row] 1

10.0

[Row] 2

15.0

[Row] 3

15.0

[Row] 4

10.0

[Row] 5

10.0

[Row] 6

15.0

[Row] 7

15.0

[Row] 8

10.0

|

| The inductance matrix has loads of coupling

|

[Inductance Matrix] Full\_matrix

[Row] 1

3.04859e-07 4.73185e-08 1.3428e-08 6.12191e-09

1.74022e-07 7.35469e-08 2.73201e-08 1.33807e-08

[Row] 2

3.04859e-07 4.73185e-08 1.3428e-08 7.35469e-08

1.74022e-07 7.35469e-08 2.73201e-08

[Row] 3

3.04859e-07 4.73185e-08 2.73201e-08 7.35469e-08

1.74022e-07 7.35469e-08

[Row] 4

3.04859e-07 1.33807e-08 2.73201e-08 7.35469e-08

1.74022e-07

[Row] 5

4.70049e-07 1.43791e-07 5.75805e-08 2.95088e-08

[Row] 6

4.70049e-07 1.43791e-07 5.75805e-08

[Row] 7

4.70049e-07 1.43791e-07

[Row] 8

4.70049e-07

|

| The capacitance matrix has sparse coupling

|

[Capacitance Matrix] Sparse\_matrix

[Row] 1

1 2.48227e-10

2 -1.56651e-11

5 -9.54158e-11

6 -7.15684e-12

[Row] 2

2 2.51798e-10

3 -1.56552e-11

5 -6.85199e-12

6 -9.0486e-11

7 -6.82003e-12

[Row] 3

3 2.51798e-10

4 -1.56651e-11

6 -6.82003e-12

7 -9.0486e-11

8 -6.85199e-12

[Row] 4

4 2.48227e-10

7 -7.15684e-12

8 -9.54158e-11

[Row] 5

5 1.73542e-10

6 -3.38247e-11

[Row] 6

6 1.86833e-10

7 -3.27226e-11

[Row] 7

7 1.86833e-10

8 -3.38247e-11

[Row] 8

8 1.73542e-10

|

[End Model Data]

[End Package Model]

|

# Electrical Board Description

**INTRODUCTION**:

A “board level component” is the generic term to be used to describe a printed circuit board (PCB) or substrate which can contain components or even other boards, and which can connect to another board through a set of user visible pins. The electrical connectivity of such a board level component is referred to as an “Electrical Board Description”. For example, a SIMM module is a board level component that is used to attach several DRAM components on the PCB to another board through edge connector pins. An electrical board description file (a .ebd file) is defined to describe the connections of a board level component between the board pins and its components on the board.

A fundamental assumption regarding the electrical board description is that the inductance and capacitance parameters listed in the file are derived with respect to well-defined reference plane(s) within the board. Also, this current description does not allow one to describe electrical (inductive or capacitive) coupling between paths. It is recommended that if coupling is an issue, then an electrical description be extracted from the physical parameters of the board.

What is, and is not, included in an Electrical Board Description is defined by its boundaries. For the definition of the boundaries, see the Description section under the [Path Description] Keyword.

Usage Rules:

A .ebd file is intended to be a stand-alone file, not referenced by or included in any .ibs or .pkg file. Electrical Board Descriptions are stored in a file whose name looks like <filename>.ebd, where <filename> must conform to the naming rules given in Section 3 of this specification. The .ebd extension is mandatory.

Contents:

An .ebd file is structured similar to a standard .ibs file. It must contain the following keywords, as defined in IBIS: [IBIS Ver], [File Name], [File Rev], and [End]. It may also contain the following optional keywords: [Comment Char], [Date], [Source], [Notes], [Disclaimer], and [Copyright]. The actual board description is contained between the keywords [Begin Board Description] and [End Board Description], and includes the keywords listed below:

[Begin Board Description]

[Manufacturer]

[Number Of Pins]

[Pin List]

[Path Description]

[Reference Designator Map]

[End Board Description]

More than one [Begin Board Description]/[End Board Description] keyword pair is allowed in a .ebd file.

**KEYWORD DEFINITIONS:**

*Keyword:* [Begin Board Description]

*Required:* Yes

*Description:* Marks the beginning of an Electrical Board Description.

*Usage Rules:* The keyword is followed by the name of the board level component. If the .ebd file contains more than one [Begin Board Description] keyword, then each name must be unique. The length of the component name must not exceed 40 characters in length, and blank characters are allowed. For every [Begin Board Description] keyword there must be a matching [End Board Description] keyword.

*Example:*

[Begin Board Description] 16Meg X 8 SIMM Module

*Keyword:* [Manufacturer]

*Required:* Yes

*Description:* Declares the manufacturer of the components(s) that use this .ebd file.

*Usage Rules:* Following the keyword is the manufacturer’s name. It must not exceed 40 characters, and can include blank characters. Each manufacturer must use a consistent name in all .ebd files.

*Example:*

[Manufacturer] Quality SIMM Corp.

*Keyword:* [Number Of Pins]

*Required:* Yes

*Description:* Tells the parser the number of pins to expect. Pins are any externally accessible electrical connection to the component.

*Usage Rules:* The field must be a positive decimal integer. Note: The simulator must not limit the Number Of Pins to any value less than 1,000. The [Number Of Pins] keyword must be positioned before the [Pin List] keyword.

*Example:*

[Number Of Pins] 128

*Keyword:* [Pin List]

*Required:* Yes

*Description:* Tells the parser the pin names of the user accessible pins. It also informs the parser which pins are connected to power and ground.

*Sub-Params:* signal\_name

*Usage Rules:* Following the [Pin List] keyword are two columns. The first column lists the pin name while the second lists the data book name of the signal connected to that pin. There must be as many pin\_name/signal\_name rows as there are pins given by the preceding [Number Of Pins] keyword. Pin names must be the alphanumeric external pin names of the part. The pin names cannot exceed eight characters in length. Any pin associated with a signal name that begins with “GND” or “POWER” will be interpreted as connecting to the boards ground or power plane. In addition, NC is a legal signal name and indicates that the Pin is a “no connect”. As per the IBIS standard “GND,” “POWER,” and “NC” are case insensitive.

*Example:*

| A SIMM Board Example:

|

[Pin List] signal\_name

A1 GND

A2 data1

A3 data2

A4 POWER5 | This pin connects to 5 V

A5 NC | a no connect pin

| .

| .

A22 POWER3.3 | This pin connects to 3.3 V

B1 casa

| .

| .

|etc.

*Keyword:* [Path Description]

*Required:* Yes

*Description:* This keyword allows the user to describe the connection between the user accessible pins of a board level component and other pins or pins of the ICs mounted on that board. Each pin to node connection is divided into one or more cascaded “sections,” where each section is described in terms of its L/R/C per unit length. The Fork and Endfork subparameters allow the path to branch to multiple nodes, or another pin. A path description is required for each pin whose signal name is not “GND,” “POWER,” or “NC.”

Board Description and IC Boundaries:

In any system, each board level component interfaces with another board level component at some boundary. Every electrical board description must contain the components necessary to represent the behavior of the board level component being described within its boundaries. The boundary definition depends upon the board level component being described.

For CARD EDGE CONNECTIONS such as a SIMM or a PC Daughter Card plugged into a SIMM Socket or Edge Connector, the boundary should be at the end of the board card edge pads as they emerge from the connector.

For any THROUGH-HOLE MOUNTED COMPONENT, the boundary will be at the surface of the board on which the component is mounted.

SURFACE MOUNTED COMPONENT models end at the outboard end of their recommended surface mount pads.

If the board level component contains an UNMATED CONNECTOR, the unmated connector will be described in a separate file, with its boundaries being as described above for the through-hole or surface mounted component.

*Sub-Params:* Len, L, R, C, Fork, Endfork, Pin, Node

*Usage Rules:* Each individual connection path (user pin to node(s)) description begins with the [Path Description] keyword and a path name, followed by the subparameters used to describe the path topology and the electrical characteristics of each section of the path. The path name must not exceed 40 characters, blanks are not allowed, and each occurrence of the [Path Description] keyword must be followed by a unique path name. Every signal pin (pins other than POWER, GND or NC) must appear in one and only one path description per [Begin Board Description]/[End Board Description] pair. Pin names do not have to appear in the same order as listed in the [Pin List] table. The individual subparameters are broken up into those that describe the electrical properties of a section, and those that describe the topology of a path.

Section Description Subparameters:

The Len, L, R, and C subparameters specify the length, the series inductance, resistance, and the capacitance to ground of each section in a path description.

Len The physical length of a section. Lengths are given in terms of arbitrary “units”. Any non-zero length requires that the parameters that follow must be interpreted as distributed elements by the simulator.

L The series inductance of a section, in terms of henries/unit length. For example, if the total inductance of a section is 3.0 nH and the length of the section is 2 “units”, the inductance would be listed as L = 1.5nH (i.e., 3.0 / 2).

C The capacitance to ground of a section, in terms of farads/unit length.

R The series DC (ohmic) resistance of a section, in terms of ohms/unit length.

Topology Description Subparameters:

The Fork and Endfork subparameters denote branches from the main pin-to-node or pin-to-pin connection path. The Node subparameter is used to reference the pin of a component or board as defined in a .ibs or .ebd file. The Pin subparameter is used to indicate the point at which a path connects to a user visible pin.

Fork This subparameter indicates that the sections following (up to the Endfork subparameter) are part of a branch off of the main connection path. This subparameter has no arguments.

Endfork This subparameter indicates the end point of a branch. For every Fork subparameter there must be a corresponding Endfork subparameter. As with the Fork subparameter, the Endfork subparameter has no arguments. The Fork and Endfork parameters must appear on separate lines.

Node reference\_designator.pin  
This subparameter is used when the connection path connects to a pin of another, externally defined component. The arguments of the Node subparameter indicate the pin and reference designator of the external component. The pin and reference designator portions of the argument are separated by a period (“.”). The reference designator is mapped to an external component description (another .ebd file or .ibs file) by the [Reference Designator Map] Keyword. Note that a Node MUST reference a model of a passive or active component. A Node is not an arbitrary connection point between two elements or paths.

Pin This subparameter is used to mark the point at which a path description connects to a user accessible pin. Every path description must contain at least one occurrence of the Pin subparameter. It may also contain the reserved word NC. The value of the Pin subparameter must be one of the pin names listed in the [Pin List] section.

Note: The reserved word NC can also be used in path descriptions in a similar manner as the subparameters in order to terminate paths. This usage is optional.

Using The Subparameters to Describe Paths:

A section description begins with the Len subparameter and ends with the slash (/) character. The value of the Len, L, R, and C subparameters and the subparameter itself are separated by an equals sign (=); white space around the equals sign is optional. The Fork, Endfork, Node, and Pin subparameters are placed between section descriptions (i.e., between the concluding slash of one section and the “Len” parameters that starts another). The arguments of the Pin and Node subparameter are separated by white space.

Specifying a Len or L/R/C value of zero is allowed. If Len = 0 is specified, then the L/R/C values are the total for that section. If a non-zero length is specified, then the total L/R/C for a section is calculated by multiplying the value of the Len subparameter by the value of the L, R, or C subparameter. However, as noted below, if a non-zero length is specified, that section MUST be interpreted as distributed elements.

Legal Subparameter Combinations for Section Descriptions:

A) Len, and one or more of the L, R and C subparameters. If the Len subparameter is given as zero, then the L/R/C subparameters represent lumped elements. If the Len subparameter is non-zero, then the L/R/C subparameters represent distributed elements and both L and C must be specified, R is optional. The segment Len ..../ must not be split; the whole segment must be on one line.

B) The first subparameter following the [Path Description] keyword must be “Pin”, followed by one or more section descriptions. The path description can terminate in a Node, another pin or the reserved word, NC. However, NC may be optionally omitted.

Dealing With Series Elements:

A discrete series R or L component can be included in a path description by defining a section with Len=0 and the proper R or L value. A discrete series component can also be included in a path description by writing node statements that reference the same component. This can be done as two back to back node statements for a series component within a single [Path Description]. It is also allowed to insert a series component between two branches of a single [Path Description], or even between two separate [Path Description]s (see the examples below).

When a series component is modeled with node statements and reference designator.pin arguments, the references pin models can be Series or Series\_switch. The following models are supported: [R Series], [L Series], [C Series], [Rl Series], [Lc Series], [Rc Series], [Series Current], and [Series MOSFET].

*Examples:*

An Example Path for a SIMM Module (see Figure 32):

|

[Path Description] CAS\_2

Pin J25

Len = 0.5 L=8.35n C=3.34p R=0.01 /

Node u21.15

Len = 0.5 L=8.35n C=3.34p R=0.01 /

Node u22.15

Len = 0.5 L=8.35n C=3.34p R=0.01 /

Node u23.15



1. - SIMM Package Path Example

A Description Using The Fork and Endfork Subparameters (see Figure 33):

|

[Path Description] PassThru1

Pin B5

Len = 0 L=2.0n /

Len = 2.1 L=6.0n C=2.0p /

Fork

Len = 1.0 L = 1.0n C= 2.0p /

Node u23.16

Endfork

Len = 1.0 L = 6.0n C=2.0p /

Pin A5

|



1. - Fork and Endfork in [Path Description]

A Description Including a Discrete Series Element (see Figure 34):

|

[Path Description] sig1

Pin B27

Len = 0 L=1.6n /

Len = 1.5 L=6.0n C=2.0p /

Node R2.1

Node R2.2

Len = 0.25 L=6.0n C=2.0p /

Node U25.6



1. – Discrete Series Element in [Path Description]

A path including series passive components (C17, R21) between branches forming a differential termination (see Figure 35):

[Path Description] CLK

Pin 137

Len=1.1 L=1n C=0.4p /

Node C17.1 | Pin 1 of Series C17

Len=1.2 L=1n C=0.4p /

Node R21.1 | Series R21 Pin 1 and 2 connections

Node R21.2

Len=1.3 L=1n C=0.4p /

Node C17.2 | Pin 2 of Series C17

Len=1.4 L=1n C=0.4p

Pin 138



1. – Series Passive Components as Differential Termination

Two paths connected by series resistors (R8, R9) used as differential termination between components:

[Path Description] DP+

Pin 20

Len=1 L=1n C=0.4p /

Fork

Len=1.1 L=1n C=0.4p /

Fork

Node P8.D7

Endfork

Len=1.2 L=1n C=0.4p /

Node R8.1 | Pin 1 of Series R8

Endfork

Len=1.3 L=1n C=0.4p /

Fork

Len=1.4 L=1n C=0.4p /

Node P8.D5

Endfork

Len=1.5 L=1n C=0.4p /

Node R9.1 | Pin 1 of Series R9

Other path(s):

[Path Description] DP-

Pin 22

Len=1 L=1n C=0.4p /

Fork

Len=1.1 L=1n C=0.4p /

Fork

Node Q8.D7

Endfork

Len=1.2 L=1n C=0.4p /

Node R8.2 | Pin 2 of Series R8

Endfork

Len=1.3 L=1n C=0.4p /

Fork

Len=1.4 L=1n C=0.4p /

Node Q8.D5

Endfork

Len=1.5 L=1n C=0.4p /

Node R9.2 | Pin 2 of Series R9



1. – Paths Connected by Series Resistors as Differential Terminators

*Keyword:* [Reference Designator Map]

*Required:* Yes, if any of the path descriptions use the Node subparameter

*Description:* Maps a reference designator to a component or electrical board description contained in a .ibs or .ebd file.

*Usage Rules:* The [Reference Designator Map] keyword must be followed by a list of all of the reference designators called out by the Node subparameters used in the various path descriptions. Each reference designator is followed by the name of the .ibs or .ebd file containing the electrical description of the component or board, then the name of the component itself as given by the .ibs or .ebd file’s [Component] or [Begin Board Description] keyword respectively. The reference designator, file name and component name terms are separated by white space. By default the .ibs or .ebd files are assumed to exist in the same directory as the calling .ebd file. It is legal for a reference designator to point to a component that is contained in the calling .ebd file.

The reference designator is limited to ten characters.

*Example:*

[Reference Designator Map]

|

| External Part References:

|

| Ref Des File name Component name

u23 pp100.ibs Processor

u24 simm.ebd 16Meg X 36 SIMM Module

u25 ls244.ibs NoName 74LS244a

u26 r10K.ibs My\_10K\_Pullup

*Keyword:* [End Board Description]

*Required:* Yes

*Description:* Marks the end of an Electrical Interconnect Description.

*Usage Rules:* This keyword must come at the end of each complete electrical interconnect model description.

Optionally, a comment may be added after the [End Electrical Description] keyword to clarify which board model has ended.

*Example:*

[End Board Description] | End: 16Meg X 8 SIMM Module

Keyword: [End]

*Required:* Yes

*Description:* Defines the end of the .ibs, .pkg, or .ebd file.

*Example:*

[End]

# Notes on Data Derivation Method

This section explains how data values are derived. It describes certain assumed parameter and table extraction conditions if they are not explicitly specified. It also describes the allocation of data into the “typ,” “min,” and “max” columns under variations of voltage, temperature, and process.

The required “typ” column for all data represents typical operating conditions. For most [Model] keyword data, the “min” column describes slow, weak performance, and the “max” column describes the fast, strong performance. It is permissible to use slow, weak components or models to derive the data for the “min” column, and to use fast, strong components or models to derive the data in the “max” columns under the corresponding voltage and temperature derating conditions for these columns. It is also permissible to use typical components or models derated by voltage and temperature and optionally apply proprietary “X%” and “Y%” factors described later for further derating. This methodology has the nice feature that the data can be derived either from semiconductor vendor proprietary models, or typical component measurement over temperature/voltage.

The voltage and temperature keywords and optionally the process models control the conditions that define the “typ,” “min,” and “max” column entries for all I-V table keywords [Pulldown], [Pullup], [GND Clamp], and [POWER Clamp]; all [Ramp] subparameters dV/dt\_r and dV/dt\_f; and all waveform table keywords and subparameters [Rising Waveform], [Falling Waveform], V\_fixture, V\_fixture\_min, and V\_fixture\_max.

The voltage keywords that control the voltage conditions are [Voltage Range], [Pulldown Reference], [Pullup Reference], [GND Clamp Reference], and [POWER Clamp Reference]. The entries in the “min” columns contain the smallest magnitude voltages, and the entries in the “max” columns contain the largest magnitude voltages.

The optional [Temperature Range] keyword will contain the temperature which causes or amplifies the slow, weak conditions in the “min” column and the temperature which causes or amplifies the fast, strong conditions in the “max” column. Therefore, the “min” column for [Temperature Range] will contain the lowest value for bipolar models (TTL and ECL) and the highest value for CMOS models. Default values described later are assumed if temperature is not specified.

The “min” and “max” columns for all remaining keywords and subparameters will contain the smallest and largest magnitude values. This applies to the [Model] subparameter C\_comp as well, even if the correlation to the voltage, temperature, and process variations are known, because information about such correlation is not available in all cases.

C\_comp is considered an independent variable. This is because C\_comp includes bonding pad capacitance, which does not necessarily track fabrication process variations. The conservative approach to using IBIS data will associate large C\_comp values with slow, weak models, and the small C\_comp values with fast, strong models.

The default temperatures under which all I-V tables are extracted are provided below. The same defaults also are stated for the [Ramp] subparameters, but they also apply for the waveform keywords.

The stated voltage ranges for I-V tables cover the most common, single supply cases. When multiple supplies are specified, the voltages shall extend similarly to values that handle practical extremes in reflected wave simulations.

For the [Ramp] subparameters, the default test load and voltages are provided. However, the test load can be entered directly by the R\_load subparameter. The allowable test loads and voltages for the waveform keywords are stated by required and optional subparameters; no defaults are needed. Even with waveform keywords, the [Ramp] keyword continues to be required so that the IBIS model remains functional in situations which do not support waveform processing.

The following discussion lists test details and default conditions.

1) I-V Tables:

I-V tables for CMOS models:

typ = typical voltage, typical temp deg C, typical process

min = minimum voltage, max temp deg C, typical process, minus “X%”

max = maximum voltage, min temp deg C, typical process, plus “X%”

I-V tables for bipolar models:

typ = typical voltage, typical temp deg C, typical process

min = minimum voltage, min temp deg C, typical process, minus “X%”

max = maximum voltage, max temp deg C, typical process, plus “X%”

Nominal, min, and max temperature are specified by the semiconductor vendor. The default range is 50 deg C nom, 0 deg C min, and 100 deg C max temperatures.

X% should be statistically determined by the semiconductor vendor based on numerous fab lots, test chips, process controls, etc. The value of X need not be published in the .ibs file, and may decrease over time as data on the I/O buffers and silicon process increases.

Temperatures are junction temperatures.

2) Voltage Ranges:

Points for each table must span the voltages listed in Table 16.

Table – Voltage Ranges

|  |  |  |
| --- | --- | --- |
| **Table** | **Low Voltage** | **High Voltage** |
| [Pulldown] | GND – POWER | POWER + POWER |
| [Pullup] | GND – POWER | POWER + POWER |
| [GND Clamp] | GND – POWER | GND + POWER |
| [POWER Clamp] | POWER | POWER + POWER |
| [Series Current] | GND – POWER | GND + POWER |
| [Series MOSFET] | GND | GND + POWER |

As described in the [Pulldown Reference] keyword section, the I-V tables of the [Pullup] and the [POWER Clamp] structures are “Vcc relative”, using the equation:

*Vtable = Vcc - Voutput*

For example, a model with a 5 V power supply voltage should be characterized between (0 - 5) = -5 V and (5 + 5) = 10 V; and a model with a 3.3 V power supply should be characterized between (0 - 3.3) = -3.3 V and (3.3 + 3.3) = 6.6 V for the [Pulldown] table.

When tabulating output data for ECL type models, the voltage points must span the range of Vcc to Vcc - 2.2 V. This range applies to both the [Pullup] and [Pulldown] tables. Note that this range applies ONLY when characterizing an ECL output.

These voltage ranges must be spanned by the IBIS data. Data derived from lab measurements may not be able to span these ranges as such and so may need to be extrapolated to cover the full range. This data must not be left for the simulator to provide.

3) Ramp Rates:

The following steps assume that the default load resistance of 50 ohms is used. There may be models that will not drive a load of only 50 ohms into any useful level of dynamics. In these cases, use the semiconductor vendor’s suggested (nonreactive) load and add the load subparameter to the [Ramp] specification.

The ramp rate does not include packaging but does include the effects of the C\_comp parameter; it is the intrinsic output stage rise and fall time only.

The ramp rates (listed in AC characteristics below) should be derived as follows:

1. If starting with the silicon model, remove all packaging. If starting with a packaged model, perform the measurements as outlined below. Then use whatever techniques are appropriate to derive the actual, unloaded rise and fall times.
2. If: The Model\_type is one of the following: Output, I/O, or 3-state (not open or ECL types);

Then: Attach a 50 ohm resistor to GND to derive the rising edge ramp. Attach a 50 ohm resistor to POWER to derive the falling edge ramp.

If: The Model\_type is Output\_ECL, I/O\_ECL, 3-state\_ECL;

Then: Attach a 50 ohm resistor to the termination voltage (Vterm = VCC - 2 V). Use this load to derive both the rising and falling edges.

If: The Model\_type is either an Open\_sink type or Open\_drain type;

Then: Attach either a 50 ohm resistor or the semiconductor vendor suggested termination resistance to either POWER or the suggested termination voltage. Use this load to derive both the rising and falling edges.

If: The Model\_type is an Open\_source type;

Then: Attach either a 50 ohm resistor or the semiconductor vendor suggested termination resistance to either GND or the suggested termination voltage. Use this load to derive both the rising and falling edges.

1. Due to the resistor, output swings will not make a full transition as expected. However the pertinent data can still be collected as follows:
2. Determine the 20% to 80% voltages of the 50 ohm swing.
3. Measure this voltage change as “dV”.
4. Measure the amount of time required to make this swing “dt”.
5. Post the value as a ratio “dV/dt”. The simulator extrapolates this value to span the required voltage swing range in the final model.
6. Typ, Min, and Max must all be posted, and are derived at the same extremes as the I-V tables, which are:

Ramp rates for CMOS models:

typ = typical voltage, typical temp deg C, typical process

min = minimum voltage, max temp deg C, typical process, minus “Y%”

max = maximum voltage, min temp deg C, typical process, plus “Y%”

Ramp rates for bipolar models:

typ = typical voltage, typical temp deg C, typical process

min = minimum voltage, min temp deg C, typical process, minus “Y%”

max = maximum voltage, max temp deg C, typical process, plus “Y%”

where nominal, min, and max temp are specified by the semiconductor vendor. The preferred range is 50 deg C nom, 0 deg C min, and 100 deg C max temperatures.

Note that the derate factor, “Y%”, may be different than that used for the I-V table data. This factor is similar to the X% factor described above. As in the case of I-V tables, temperatures are junction temperatures.

1. During the I-V measurements, the driving waveform should have a rise/fall time fast enough to avoid thermal feedback. The specific choice of sweep time is left to the modeling engineer.

4) Transit Time Extractions:

The transit time parameter is indirectly derived to be the value that produces the same effect as that extracted by the reference measurement or reference simulation. See Figure 37.

The test circuit consists of the following:

1. A pulse source (10 ohms, 1 ns at full duration ramp) or equivalent and transitioning between Vcc and 0 V,
2. A 50 ohm, 1 ns long trace or transmission line,
3. A 500 ohm termination to the ground clamp reference voltage for TTgnd extraction and to the power clamp reference voltage for TTpower extraction (to provide a convenient, minimum loading 450 ohm - 50 ohm divider for high-speed sampling equipment observation of the component denoted as the device under test), and
4. The device under test (DUT).



1. - Example of TTgnd Extraction Setup

The TTgnd extraction will be done only if a [GND Clamp] table exists. A high to low transition that produces a positive “glitch,” perhaps several nanoseconds later, indicates a stored charge in the ground clamp circuit. The test circuit is simulated using the complete IBIS model with C\_comp and the Ct model defined under the [TTgnd] and [TTpower] keywords. An effective TTgnd value that produces a “glitch” with the same delay is extracted.

Similarly, the TTpower extraction will be done only if a [POWER Clamp] table exists. A low to high transition that produces a negative “glitch,” perhaps several nanoseconds later, indicates a stored charge in the power clamp circuit. An effective TTpower value that produces a glitch with the same delay is extracted.

It is preferred to do the extractions with the package parameters removed. However, if the extraction is done from measurements, then the package model should be included in the IBIS based simulation.

5) Series MOSFET Table Extractions:

An extraction circuit is set up according to Figure 38. The switch is configured into the “On” state. This assumes that the Vcc voltage will be applied to the gate by internal logic. Designate one pin of the switch as the source node, and the other pin as the drain node. The Table Currents designated as Ids are derived directly as a function of the Vs voltage at the source node as Vs is varied from 0 to Vcc. This voltage is entered as a Vgs value as a consequence of the relationship Vtable = Vgs = Vcc - Vs. Vds is held constant by having a fixed voltage Vds between the drain and source nodes. Note, Vds > 0 V. The current flowing into the drain is tabulated in the table for the corresponding Vs points.



1. - Example of Series MOSFET Table Extraction

It is expected that this data will be created from semiconductor vendor proprietary silicon models, and later correlated with actual component measurement.

# AMI Executable Model File Programming Guide

This section is organized as an interface and programming guide for the executable model file referenced by the [Algorithmic Model] keyword described in Section 6C. Section 10A serves as a reference document for the AMI parameter definition file structure for model makers and software engineers.

## Overview

The executable model file of a Serializer-Deserializer (SERDES) transmitter or receiver contains up to three functions: “AMI\_Init”, “AMI\_GetWave” and “AMI\_Close”. The interfaces to these functions are designed to support three different phases of the simulation process: initialization, simulation of a segment of time, and termination of the simulation.

These functions (AMI\_Init, AMI\_GetWave and AMI\_Close) should all be supplied in a single executable model file, and their names and signatures must be as described in this section. If they are not supplied in the executable model file named by the Executable sub-parameter, then they shall be ignored. This is acceptable so long as:

1. The entire functionality of the model is supplied in the executable model file.
2. All termination actions required by the model are included in the executable model file.

The three functions can be included in the executable model file in one of the following two combinations:

Case 1: Executable model file has AMI\_Init, AMI\_GetWave and AMI\_Close.

Case 2: Executable model file has AMI\_Init and AMI\_Close.

Please note that the functions AMI\_Init and AMI\_Close are always required.

The interfaces to these functions are defined from three different perspectives. In addition to specifying the signature of the functions to provide a software coding perspective, anticipated application scenarios provide a functional and dynamic execution perspective, and a specification of the software infrastructure provides a software architecture perspective. Each of these perspectives is required to obtain interoperable software models.

Notes:

1. Throughout this section, terms “long”, “double” etc. are used to indicate the data types in the C programming language as published in ISO/IEC 9899-1999.
2. Throughout this section, text strings inside the symbols “<” and “>” should be considered to be supplied or substituted by the model maker.  Text strings inside “<” and “>” are not reserved and can be replaced.

## Application Scenarios

The next two sections provide an overview of the two simulation types supported for algorithmic models by IBIS. Statistical simulations require that the algorithm in the executable model file is linear and time-invariant (LTI). Time domain simulations do not have this requirement. Therefore executable model files used in time domain simulations may also contain non-linear and/or time-variant (non-LTI) algorithms.

System simulations will commonly involve a transmitter (Tx) and a receiver (Rx) executable model file, each of which may perform filtering in the AMI\_Init function, the AMI\_GetWave function, or both (i.e., a "dual" algorithmic model). In the case of a "dual" algorithmic model, the filtering functionality in the AMI\_Init and AMI\_GetWave functions are each intended to be independent representations of the device’s equalization. Users of a dual model can elect to use either the AMI\_Init or AMI\_GetWave filtering functionality, but not combine both simultaneously.

While the primary purpose of the AMI\_Init function is to perform the required initialization steps, it may also include LTI signal processing algorithms. Therefore, statistical simulations may be performed using the AMI\_Init function alone.

Even though time domain simulations may also be performed with the LTI AMI\_Init and/or LTI AMI\_GetWave functions, AMI\_GetWave functions containing non-LTI algorithms may only be simulated in the time domain.

### Statistical simulations

1. From the system netlist, the EDA tool determines that a given buffer is described by an IBIS [Model].

2. From the IBIS [Model], the EDA tool determines that the buffer is described in part by an [Algorithmic Model].

3. The EDA tool loads the executable model file referenced by [Algorithmic Model], and obtains the addresses of the AMI\_Init, AMI\_GetWave, and AMI\_Close functions.

4. The EDA tool loads the corresponding parameter definition file (.ami file) and assembles the arguments for the AMI\_Init function. These arguments include an impulse response matrix, a memory handle for the dynamic memory used by the executable model, the parameters for configuring the algorithmic model, and optionally the impulse response(s) of any crosstalk interferers.

5. The EDA tool calls the AMI\_Init function with the arguments previously prepared. The AMI\_Init function of the transmitter and receiver [Algorithmic Model]s are called separately as described in the reference flow below.

6. The AMI\_Init function parses the configuration parameters, allocates dynamic memory, places the address of the start of the dynamic memory into the memory handle and modifies the impulse response by the filter response of the [Algorithmic Model].

7. The EDA tool completes the rest of the simulation/analysis using the impulse response calculated by the AMI\_Init function which is a complete representation of the behavior of a given [Algorithmic Model] combined with the channel.

8. Before exiting, the EDA tool calls the AMI\_Close function, giving it the address in the memory handle for the [Algorithmic Model].

9. The AMI\_Close function de-allocates the dynamic memory used by the [Algorithmic Model] and performs whatever other clean-up actions are required.

10. The EDA tool terminates execution.

### Time domain simulations

1. From the system netlist, the EDA tool determines that a given buffer is described by an IBIS [Model].

2. From the IBIS [Model], the EDA tool determines that the buffer is described in part by an [Algorithmic Model].

3. The EDA tool loads the executable model file referenced by [Algorithmic Model], and obtains the addresses of the AMI\_Init, AMI\_GetWave, and AMI\_Close functions.

4. The EDA tool loads the corresponding parameter definition file (.ami file) and assembles the arguments for the AMI\_Init function. These arguments include an impulse response matrix, a memory handle for the dynamic memory used by the [Algorithmic Model], the parameters for configuring the [Algorithmic Model], and optionally the impulse response(s) of any crosstalk interferers.

5. The EDA tool calls the AMI\_Init function with the arguments previously prepared. The AMI\_Init function of the transmitter and receiver [Algorithmic Model]s are called separately as described in the reference flow below.

6. The AMI\_Init function parses the configuration parameters, allocates dynamic memory, places the address of the start of the dynamic memory into the memory handle and (optionally) modifies the impulse response by the filter response of the [Algorithmic Model]. The EDA tool may make use of the impulse response returned by the AMI\_Init function in its further analysis if needed.

7. The EDA tool generates a time domain digital input waveform bit pattern (stimulus). A long bit pattern (and simulation) may be broken up into multiple time segments by the EDA tool. For example, if one million bits are to be simulated, there can be 1000 segments of 1000 bits each, i.e., one time segment comprises 1000 bits. The segments are not required to be equally sized and are not required to contain an integer number of bits.

8. For each time segment, the EDA tool calls the AMI\_GetWave function of the transmitter (if it exists), giving it the digital input waveform and the address in the memory handle for the [Algorithmic Model].

9. For the AMI\_GetWave function of the receiver, the EDA tool takes the output from the transmitter AMI\_GetWave function (if it exists) and combines it (for example by convolution) with the channel impulse response to produce an analog waveform and passes this result to the receiver AMI\_GetWave function for each time segment of the simulation. If the transmitter AMI\_GetWave function doesn’t exist, the EDA tool takes the output of the transmitter AMI\_Init function and combines that (for example by convolution) with the digital stimulus bit pattern to produce the analog waveform for the receiver AMI\_GetWave function.

10. The output waveform of the receiver AMI\_GetWave function represents the voltage waveform at the decision point of the receiver. The EDA tool completes the simulation/analysis with this waveform.

11. Before exiting, the EDA tool calls the AMI\_Close function, giving it the address in the memory handle for the [Algorithmic Model].

12. The AMI\_Close function de-allocates the dynamic memory used by the [Algorithmic Model] and performs whatever other clean-up actions are required.

13. The EDA tool terminates execution.

### Reference Flows

The next two sections define a reference simulation flow for statistical and time domain system analysis simulations. Other methods of calling models and processing results may be employed, but the final simulation waveforms are expected to match the waveforms produced by this reference simulation flow.

A system simulation usually involves a transmitter (Tx) and a receiver (Rx) model with a passive channel placed between them.

#### Statistical simulation reference flow

Step 1. The EDA tool obtains the impulse response for the analog channel. This represents the combined impulse response of the transmitter’s analog output, the channel and the receiver’s analog front end. The transmitter’s output or receiver’s input characteristics must not include any filtering effects, for example equalization, in this impulse response, although it may include any parasitics which are included in the Tx or Rx analog model.

Step 2. The output of Step 1 is presented to the Tx executable model file’s AMI\_Init function and the Tx AMI\_Init function is executed. The impulse response returned by the Tx AMI\_Init function is passed onto Step 3.

Step 3. The output of Step 2 is presented to the Rx executable model file’s AMI\_Init function and the Rx AMI\_Init function is executed. The impulse response returned by the Rx AMI\_Init function is passed onto Step 4.

Step 4. The EDA tool completes the rest of the simulation/analysis using the impulse response calculated in Step 3 by the Rx executable model file’s AMI\_Init function which is a complete representation of the behavior of a given [Algorithmic Model] combined with the channel.

#### Time domain simulation reference flow

Step 1. The EDA tool obtains the impulse response for the analog channel. This represents the combined impulse response of the transmitter’s analog output, the channel and the receiver's analog front end. The transmitter’s output or receiver’s input characteristics must not include any filtering effects, for example equalization, in this impulse response, although it may include any parasitics which are included in the Tx or Rx analog model.

Step 2. The output of Step 1 is presented to the Tx executable model file’s AMI\_Init function and the Tx AMI\_Init function is executed. The Tx AMI\_Init function may modify the impulse response or choose to leave it unchanged.

Step 3. The output of Step 2 is presented to the Rx executable model file’s AMI\_Init function and the Rx AMI\_Init function is executed. The Rx AMI\_Init function may modify the impulse response or choose to leave it unchanged.

Under certain circumstances, for example when the Rx AMI\_Init function includes an optimization algorithm, the impulse response presented to the Rx AMI\_Init function must include the Tx equalization effects for the optimization to work correctly. However, when the Tx AMI model contains an AMI\_GetWave function that performs a similar or better equalization than the Tx AMI\_Init function, there is a possibility for “double-counting” the equalization effects in the Tx executable model file. To allow for such models to work correctly, the EDA tool can operate in one of several ways, two of which are documented here:

* not utilize the Tx AMI\_GetWave functionality, by treating the Tx AMI model as if the Tx GetWave\_Exists was False.
* use deconvolution to obtain the impulse response of the Rx filter. Since the AMI\_Init function contains a linear and time invariant algorithm, the Rx equalization can be represented as an impulse response. Since the output of the Rx AMI\_Init function (output of Step 3) is an impulse response modified by the Rx equalization (e.g., by convolving the input of the Rx AMI\_Init function with the impulse response of the Rx filter), the impulse response of the Rx filter can be obtained by deconvolving the output of Step 3 with the input presented to Step 3.

Note: The Rx executable model file writer should keep in mind that it is not guaranteed that the impulse response that is presented to the Rx AMI\_Init function will always include the effects of the Tx filter. Therefore the Rx AMI\_Init function may not be able to perform accurate optimization under all circumstances. For this reason, the parameters of the Rx AMI\_Init function should always default to valid values or have a mechanism to accept user-defined coefficients and allow the user to turn off any automatic optimization routines to ensure successful simulations.

Step 4. The EDA tool produces a digital stimulus waveform. A digital stimulus waveform is 0.5 when the stimulus is "high", -0.5 when the stimulus is "low", and may have a value between -0.5 and 0.5 such that transitions occur when the stimulus crosses 0.

Step 5. If Tx GetWave\_Exists is True the output of Step 4 is presented to the Tx executable model file’s AMI\_GetWave function and the Tx AMI\_GetWave function is executed. The output of the Tx AMI\_GetWave function is passed on to Step 6.

Step 6a. If Tx GetWave\_Exists is True and Rx GetWave\_Exists is True, the output of Step 5 is convolved with the output of Step 1 by the EDA tool and the result is passed on to Step 7.

Step 6b. If Tx GetWave\_Exists is False and Rx GetWave\_Exists is True, the output of Step 4 is convolved with the output of Step 2 by the EDA tool and the result is passed on to Step 7.

Step 6c. If Tx GetWave\_Exists is False and Rx GetWave\_Exists is False, the output of Step 4 is convolved with the output of Step 3 by the EDA tool and the result is passed on to Step 8.

Step 6d. If Tx GetWave\_Exists is True and Rx GetWave\_Exists is False, the output of Step 5 is convolved with the output of Step 1 and the Impulse Response of the Rx filter by the EDA tool and the result is passed on to Step 8. (The Impulse Response of the Rx filter may be obtained by deconvolving the output of Step 3 by the input of Step 3).

Note: For the scenario where the Tx AMI\_Init function does NOT include equalization effects (i.e., does not modify the impulse response of the channel), Step 6d is functionally equivalent to simply convolving the output of Step 5 with the output of Step 3.

Step 7. If Rx GetWave\_Exists is True the output of Step 6 is presented to the Rx executable model file’s AMI\_GetWave function and the Rx AMI\_GetWave function is executed. The output of the Rx AMI\_GetWave function is passed on to Step 8.

Step 8. The output of Step 6c, 6d or 7 becomes the simulation waveform output at the Rx decision point. Step 7 optionally may also return clock ticks, which may be post-processed by the simulation tool or presented to the user as is.

Steps 4 through 8 can be called once or can be called multiple times to process the full analog waveform. Splitting up the full analog waveform into multiple calls reduces the memory requirements when doing long simulations, and allows AMI\_GetWave to return model status every so many bits. Once all blocks of the input waveform have been processed, Tx AMI\_Close and Rx AMI\_Close are called to perform any final processing and release allocated memory.

## Function Signatures

This section defines the structure and parameters used with required and optional functions.

*Function:* **AMI\_Init**

*Required:* Yes

*Declaration:* long AMI\_Init (double \*impulse\_matrix,

long number\_of\_rows,

long aggressors,

double sample\_interval,

double bit\_time,

char \*AMI\_parameters\_in,

char \*\*AMI\_parameters\_out,

void \*\*AMI\_memory\_handle,

char \*\*msg)

*Arguments:*

impulse\_matrix

“impulse\_matrix” points to a memory location where the collection of channel voltage impulse responses, called the "impulse response matrix", is stored in the form of a single dimensional array of floating point numbers. The impulse responses pointed to by the “impulse\_matrix” argument are both input and output. The EDA tool provides the impulse responses. The algorithmic model is expected to modify the impulse responses in place by applying a filtering behavior, for example, an equalization function, if modeled in the AMI\_Init function. The impulse response values are uniformly spaced in time. The sample spacing is determined by the EDA tool and passed to the algorithmic model trough the AMI\_Init function’s “sample\_interval” argument.

The first column of the impulse response matrix is the impulse response for a through channel, a channel that serves as a communication path between a transmitter/receiver pair. The rest of the columns contain the impulse responses of crosstalk channels. Crosstalk channels describe the paths between aggressor transmitters and victim receiver(s). Transmitters which are not part of a through channel between a certain transmitter/receiver pair are all considered aggressor transmitters with respect to that through channel. The receiver of the through channel in consideration is referred to as the victim receiver. The crosstalk impulse responses may be placed into the impulse response matrix in any order.

The single dimensional array of “impulse\_matrix” is formed by concatenating the columns of an impulse response matrix, starting with the first column and ending with the last column. The matrix elements can be retrieved or identified using the following relationships:

impulse\_matrix[idx] = impulse response matrix element (row, col)

idx = col \* number\_of\_rows + row

row: row index ranges from 0 to number\_of\_rows-1

col: column index ranges from 0 to aggressors

Each impulse response in the impulse response matrix must have the same sample spacing and the same length.

To include any crosstalk effects in the Reference Flows described in this section of this specification, the crosstalk impulse responses must be included in the “impulse\_matrix” and passed to the transmitter and receiver AMI\_Init functions. If present, any filtering in the transmitter and/or receiver AMI\_Init function(s) must also be applied to the crosstalk impulse responses to properly account for the crosstalk effects.

Note that the “impulse\_matrix” will contain a different set of crosstalk impulse responses for the transmitter and receiver AMI\_Init calls, even for a transmitter/receiver pair of the same through channel. A transmitter’s AMI\_Init function operates on those impulse responses which originate from that transmitter, including the through channel and crosstalk channel impulse responses. A victim receiver’s AMI\_Init function, on the other hand, operates on all of those impulse responses which are received by that victim receiver, including the through channel and crosstalk channel impulse responses.

As an illustration, consider a crosstalk analysis with five channels numbered 1 through 5, where channel 3 in the center is the through channel of the transmitter/receiver pair Tx3/Rx3, and Rx3 is the victim receiver. In this case channels 1, 2 and 4, 5 are the aggressor channels with the aggressor transmitters Tx1, Tx2, Tx4 and Tx5. If the five “impulse\_matrix”-es of the five transmitters’ AMI\_Init functions contain the following data:

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*

impulse\_matrix impulse\_matrix

column 1 column 2

Tx1 IR1\_1 IR1\_3

Tx2 IR2\_2 IR2\_3

Tx3 IR3\_3

Tx4 IR4\_4 IR4\_3

Tx5 IR5\_5 IR5\_3

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*

then the “impulse\_matrix” passed into the victim receiver’s (Rx3) AMI\_Init function will contain the following data:

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*

impulse\_matrix impulse\_matrix impulse\_matrix impulse\_matrix impulse\_matrix

column 1 column 2 column 3 column 4 column 5

Rx3 Tx3Init(IR3\_3) Tx1Init(IR1\_3) Tx2Init(IR2\_3) Tx4Init(IR4\_3) Tx5Init(IR5\_3)

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*

where "IRi\_j" represents the impulse response from the transmitter on channel i to the receiver on channel j, Tx1Init() .. Tx5Init() represents the output of a transmitter’s AMI\_Init function which modified the impulse response denoted inside the parentheses. Note that while in this example the “impulse\_matrix” of each transmitter’s AMI\_Init function contains at most one crosstalk impulse response, the victim receiver’s “impulse\_matrix” contains four crosstalk impulse responses. Also, using the above notation note that the first index number of each impulse response passed to the transmitter’s AMI\_Init function matches the transmitter’s channel number, and the second index number of each impulse response passed to the receiver’s AMI\_Init function matches the receiver’s channel number.

It is the EDA tool’s responsibility to rearrange the content of the “impulse\_matrix” between the transmitter and receiver AMI\_Init calls.

The EDA tool is also responsible to limit the number of crosstalk channel impulse responses in “impulse\_matrix” so that they shall not exceed “Max\_Init\_Aggressors” as specified in the corresponding parameter definition file of the algorithmic model. Consequently, the “aggressors” parameter of the AMI\_Init function shall never contain a greater value than the value provided in “Max\_Init\_Aggressors” of the corresponding parameter definition file. While the allocated memory space for “impulse\_matrix” may be larger, it is assumed that there is no meaningful data in that space beyond the last column of the impulse response matrix that is stored in it.

The AMI\_Init function must not change the size or organization of “impulse\_matrix” that it was given in any way.

number\_of\_rows

The number of rows in the impulse\_matrix.

aggressors

The number of aggressors in the impulse\_matrix.

sample\_interval

This is the sampling interval of the “impulse\_matrix” passed into the AMI\_Init function and the “wave” passed into the AMI\_GetWave function. The sample\_interval is determined by the EDA tool and it is usually a fraction of the bit\_time. The “impulse\_matrix” and “wave” returned by the algorithmic model must have the same “sample\_interval” as the original “impulse\_matrix” and “wave” that was passed into the algorithmic model. The unit for sample\_interval is the second.

Impulse responses in “impulse\_matrix” and waveforms in “wave” should be treated as continuous analog waveforms by the algorithmic models. For this reason, algorithmic models must be able to produce valid results at any sample\_interval. Any internal analog to digital conversion or resampling is the responsibility of the algorithmic model. In case the algorithmic model is unable to operate at a given sample\_interval, it should abort gracefully with an exit code 0 (failure) and appropriate messaging.

*Example:*

Sample\_interval = (lowest\_bit\_time/64)

bit\_time

bit\_time is the bit time or unit interval (UI) of the current data, e.g., 100 ps, 200 ps etc. The executable model file may use this information along with the impulse\_matrix to initialize the filter coefficients. The unit for bit\_time is the second.

AMI\_parameters\_in

The AMI\_parameters\_in argument is a pointer to a string. Memory for the string is allocated and de-allocated by the EDA tool. All the input from the parameter definition file is passed to the algorithmic model using a string that has been formatted as using the tree structure defined below.

The AMI\_parameters\_in argument must always be present in the AMI\_Init function call and it must always contain the address of a valid string. The string must always contain at least the root name of the parameter tree, even if there are no parameters to pass to the algorithmic model.

*Examples:*

Examples of tree structures used for formatting and passing parameters:

(mySampleAMI\_1)

(mySampleAMI\_2

(tx

(taps 4)

(spacing sync)

)

)

(mySampleAMI\_3

(branch1

(leaf1 value1)

(leaf2 value2)

(branch2

(leaf3 value3)

(leaf4 value4)

)

(leaf5 value5 value6 value7)

)

)

The syntax for the parameter string is:

1. The parameter and message strings passed through the AMI\_parameters\_in, AMI\_parameters\_out and msg arguments must not be enclosed in double quotes.

2. Neither names nor individual values except for string literals may contain white space characters.

1. Parameter name/value pairs are always enclosed in parentheses, with the value separated from the name by white space.
2. A parameter value in a name/value pair can be either a single value or a list of values separated by whitespace.
3. Parameter name/value pairs can be grouped together into parameter groups by starting with an open parenthesis followed by the group name followed by the concatenation of one or more name/value pairs followed by a close parenthesis.
4. Parameter name/values pairs and parameter groups can be freely intermixed inside a parameter group.
5. The top level parameter string must be a parameter group.
6. White space is ignored, except as a delimiter between the parameter name and value.
7. Parameter values can be expressed either as a string literal, Boolean literal (True or False), decimal number, or a floating point number in the standard ANSI “C” notation (e.g., 2.0e-9). String literal values are delimited using a double quote (") and no double quotes are allowed inside the string literals. Empty string literals are denoted by two successive double quote characters.
8. A parameter can be assigned an array of values by enclosing the parameter name and the array of values inside a single set of parentheses, with the parameter name and the individual values all separated by white space.

The modified BNF specification for the syntax is:

<tree>:

<branch>

<branch>:

( <branch name> <leaf list> )

<leaf list>:

<branch>

<leaf>

<leaf list> <branch>

<leaf list> <leaf>

<leaf>:

( <parameter name> whitespace <value list> )

<value list>:

<value>

<value list> whitespace <value>

<value>:

<string\_literal>

<Boolean\_literal>

<decimal number>

<decimal number>e<exponent>

<decimal number>E<exponent>

AMI\_parameters\_out

The AMI\_parameters\_out argument is a pointer to a string pointer. Memory for the string is allocated and de-allocated by the algorithmic model. The model returns a pointer to the string as the contents of this argument. The string must be formatted using the tree structure described in AMI\_parameters\_in above. The AMI\_Init function may use this string to return parameters to the EDA tool.

While the AMI\_parameters\_out argument must always be present in the AMI\_Init function call and the EDA tool must always provide a valid (non-zero) address value in it, algorithmic models are not required to return anything at that address to the EDA tool. For this reason, the EDA tool must also initialize the memory content at that address to zero (null pointer) prior to calling the AMI\_Init function, so that after the execution of the function it can determine whether or not the function returned a valid string pointer at that address. If the AMI\_Init function does not have any parameters to return to the EDA tool, it must return a pointer at the address provided in this argument to a string which contains nothing but the root name. Note that the root name must always be included in the string.

AMI\_memory\_handle

Used to point to local storage for the algorithmic block being modeled and shall be passed back during the AMI\_GetWave calls. e.g., a code snippet may look like the following:

my\_space = allocate\_space( sizeof\_space );

status = store\_all\_kinds\_of\_things( my\_space );

\*serdes\_memory\_handle = my\_space;

The memory pointed to by AMI\_handle is allocated and de-allocated by the model.

msg

The msg argument is a pointer to a string pointer. Memory for the string is allocated and de-allocated by the algorithmic model. The model returns a pointer to the string as the contents of this argument. The AMI\_Init function may use this string to send a descriptive, textual message to the EDA tool to be displayed in the user interface and/or to be saved in a log file.

While the msg argument must always be present in the AMI\_Init function call and the EDA tool must always provide a valid (non-zero) address value in it, algorithmic models are not required to return anything at that address to the EDA tool. For this reason, the EDA tool must also initialize the memory content at that address to zero (null pointer) prior to calling the AMI\_Init function, so that after the execution of the function it can determine whether or not the function returned a valid string pointer at that address. If the AMI\_Init function does not have a message string to return to the EDA tool, it may take the following actions:

* + ignore the address provided in this argument (leaving the EDA tool provided null pointer at that address)
  + return a null pointer at the address provided in this argument (redundantly rewriting the EDA tool provided null pointer at that address)

Return Value

1 for success

0 for failure

Algorithmic models shall return a failure code (0) if and only if the function call fails due to a program execution error. In all other cases the return code shall be "success" (1), even if the function cannot operate properly due to some functional problems. For example, if a function includes a CDR which is unable to get into a stable mode, the function shall still return a success code (1). Examples for returning a failure code (0) may include an invalid data type, a null pointer during run time, or anything that prevents the successful execution of the model’s code.

The authors of Algorithmic Models are encouraged to provide feedback to the EDA tool’s users through the various available messaging options about any difficulties the model encounters during execution, regardless of what the value of the function’s return code is.

*Function:* **AMI\_GetWave**

*Required:* No

*Declaration:* long AMI\_GetWave (double \*wave,

long wave\_size,

double \*clock\_times,

char \*\*AMI\_parameters\_out,

void \*AMI\_memory)

*Arguments:*

**wave**

“wave” points to a memory location where a uniformly sampled vector of a time domain waveform is stored. The waveform pointed to by the “wave” argument is both input and output. The EDA tool provides the wave. The algorithmic model is expected to modify the waveform in place by applying a filtering behavior, for example, an equalization function, if modeled in the AMI\_GetWave function. The sample spacing is determined by the EDA tool and passed to the algorithmic model trough the AMI\_Init function’s “sample\_interval” argument.

Depending on the EDA tool and the analysis/simulation method chosen, the input waveform could include many components. For example, the input waveform could include:

* The waveform for the primary channel only.
* The waveform for the primary channel plus crosstalk and amplitude noise.
* The output of a time domain circuit simulator such as SPICE.

It is assumed that the electrical interface to either the driver or the receiver is differential. Therefore, the sample values are assumed to be differential voltages centered nominally around zero volts. The algorithmic model’s logic threshold may be non-zero, for example to model the differential offset of a receiver; however that offset will usually be small compared to the input or output differential voltage.

The output waveform is expected to be the waveform at the decision point of the receiver (that is, the point in the receiver where the choice is made as to whether the data bit is a “1” or a “0”). It is understood that for some receiver architectures, there is no one circuit node which is the decision point for the receiver. In such a case, the output waveform is expected to be the equivalent waveform that would exist at such a node were it to exist.

**wave\_size**

This is the number of samples in the waveform vector that is in the AMI\_GetWave function argument “wave”. The length of this waveform is determined by the EDA tool. The value of “wave\_size” may be different between GetWave calls within the same simulation. The “wave” returned by the algorithmic model must have the same number of samples as the original “wave” that was passed into the algorithmic model. Algorithmic models must be able to produce valid results with any wave\_size. In case the algorithmic model is unable to operate with a given wave\_size, it should abort gracefully with an exit code 0 (failure) and appropriate messaging.

**clock\_times**

Vector to return clock times. The clock times are referenced to the start of the simulation (the first AMI\_GetWave call). The clock\_times vector is allocated by the EDA tool and is guaranteed to be greater than the number of clocks expected during the AMI\_GetWave call. The clock times are exactly bit\_time/2 before the input data signal is sampled. The algorithmic model will return non-negative clock\_times values, and place -1 after the last valid clock tick in the clock\_times vector during each AMI\_GetWave call. If there are no valid clock ticks for the duration of an AMI\_GetWave call, a single entry of -1 will be returned in the clock\_times vector. The units of clock\_times are seconds.

The clock ticks represented by clock times should be strictly monotonic, both within the clock\_times vector returned from a single call to AMI\_GetWave and between successive calls to AMI\_GetWave. That is, within a given clock\_times vector each successive valid value is greater than the value that preceded it, and the first valid value from a given call to AMI\_GetWave must be greater than the last valid value from the preceding call to AMI\_GetWave. Any non-strict-monotonic behavior of clock times (including two identical values) should be considered by EDA tool as an algorithmic model failure.

Each valid value in the clock\_times vector shall be used to sample the output waveform by adding to it bit\_time/2, regardless whether that waveform sample occurs in the waveform segment being returned by the current call to AMI\_GetWave, or in the waveform segment to be returned by the next AMI\_GetWave call. Care should be taken in implementation of clock\_times to insure that the calculations used always maintain full double-precision floating point accuracy across multi-million bit simulations.

Although clock\_times will generally be related to the unit interval for the primary SerDes channel being simulated, there is no requirement that there be any relationship between the clock ticks generated by clock\_times and the actual waveform returned in the primary channel. It is possible for the CDR to go out of lock, resulting in clock ticks that have no definite relationship to the output wave. It is possible for the CDR to be suppressed for an undefined number of bits until the output of the 1st clock tick. In the case of a receiver without a CDR, it is possible for only -1 to ever be output during all AMI\_GetWave calls.

**AMI\_parameters\_out**

The AMI\_parameters\_out argument is a pointer to a string pointer. Memory for the string is allocated and de-allocated by the algorithmic model. The model returns a pointer to the string as the contents of this argument. The string must be formatted using a tree structure, as described in AMI\_parameters\_in above. The AMI\_GetWave function may use this string to return parameters to the EDA tool.

While the AMI\_parameters\_out argument must always be present in the AMI\_GetWave function call and the EDA tool must always provide a valid (non-zero) address value in it, executable model files are not required to return anything at that address to the EDA tool. For this reason, the EDA tool must also initialize the memory content at that address to zero (null pointer) prior to calling the AMI\_GetWave function, so that after the execution of the function it can determine whether or not the function returned a valid string pointer at that address. If the AMI\_GetWave function does not have any parameters to return to the EDA tool, it must return a pointer at the address provided in this argument to a string which contains nothing but the root name. Note that the root name must always be included in the string.

**AMI\_memory**

This is the memory which was allocated during the AMI\_Init call.

**Return Value**

1 for success

0 for failure

Executable model files shall return a failure code (0) if and only if the function call fails due to a program execution error. In all other cases the return code shall be "success" (1), even if the function cannot operate properly due to some functional problems. For example, if a function includes a CDR which is unable to get into a stable mode, the function shall still return a success code (1). Examples for returning a failure code (0) may include an invalid data type, a null pointer during run time, or anything that prevents the successful execution of the model’s code.

The authors of executable model files are encouraged to provide feedback to the EDA tool’s users through the various available messaging options about any difficulties the model encounters during execution, regardless of what the value of the function’s return code is.

*Function:* **AMI\_Close**

*Required:* Yes

*Declaration:* long AMI\_Close(void \* AMI\_memory)

*Arguments:*

**AMI\_memory**

Same as for AMI\_GetWave. See **AMI\_GetWave**.

**Return Value**

1 for success

0 for failure

Executable model files shall return a failure code (0) if and only if the function call fails due to a program execution error. In all other cases the return code shall be "success" (1), even if the function cannot operate properly due to some functional problems. For example, if a function includes a CDR which is unable to get into a stable mode, the function shall still return a success code (1). Examples for returning a failure code (0) may include an invalid data type, a null pointer during run time, or anything that prevents the successful execution of the model’s code.

The authors of executable model files are encouraged to provide feedback to the EDA tool’s users through the various available messaging options about any difficulties the model encounters during execution, regardless of what the value of the function’s return code is.

## Code Segment Examples

extern long AMI\_GetWave (wave, wave\_size, clock\_times, AMI\_parameters\_out, AMI\_memory);

my\_space = AMI\_memory;

clk\_idx=0;

time = my\_space->prev\_time + my\_space->sample\_interval;

for(i=0; i<wave\_size; i++)

{

wave = filterandmodify(wave, my\_space);

if (clock\_times && found\_clock (my\_space, time))

clock\_times[clk\_idx++] = getclocktime (my\_space, time);

time += my\_space->sample\_interval;

}

clock\_times[clk\_idx] = -1; //terminate the clock vector

Return 1;

1. AMI Parameter Definition File Structure

INTRODUCTION:

The information provided in this section is applicable to the content of the AMI parameter definition file (.ami file; hereinafter, parameter definition file). Note that the rules described below deviate from the rules for .ibs files

PARAMETER DEFINITION FILE ORGANIZATION

The parameter definition file is organized as a “tree”, with “leaves” and “branches” off a single “root” identified by a unique name. A branch may contain an AMI parameter, which itself contains individual leaves, describing features of the model. Branches, unless otherwise noted, may themselves be used to group other branches.

The file shall contain a distinct section or branch named “Reserved\_Parameters” beginning and ending with parentheses. The file may also contain another section or branch named “Model\_Specific”, beginning and ending with parentheses. “Reserved\_Parameters” and “Model\_Specific” are the only branches permitted to be connected to the root of the tree.

The parameter definition file shall be organized in the following way:

(my\_AMIname | Root name given to the Parameter file

(Reserved\_Parameters | Required heading to start the

| required Reserved\_Parameters

| section

...

(Reserved Parameter text starting with AMI\_Version)

...

) | End of Reserved\_Parameters

| section

(Model\_Specific | Required heading to start the

| optional Model\_Specific section

...

(Model Specific Parameter text)

...

) | End of Model\_Specific section

(Description <string>) | description of the model

| (optional)

) | End my\_AMIname parameter file

General Rules:

The content of the parameter definition file is case sensitive.

Only the pipe ("|") character is acceptable as a comment character regardless of what the calling .ibs file uses for the comment character.

The line length of the parameter definition file is not limited to a specific number of characters.

The root name in the file may contain an arbitrary string and does not need to match the file name.

A white space in the parameter definition file may be one or more space, tab, and/or line termination characters.

The “Reserved\_Parameter” section is required while the “Model\_Specific” section is optional.

For AMI\_Version 5.1 and above, the Reserved\_Parameter branch shall appear before the Model\_Specific branch.  Branches may be in any order in the Parameter definition file. The “|” character is the comment character.  Any text after the “|” character until the end of the line will be ignored by the parser.

Scaling factors or suffixes, such as p, n, etc., are not permitted in the Parameter definition file.

Scientific and floating point notation is permitted.

Note that Description is considered a leaf that may be optionally used within the individual “Reserved\_Parameters” or “Model\_Specfiic” branches. Description is also the only leaf that may be directly connected to the root.

Leaves may not connect to other leaves, except in the case of Labels for Table (see below).

Note:

* + - 1. Throughout this section, text strings inside the symbols “<” and “>” should be considered to be supplied or substituted by the model maker.  Text strings inside “<” and “>” are not reserved and can be replaced.

PARAMETER RULES SUMMARY

The features of a model described in a parameter definition file are called AMI parameters, and are grouped into the branches Reserved Parameters and Model\_Specific Parameters. AMI parameters are themselves branches, but may only contain leaves and not other branches.

Branches may define AMI parameters and/or other branches. A branch which contains one or more sub-branches may only contain the (Description <string>) leaf in addition to the sub-branches. Each sub-branch of a branch must have a unique name.

All AMI parameter branches shall contain leaf entries formatted as follows:

(parameter\_name

(Usage <usage>)

(Type <data\_type>)

({Format} <data\_format> <data>)

(List\_Tip) | only with ({Format} List) as discussed below

(Default <value>)

(Description <string>))

AMI parameter branches shall contain the leaves Type, Usage, and any of the following leaves:

Default

<data\_format> or Format <data\_format>

List\_Tip | only with List as discussed below

All leaves of the parameter definition file shall begin with one of the following reserved words:

Type

Usage

Description

Default

<data\_format> or Format <data\_format>

List\_Tip | only with List as discussed below

Multiple leaves containing the same reserved word are not allowed within an AMI parameter branch.

Notes:

* 1. The order of the leaf entries within an AMI parameter branch is not important.
  2. The word Format is optional as indicated by the curly braces "{" and "}" and may be ignored by EDA tools (the examples do not show the word Format).
  3. Certain Reserved Parameter names allow only certain <data\_format> selections, as described below.
  4. The <data\_format> selection of Value and Default are always mutually exclusive. Certain parameters may require Value or Default, but Value and Default are not allowed to be present together for the same parameter.
  5. <data\_format> is always required for selections other than Value.
  6. Default is optional for <data\_format> Range, List, Corner, Increment and Steps.
  7. Default is not allowed for Usage Out parameters.
  8. Default is not allowed for <data\_format> Table, Gaussian, Dual-Dirac and DjRj.
  9. Additional rules apply when <data\_format> is Table. The format for <data> describes a set of rows containing data values. Each row has its set of column data values enclosed by parentheses “(“ and “)”. Each row contains the same number of column values. Any or all of these columns may have different data types. For this case the <data\_type> argument is either a list of data types (one for each column), or a single data type. If it is a single data type then this type shall be applied to all of the columns in each row.
  10. <data\_format> Corner is not allowed for Usage Out.
  11. Description is optional.

RESERVED WORD RULES

Usage, Type, Format and Default and their allowed values are reserved names in the parameter definition (.ami) file.

**Usage** <usage>:

Required for all AMI parameters, where <usage> must be substituted by one of the following:

**In**

Parameter value is a required input to the AMI model

**Out**

Parameter value is coming from the AMI model

**Info**

Information for user or EDA tool

**InOut**

Parameter value is a required input to the AMI model. The AMI model may return a different value.

Note that the purpose of Usage Out or InOut is to provide a mechanism for the algorithmic model to return values to the EDA tool to be used as described by this specification.

**Type** <data\_type> or **Type** <type1><type2>…:

Required, where <data\_type> is replaced by one of the entries listed below. For {Format} Table, separate <type1> <type2>… entries are permitted for each column as discussed below, but Type Tap is not permitted.

**Float**

Float numbers are in general represented by a floating point number that may be scaled using a decimal exponent. A floating point number is represented by the significant digits, and optionally a sign and decimal point. For example, -1.23e-3, 123e-3, 1.23, 1 are all of type float.

**Integer**

Integers are numbers which are written without a fractional or decimal component, and fall within -2147483648 and 2147483647. If scientific notation is used then the exponent must be positive. For example, 65, 7, and -756, 123e3 are integers, but 1.6, 123e99 or 123e-2 are not integers.

**String**

String is a sequence of ASCII characters enclosed in double quotes ("). As defined in ANSI Standard X3.4-1986, the allowable ASCII characters consist of hexadecimal 20, 21, 23 to 7E, and the ASCII control characters 09 (HT), 0A (LF), and 0D (CR) for defining tabs and line termination sequences. The double quote character 22 (") is not allowed inside strings.

**Boolean**

Acceptable values are True and False, without quotation marks. Boolean Type values are not considered strings.

**Tap**

(For use by Tx and Rx equalizers)

The type Tap accepts only floating point values. Note that if the type Tap is used and the parameter value provided is not a number, this shall be considered an error condition for which EDA tool behavior is not specified.

A tapped delay line can be described by creating a separate parameter for each tap weight and grouping all the tap weights for a given tapped delay line in a single parameter group which is given the name of the tapped delay line. If in addition the individual tap weights are each given a name which is their tap number (i.e., "-1" is the name of the first precursor tap, "0" is the name of the main tap, "1" is the name of the first postcursor tap, etc.) and the tap weights are declared to be of type Tap, then the EDA tool can assume that the individual parameters are tap weights in a tapped delay line, and use that assumption to perform tasks such as optimization. The model developer is responsible for choosing whether or not to follow this convention.

A complete equalizer example featuring the Tap Type is provided later in this section.

**UI**

Unit Interval. 1 UI is the inverse of the data rate frequency, for example 1 UI of a channel operating at 10 Gb/s is 100 ps. UI parameter values are in units of UI (bit time). The parameter may take on either floating point or integer values.

**Format <data\_format>** <data>or **<data\_format>**<data>:

Required, except for the <data\_format> selection of Value as noted below. The word “Format” as part of the Format <data\_format> <data> sequence is optional. Valid entries for the <data\_format> and <data> fields are:

**Value** <value>

Single value data. The model maker may provide any value without any restrictions within the constraints of the Type of the variable. Note that Value and Default (defined below) are mutually exclusive, and shall not be used together for the same parameter.

**Range** <typ value> <min value> <max value>

This defines a continuous range for which the user may select any value greater than or equal to <min value> and less than or equal to <max value> within the constraints of the Type of the variable

**List** <default value> <value> <value> <value> ... <value>

This defines a discrete set of values from which the user may select one value

**List\_Tip** <default\_entry><entry><entry><entry>…<entry>

This is an optional leaf of a parameter with Format **List** and it is followed by a String entry for each entry in the **List**. The number of entries in List\_Tip must be the same as the number of entries in **List**. The nth entry in List\_Tip shall correspond to the nth entry in **List**. Quoted null entries are not permitted. All entries in List\_Tip shall be unique, except that if two entries in **List** are the same, then the corresponding List\_Tip entries must also be the same. List is required for List\_Tip to be entered, and the word Format before List\_Tip as in (Format List\_Tip ,,,) is not allowed.

Example:

(Strength (Usage In) (Type Integer)(Description "Strength of Driver")

(List 0 1 2 3 4)(Default 2)

(List\_Tip "Extra Weak" "Weak" "Nominal" "Strong" "Extra Strong"))

**Corner** <typ value> <slow value> <fast value>

Corner is not allowed with Usage Out parameters. The selection of one value is automatically carried out by the EDA tool based on its internal simulation corner setting

**Increment** <typ> <min> <max> <delta>

where min <= typ <= max and delta is always positive. After expansion, the expanded values of the parameter are typ + N\*delta where N is any positive or negative integer value provided by the EDA tool during the expansion process so that: min <= expanded values <= max

**Steps** <typ> <min> <max> <# steps>

Treat exactly like Increment with <delta> == (<max>-<min>)/<# steps>

**Table** and optional leaf **Labels**

The Format Table states that this parameter consists of one or more columns of data, with each row delimited by parentheses “(“ and “)”. All rows must contain the same number of entries (columns). At least one row shall be included. Default is illegal when Format Table is used.

The column entries shall be of Type Float, UI, Integer, String or Boolean.

Type Tap is illegal under Table. If only one Type is provided, then all Table entries shall be of the specified type.

(Type <type>)

For Table only, Type can also be used to designate the entries for each column. In this case, type entries shall be given for each column in the Table:

(Type <type1> <type2> <type3> ...)

Labels is an optional leaf within Table and it is followed by a String entry for each column in the Table. Quoted null entries are permitted. Labels shall be positioned immediately before the first row in a Table and are of the form:

(Labels <"label1"> <"label2"> <"label3"> ...)

If Table is used for a Reserved Parameter, the rules for the number of columns and their meaning are described in the Reserved\_Parameters section.

The EDA tool and the executable model file shall always transmit the entire contents of a table through the AMI\_parameters\_in or AMI\_parameters\_out string (defined in Section 10 and illustrated in the examples below). Only the parameter name and values in the table are included in the parameter string. The values in each row of the table are flattened into a single row of values without the parentheses surrounding each row when producing the parameter string.

For Usage Out and InOut, the number of rows returned by the executable model file may differ from the number of rows documented in the parameter definition file, but a minimum of one row shall be returned. Multiple GetWave calls are not required to return the same number of rows. For Usage Out, a one-row Table is required in the parameter definition file to serve as a template for single and multi-row tables. This can be used by the EDA tool to reconstruct a sequence of data values returned by the executable model file into a table with as many rows as needed, and optionally for parameter initialization before being replaced by the actual Table data returned by the executable model file.

*Examples:*

Single Row Table where all numbers are Float (note that “1” is a legal float entry):

(fwd (Usage In) (Type Float)

(Table

(1 -0.169324 1.40308 0.33024)

)

(Description "Application Description")

)

The EDA tool sends to the executable model file in the parameter string:

(fwd 1 -0.169324 1.40308 0.33024)

Single Row, all numbers would be encoded as integers by the EDA tool:

(bit\_pattern (Usage In) (Type Integer)

(Table

(1 1 1 1 0 0 0 1 0 0 1)

)

(Description "Bit Pattern Sequence")

)

The EDA tool sends to the executable model file in the parameter string:

(bit\_pattern 1 1 1 1 0 0 0 1 0 0 1)

Multiple row Table example with Labels:

The optional Labels line is added above the first row. It is not sent or returned to/from the executable model file, but is available to the EDA tool for information.

(poles (Usage InOut) (Type Float)

(Table

(Labels "complex\_conj\_flag" "real\_part" "imag\_part")

(1 -5e8 0)

(2 -9.4e8 8.3e8)

(1 -7.3e8 0)

)

(Description "Two real poles and one complex pole")

)

The EDA tool sends to the executable model file in the parameter string:

(poles 1 -5e8 0 2 -9.4e8 8.3e8 1 -7.3e8 0)

An updated set with a different number of pole and row entries can be returned with a similar sequence to be converted back into the same or a different number of rows.

Type used to specify the type entry for each column (the example above is modified with Type entries for each column):

(poles (Usage InOut) (Type Integer Float Float)

(Table

(Labels "complex\_conj\_flag" "real\_part" "imag\_part")

(1 -5e8 0)

(2 -9.4e8 8.3e8)

(1 -7.3e8 0)

)

(Description "Two real poles and one complex poles")

)

The encoding in the previous example is sent to the EDA tool and returned to the executable model file.

Example of two rows with Type entries for each column (the fourth column numbers are interpreted as UI values):

(pdf (Usage In) (Type Integer Integer Float UI Float)

(Table

(Labels "Row" "Bin number" "Time" "UI" "Probability")

(1 -5 -5e-9 -1 1e-5)

(2 -4 -4e-9 -0.8 1e-4)

)

(Description "Probability Distribution Function Table")

)

The EDA tool sends to the executable model file in the parameter string:

(pdf 1 -5 -5e-9 -1 1e-5 2 -4 -4e-9 -0.8 1e-4 ...)

Example above, but with Usage Out (only one row is necessary in the parameter definition file):

(pdf (Usage Out) (Type Integer Integer Float UI Float)

(Table

(Labels "Row" "Bin number" "Time" "UI" "Probability")

(1 -5 -5e-9 -1 1e-5)

)

(Description "Probability Distribution Function Table")

)

One row is provided as a template, but the executable model file can return, in the parameter string, different data and more than one row such as shown.

(pdf 1 -6 -6e-9 -1.2 3e-6 2 -5 -5e-9 -1 9e-6 ...)

**Gaussian** <mean> <sigma>

Gaussian defines a statistical distribution as the data Format, with mean and sigma (standard deviation) specified by the “mean” and “sigma” floating point entries, respectively. Gaussian mean and sigma values are assumed to be in units of UI when declared as Type UI. Reserved\_Parameters may define units for Gaussian values declared as Type Float, as detailed below.

**Dual-Dirac** <mean> <mean> <sigma>

Dual-Dirac consists of a composite of two Gaussian data sets. Two separate means are defined, but with a common sigma for each. Both mean entries and the sigma entry are floating point values and are assumed to be in units of UI when declared as Type UI. Reserved\_Parameters may define units for Dual-Dirac values declared as Type Float, as detailed below.

**DjRj** <minDj> <maxDj> <sigma>

DjRj defines the combination of deterministic and random jitter values, by convolution. Rj is assumed to take on a Gaussian distribution with standard deviation value “sigma”, while Dj is assumed to have a uniform distribution with minimum and maximum values “minDj” and “maxDj”, respectively. All entries shall be floating point, and are assumed to be in units of UI when declared as Type UI and in units of seconds when Type Float.

**Default** <value>:

When used with single value data, Default and Value are mutually exclusive, and shall not be used together for the same parameter. In these situations, Default is a synonym of Value and does not imply any additional meaning or actions. Default is not allowed for any Usage Out parameter types, and Table, Gaussian, Dual-Dirac and DjRj. Default is optional for Range, List, Corner, Increment and Steps. When Default is specified for any of these parameter types, it shall be used by the EDA tool to pick one value from all the possibilities for that parameter if the user does not make such a selection.

If a Default <value> is specified, its value shall have the same Type as the parameter. For example, if Type is Boolean, <value> shall be either True or False; if Type is Integer, <value> shall be an integer. Also, if Default is specified, <value> shall be a member of the set of allowed values of the parameter. If Default is not specified, the default value of the parameters shall be assumed by the EDA tool to be the <typ> value.

**Description** <string>:

Description is a leaf that may appear in multiple locations, including after a Model Specific Parameter, after a Reserved Parameter or after the name of the Algorithmic model. The location of Description will determine whether it describes a parameter or the Algorithmic model as a whole.

The string following Description is used by the EDA tool to convey information to the end-user. Description <string> is optional, but it is highly recommended for describing the Algorithmic model and the Model Specific Parameters of the Algorithmic model. The Description string may span multiple lines, but it is recommended that the text contained in the Description string should not exceed 120 characters per line.

COMBINATION AND CORNER RULES

For Usage Out parameters, ({Format} <data\_format> <data>) may be ignored by the EDA tool, except when <data\_format> is Table where at least a one-row Table is required in <data> to serve as a template for single and multi-row tables.

Formats Value, Corner and List can be of any defined Types whereas Formats Range, Increment and Steps can be of Types Float, UI, Integer and Tap only. Formats Gaussian, Dual-Dirac and DjRj can only be of Types Float and UI. For Format Table, the column entries shall be of Type Float, UI, Integer, String or Boolean. Type Tap is illegal for Format Table. If only one Type is provided, then all Table entries shall be of the specified type. Type can also be used to designate the entries for each column in the table. More information is provided in the definition of the Table format.

Note that modeling and simulating different corner cases is a fundamental concept in IBIS. For each model instance, the EDA tool will make use of either the "Typ", "Min" or "Max" data provided in the .ibs file, according to the user’s simulation setup.

As described in the "Notes on Data Derivation Method" section of this document, the "Min" and "Max" data for the I-V tables and their corresponding voltage reference keywords, [Ramp] and V-T tables represent the slow and fast behavior of the device, respectively. Following the conservative approach, the "Max" value of C\_comp represents the slow, and the "Min" value of C\_comp represents the fast behavior of the device.

For AMI parameters defined as Format Corner, the EDA tool will pick one of the three supplied values (<typ value>, <slow value>, <fast value>) in the parameter definition file for any given model instance. This selection is governed by the same internal corner variable in the EDA tool that controls the selection of the "Typ", "Min", "Max" model data. <typ value> corresponds to "Typ", <slow value> corresponds to "Min" (slow or weak performance) and <fast value> corresponds to "Max" (fast or strong performance). For AMI parameters, <slow value> does not have to be less than <fast value>.

For AMI parameter Types “Range”, “Increment” and “Steps” <min value>, <max value> does not imply slow and fast corners, and the user may select any value provided by these parameters regardless of what corner is used for the simulation. If the user does not make a selection for parameter types “Range”, “List”, “Increment” and “Steps”, the EDA tool shall automatically use the value defined by Default, if it exists, or the <typ value> otherwise (regardless of what corner is used for the simulation).

When a [Model] that is associated with any of the pins listed under the [Diff Pin] keyword contains the [Algorithmic Model] keyword, the tdelay\_\*\*\* parameters in the fourth, fifth and sixth columns of the [Diff Pin] keyword are ignored in AMI channel characterization simulations, i.e., they are treated as if their value would be zero.

PROCESSING AND PASSING PARAMETER STRING RULES

The parameter string passed in and out of the executable model file (described in the sections AMI\_parameters\_in, AMI\_parameters\_out and AMI\_memory\_handle below) is formatted the same way as the tree data structure in the parameter definition file with the following exceptions.

The EDA tool shall process the content of the parameter definition file such that

1. the “Reserved\_Parameters” and “Model\_Specific” branch names and their associated open and close parentheses "()" are not included in the AMI\_parameters\_in string, and
2. the AMI parameter branches with Usage In or Usage InOut are converted to leaves for the AMI\_parameters\_in string, possibly incorporating user selections. In this conversion each AMI parameter branch name becomes a leaf name in the AMI\_parameters\_in string and each leaf name is followed by a white space, a value and a closing parenthesis ")"

The executable model shall generate a parameter string that is consistent with the content of the parameter definition file so that

1. the “Reserved\_Parameters” and “Model\_Specific” branch names and their associated open and close parentheses "()" are not included in the AMI\_parameters\_out string, and
2. the AMI parameter branches Usage Out or Usage InOut are returned as leaves in the AMI\_parameters\_out string.

The EDA tool shall pass a string to the executable model through the AMI\_parameters\_in argument. This string shall contain all of the leaf-formatted Usage In and Usage InOut AMI parameters if there are any defined in the .ami file. No other information may be included in this string. The string shall always include the root name of the parameter tree, even if there are no parameters to pass to the algorithmic model.

The executable model shall return a string to the EDA tool through the AMI\_parameters\_out argument. This string shall contain all of the leaf formatted Usage InOut and Usage Out AMI parameters if there are any defined in the parameter definition file. No other information may be included in this string. The string shall always include the root name of the parameter tree, even if there are no parameters to return to the EDA tool.

For Usage In, the value in the AMI parameter leaves are determined by the EDA tool based on the AMI parameter branches in the parameter definition file. For Usage Out, the value in the AMI parameter leaves are determined by the Algorithmic Model. For Usage InOut, the value in the AMI parameter leaves are first determined by the EDA tool based on the AMI parameter branches in the parameter definition file and passed into the Algorithmic Model which may return a new value in the AMI parameter leaves after some processing.

RESERVED PARAMETERS REFERENCE

The parameter definition file shall have a branch with the heading “Reserved\_Parameters”. This branch shall contain all the Reserved Parameters for the model.

The following Reserved Parameters are used by the EDA tool and are required if the [Algorithmic Model] keyword is present. The entries following the Reserved Parameter names determine their Usage, Type and Default values. Their values may be defined using either Default or Value but not both. Description is optional.

*Parameter:* AMI\_Version

*Required:* Yes for AMI\_Version 5.1 and above, illegal before AMI\_Version 5.1

*Descriptors*:

Usage: Info

Type: String

Format: Value

Default:<string\_literal>

Description:<string>

*Definition:* Tells EDA tool what version of the AMI modeling language is supported.

*Usage Rules:* AMI\_Version is required in the parameter definition files of AMI models which are written in compliance with the IBIS Version 5.1 or later specification(s), but it is not allowed in the parameter definition files of AMI models which are written in compliance with the IBIS Version 5.0 specification. When required, this parameter shall be the first parameter defined in the Reserved\_Parameters branch of the parameter definition file.

The value of this parameter shall be “5.1” for AMI models written in compliance with the IBIS Version 5.1 specification. The absence of AMI\_Version indicates that the AMI model was written in compliance with the IBIS Version 5.0 specification.

The version numbers of .ibs files and AMI models do not have to match. The EDA tool is expected to execute the AMI model according to the rules of the specification which corresponds to its version number.

*Other Notes:* For AMI\_Version 5.1 or later.

Throughout this document, the shorthand, AMI\_Version <version\_number>, is used to indicate the minimum AMI\_Version level that is supported. If the AMI\_Version is not used, then the AMI model is processed at the level defined in [IBIS Ver] 5.0. In some cases, it will be noted that a rule has changed, has become more restrictive or more relaxed for a specified AMI\_Version level.

*Examples:*

(AMI\_Version (Usage Info)(Type String)(Value “5.1”)

(Description “Valid for AMI\_Version 5.1 and above”)

)

(AMI\_Version (Usage Info)(Type String)(Default “5.1”)

(Description “Valid for AMI\_Version 5.1 and above”)

)

*Parameter:* Init\_Returns\_Impulse

*Required:* Yes

*Descriptors*:

Usage: Info

Type: Boolean

Format: Value

Default:<Boolean\_literal>

Description:<string>

*Definition:* Tells EDA tool whether the AMI\_Init function returns a modified impulse response.

*Usage Rules:* When the Boolean\_literal value is set to “True”, the model returns the convolution of the impulse response with the impulse response of the equalization.

*Other Notes:*

*Examples:*

(Init\_Returns\_Impulse (Usage Info)(Type Boolean)(Default True)

(Description “Valid for all AMI\_Version levels”)

)

(Init\_Returns\_Impulse (Usage Info)(Type Boolean)(Value True)

(Description “Valid for all AMI\_Version levels”)

)

*Parameter:* **GetWave\_Exists**

*Required:* Yes

*Descriptors*:

Usage: Info

Type: Boolean

Format: Value

Default:<Boolean\_literal*>*

Description:<string>

*Definition:* Tells EDA tool whether the AMI\_GetWave is implemented in this model

*Usage Rules:* Note that if Init\_Returns\_Impulse is set to “False”, then GetWave\_Exists SHALL be set to “True”.

*Other Notes:*

*Examples:*

(GetWave\_Exists (Usage Info)(Type Boolean)(Default True)

(Description “Valid for all AMI\_Version levels”)

)

(GetWave\_Exists (Usage Info)(Type Boolean)(Value True)

(Description “Valid for all AMI\_Version levels”)

)

*Parameter:* **Use\_Init\_Output**

*Required:* No, and legal only before AMI\_Version 5.1

*Descriptors*:

Usage: Info

Type: Boolean

Format: Value

Default:<Boolean\_literal>

Description:<string>

*Definition:* Tells EDA tool whether to use AMI\_Init output for AMI\_GetWave input

*Usage Rules:* When Use\_Init\_Output is set to “True”, the EDA tool is instructed to use the output impulse response from the AMI\_Init function when creating the input waveform presented to the AMI\_GetWave function.

If the Reserved Parameter, Use\_Init\_Output, is set to “False”, EDA tools will use the original (unfiltered) impulse response of the channel when creating the input waveform presented to the AMI\_GetWave function.

The algorithmic model is expected to modify the waveform in place.

Use\_Init\_Output is optional. The default value for this parameter is “True”.

If Use\_Init\_Output is “False”, GetWave\_Exists shall be “True”.

*Other Notes:*

*Examples:*

(Use\_Init\_Output (Usage Info)(Type Boolean)(Default True)

(Description “Use\_Init\_Output is valid only when AMI\_Version is omitted”)

)

The following Reserved Parameters are optional. If the following parameters are not present, the values are assumed as “0”.

*Parameter:* **Max\_Init\_Aggressors**

*Required:* No

*Descriptors*:

Usage: Info

Type: Integer

Format: Value

Default: <numeric\_literal>

Description:<string>

*Definition:* Tells the EDA tool how many aggressor Impulse Responses the AMI\_Init function is capable of processing.

*Usage Rules:* Its value is assumed “0” if Max\_Init\_Aggressors is not present.

*Other Notes:*

*Examples:*

(Max\_Init\_Aggressors (Usage Info)(Type Integer)(Default 5)

(Description “Valid for all AMI\_Version levels”)

)

(Max\_Init\_Aggressors (Usage Info)(Type Integer)(Value 5)

(Description “Valid for all AMI\_Version levels”)

)

*Parameter:* **Ignore\_Bits**

*Required:* No

*Descriptors*:

Usage: Info

Type: Integer

Format: Value

Default: <numeric\_literal>

Description:<string>

*Definition:* Tells the EDA tool how long the time variant model takes to complete initialization.

*Usage Rules:* This parameter is meant for AMI\_GetWave functions that model how equalization adapts to the input stream. The value in this field tells the EDA tool how many bits of the AMI\_GetWave output should be ignored.

Its value is assumed “0” if Ignore\_Bits is not present.

*Other Notes:*

*Examples:*

(Ignore\_Bits (Usage Info)(Type Integer)(Default 1000)

(Description “Valid for all AMI\_Version levels”)

)

(Ignore\_Bits (Usage Info)(Type Integer)(Value 1000)

(Description “Valid for all AMI\_Version levels”)

)

1. JITTER and noise reserved parameters

**Tx-only Reserved Parameters: Tx\_Jitter and Tx\_DCD**

These Reserved Parameters only apply to Tx algorithmic models. There parameters are optional. If these parameters are not specified, the values default to no jitter specified in the model (“0” jitter).

*Parameter:* **Tx\_Jitter**

*Required:* No

*Descriptors*:

Usage: Info (Out permitted only for AMI\_Version 5.0 and 5.1)

Type: Float, UI

Format: Gaussian, Dual-Dirac, DjRj, Table

Default: (Illegal)

Description:<string>

*Definition:* Tells EDA tool how much jitter exists at the input to the transmitter’s analog output buffer.

*Usage Rules:* For formats Gaussian, Dual-Dirac and DjRj, entries are assumed to be in units of UI when declared as Type UI and in units of seconds when Type Float.

For the Table format, only three table columns are permitted, which shall be entered in the following order:

Row\_number Time Probability, or

Row\_number UI Probability

where each Row\_number is an integer (positive or negative), each Time value is a floating point number in seconds or a bit time in units of UI, and each Probability is a unitless floating point number. The Type for each column must be specified when Format Table is used, as in:

(Type Integer Float Float)

(Type Integer UI Float)

*Other Notes:* For compatibility with earlier versions, (Type Float) and (Type UI) are permitted for data using the Table format, with Type Float signifying that the three column data types are Integer, Float and Float, and Type UI signifying that the three column data types are Integer, UI and Float. However, these variations are discouraged.

Default is not shown in the examples below.

*Examples:*

(Tx\_Jitter (Usage Info)(Type Float)

(Gaussian 0.2e-12 0.03e-12)

)

(Tx\_Jitter (Usage Info)(Type Float)

(Dual-Dirac 3e-12 6e-12 0.5e-12)

)

(Tx\_Jitter (Usage Info)(Type Float)

(DjRj 0 6E-12 1.3E-12)

)

(Tx\_Jitter (Usage Info)(Type Integer Float Float)

(Table

(Labels “Row\_No” “Time” “Probability”)

(-5 -5e-12 1e-10)

(-4 -4e-12 3e-7)

(-3 -3e-12 1e-4)

(-2 -2e-12 1e-2)

(-1 -1e-12 0.29)

(0 0 0.4)

(1 1e-12 0.29)

(2 2e-12 1e-2)

(3 3e-12 1e-4)

(4 4e-12 3e-7)

(5 5e-12 1e-10)

)

)

*Parameter:* **Tx\_DCD**

*Required:* No

*Descriptors*:

Usage: Info (Out permitted only for AMI\_Version 5.0 and 5.1)

Type: Float, UI

Format: Value, Range, Corner, List, Increment, Steps

Default: <numeric\_literal*>*

Description:<string>

*Definition:*

Tx\_DCD (Transmit Duty Cycle Distortion) defines half the peak to peak clock duty cycle distortion to be added to the behavior implemented by the EDA tool by modifying the stimulus input or by post processing the simulation

Time(n)=n\*bit\_time+Tx\_DCD\*(-1.0)^n

n\*bit\_time is the ideal time of the nth clock.

Time(n) is the time of the nth clock modified when creating input waveforms for the Tx.

. Entries are assumed to be in units of seconds when declared as Type Float. Note that all equations using jitter parameters that can be defined as UI shall be assumed to seconds in these formulae.

*Usage Rules:*

*Other Notes:*

*Examples:*

(Tx\_DCD (Usage Info)(Type Float)

(Range 2e-12 1e-12 3e-12))

The following optional Reserved Parameters are used to specify impairments for the transmitter output. These budgets specify the impairment as measured at the TX output (i.e. the transmitter output is expected to be directly modulated by these amounts). This data is used by the simulator to either modify the input stimulus presented to the algorithmic model or when post-processing the results from the model; the budget values specified by these parameters are not passed directly to the model itself.

*Parameter:* **Tx\_Rj**

*Required:* No

*Descriptors*:

Usage: Info

Type: Float or UI

Format: Value, List, Range, Corner, Increment, or Steps

Default: <numeric\_literal*>*

Description:<string>

*Definition:* The standard deviation of a white Gaussian phase noise process at the transmitter which is to be added to the behavior implemented by the EDA tool by modifying the stimulus input or by post processing the simulation results. Entries are assumed to be in units of seconds when declared as Type Float.

*Usage Rules:*

*Other Notes:* Time(n)=n\*bit\_time+Tx\_Rj\*gaussian\_rand()

gaussian\_rand() is a function that returns floating point numbers between -inf and +inf. The distribution of these numbers shall be a white Gaussian distribution centered at 0.0 with a standard deviation of 1.0. The EDA tool can protect against abs(Tx\_Rj\*gaussian\_rand())>0.5UI.

*Example:*

(Tx\_Rj (Usage Info)(Corner 0.005 0.006 0.004)(Type UI)

(Description "Tx Random Jitter in UI."))

*Parameter:* **Tx\_Dj**

*Required:* No

*Descriptors*:

Usage: Info

Type: Float or UI

Format: Value, List, Range, Corner, Increment, or Steps

Default: <numeric\_literal*>*

Description:<string>

*Definition:* The worst case half the peak to peak variation at the transmitter implemented by the EDA tool by modifying the stimulus input or by post processing the simulation results. **Tx\_Dj** shall include all deterministic and uncorrelated bounded jitter that is not accounted for by **Tx\_DCD**, and **Tx\_Sj**. Entries are assumed to be in units of seconds when declared as Type Float.

*Usage Rules:*

*Other Notes:* Time(n)= n\*bit\_time+2.0\*Tx\_Dj\*rand()

rand() is a function that returns floating point numbers between -0.5 and

+0.5 with white uniform distribution.

*Example:*

(Tx\_Dj (Usage Info)(Value 0.1)(Type UI)

(Description "Tx Bounded Jitter in UI."))

*Parameter:* **Tx\_Sj**

*Required:* No

*Descriptors*:

Usage: Info

Type: Float or UI

Format: Value, List, Range, Corner, Increment, or Steps

Default: <numeric\_literal*>*

Description:<string>

*Definition:* Half the peak to peak amplitude of a sinusoidal jitter which is to be added to the behavior implemented directly by the transmitter model.

*Usage Rules:* If **Tx\_Sj\_Frequency** is not assigned (either in the model or by the user), **Tx\_Sj** should be ignored. Entries are assumed to be in units of seconds when declared as Type Float.

*Other Notes:* Time(n)=n\*bit\_time+**Tx\_Sj**\*sin((n\*bit\_time\*2.0\*Pi)\***Tx\_Sj\_Frequency**)

*Example:*

(Tx\_Sj (Usage Info)(Corner 0.005 0.006 0.004)(Type UI)

(Description "Tx Sinosoidal Jitter in UI."))

*Parameter:* **Tx\_Sj\_Frequency**

*Required:* No

*Descriptors*:

Usage: Info

Type: Float

Format: Value, List, Range, Corner, Increment, or Steps

Default: <numeric\_literal*>*

Description:<string>

*Definition:* The frequency, in Hertz, of the sinusoidal jitter at the transmitter.

*Usage Rules:* If **Tx\_Sj\_Frequency** is not assigned (either in the model or by the user), **Tx\_Sj** should be ignored.

*Other Notes:* Time(n)=n\*bit\_time+**Tx\_Sj**\*sin((n\*bit\_time\*2.0\*Pi)\***Tx\_Sj\_Frequency**)

*Examples:*

(Tx\_Sj\_Frequency (Usage Info)(Corner 6.5E7 6.5E7 6.5E7)(Type Float)

(Description "Tx Sinusoidal Jitter Frequency in Hz."))

**Rx-only Reserved Parameters: Rx\_Clock\_PDF and Rx\_Receiver\_Sensitivity**

These Reserved Parameters only apply to Rx algorithmic models. These parameters are optional. If the parameters are not specified, the values default to “0”.

*Parameter:* **Rx\_Clock\_PDF**

*Required:* No

*Descriptors*:

Usage: Info, Out

Type: Float, UI

Format: Gaussian, Dual-Dirac, DjRj, Table

Default: (Illegal)

Description:<string>

*Definition:* Tells EDA tool the probability density function of the recovered clock.

*Usage Rules:* For formats Gaussian, Dual-Dirac and DjRj, entries are assumed to be in units of UI when declared as Type UI and in units of seconds when Type Float.

For the Table format, only three table columns are permitted, which shall be entered in the following order:

Row\_number Time Probability, or

Row\_number UI Probability

where each Row\_number is an integer (positive or negative), each Time value is a floating point number in seconds or a bit time in units of UI, and each Probability is a unitless floating point number. The Type for each column must be specified when Format Table is used, as in:

(Type Integer Float Float)

(Type Integer UI Float)

*Other Notes:* For compatibility with earlier versions, (Type Float) and (Type UI) are permitted for data using the Table format, using the Table format, with Type Float signifying that the three column data types are Integer, Float and Float, and Type UI signifying that the three column data types are Integer, UI and Float. However, these variations are discouraged.

*Examples:*

(Rx\_Clock\_PDF (Usage Info)(Type Float)

(Gaussian 0.2e-12 0.03e-12)

)

(Rx\_Clock\_PDF (Usage Info)(Type Float)

(Dual-Dirac 3e-12 6e-12 0.5e-12)

)

(Rx\_Clock\_PDF (Usage Info)(Type Float)

(DjRj 0 6E-12 1.3E-12)

)

(Rx\_Clock\_PDF (Usage Info)(Type Integer Float Float)

(Table

(Labels “Row\_No” “Time” “Probability”)

(-5 -5e-12 1e-10)

(-4 -4e-12 3e-7)

(-3 -3e-12 1e-4)

(-2 -2e-12 1e-2)

(-1 -1e-12 0.29)

(0 0 0.4)

(1 1e-12 0.29)

(2 2e-12 1e-2)

(3 3e-12 1e-4)

(4 4e-12 3e-7)

(5 5e-12 1e-10)

)

)

*Parameter:* **Rx\_Receiver\_Sensitivity**

*Required:* No

*Descriptors*:

Usage: Info, Out

Type: Float

Format: Value, Range, Corner, List, Increment, Steps

Default: <numeric\_literal*>*

Description:<string>

*Description:* Tells the EDA tool the voltage needed at the receiver data decision point to ensure proper sampling of the equalized signal.

*Usage Rules:* Entries are assumed to be in units of volts.

*Other Notes:*

*Examples:*

In the example below, 100 mV (above +100 mV or below -100 mV is needed to ensure the signal is sampled correctly).

(Rx\_Receiver\_Sensitivity (Usage Info)(Type Float)

(Value 0.1))

(Rx\_Receiver\_Sensitivity (Usage Info)(Type Float)

(List 0.1 0.05 0.06 0.07 0.08 0.09 0.11))

(Rx\_Receiver\_Sensitivity (Usage Info)(Type Float)

(Range 0.2 0.1 0.3))

(Rx\_Receiver\_Sensitivity (Usage Info)(Type Float)

(Corner 0.0 0.1 -0.1))

The following optional Reserved Parameters are used to specify characteristics of the receiver's recovered clock. This data is used by the simulator when post-processing the results from the model when the model does not return clock\_times, or when Rx AMI\_GetWave is not used; the budget values specified by these parameters are not passed directly to the model itself. For Rx models that do return clock\_times by AMI\_GetWave, these parameters represent the amount of jitter THAT HAD ALREADY BEEN IMPLEMENTED BY RX AMI\_GETWAVE AND ALREADY INCLUDED IN THE RETURNED clock\_times. For this reason, the EDA platform should NOT apply these jitter parameters again to the Rx clock\_times. These parameters are provided by the model creator to the EDA platform and end users for the sole purpose that these jitters can be properly accounted for when Rx AMI\_GetWave is NOT used or Rx clock\_times was not returned, in which cases the EDA platform is responsible to apply these jitters to the Rx output."

"Rx\_Clock\_Recovery\_Mean" is an AMI parameter of Type either Float or UI, Format

either Value, List, Range, Corner, Increment, or Steps, and Usage Info which defines

a static offset, in seconds or UI, between the recovered clock and the point half

way between the PDF medians of consecutive eye zero crossings.

*Parameter:* **Rx\_Clock\_Recovery\_Mean**

*Required:* No

*Descriptors*:

Usage: Info

Type: Float or UI

Format: Value, List, Range, Corner, Increment, or Steps

Default: <numeric\_literal*>*

Description:<string>

*Definition:* A static offset between the recovered clock and the point half way between the PDF medians of consecutive eye zero crossings. Entries are assumed to be in units of seconds when declared as Type Float.

*Usage Rules:*

*Other Notes:* actual\_time=ideal\_time+Rx\_Clock\_Recovery\_Mean

ideal\_time half way between the median of the eye crossing 0.0 on both sides of the eye.

*Examples:*

(Rx\_Clock\_Recovery\_Mean (Usage Info)(Value 0.05)

(Type UI)(Description "Recovered Clock offset in UI."))

*Parameter:* **Rx\_Clock\_Recovery\_Rj**

*Required:* No

*Descriptors*:

Usage: Info

Type: Float or UI

Format: Value, List, Range, Corner, Increment, or Steps

Default: <numeric\_literal*>*

Description:<string>

*Definition:* The standard deviation of a Gaussian phase noise exhibited by the recovered clock and included in the clock\_times vector returned by the AMI\_GetWave function. Entries are assumed to be in units of seconds when declared as Type Float.

*Usage Rules:*

*Other Notes:* actual\_time=ideal\_time+Rx\_Clock\_Recovery\_Rj\*gaussian\_rand()

*Examples:*

(Rx\_Clock\_Recovery\_Rj (Usage Info)(Corner 0.005 0.006 0.004)

(Type UI)(Description "RX Random Clock Jitter in UI."))

*Parameter:* **Rx\_Clock\_Recovery\_Dj**

*Required:* No

*Descriptors*:

Usage: Info

Type: Float or UI

Format: Value, List, Range, Corner, Increment, or Steps

Default: <numeric\_literal*>*

Description:<string>

*Definition:* The worst case half the peak to peak variation of the recovered clock. **Rx\_Clock\_Recovery\_Dj** shall include all deterministic and uncorrelated bounded jitter that is included in the clock\_times vector returned by the AMI\_GetWave function and not accounted for by **Rx\_Clock\_Recovery\_DCD** and **Rx\_Clock\_Recovery\_Sj**. Entries are assumed to be in units of seconds when declared as Type Float.

*Usage Rules:*

*Other Notes:* actual\_time = ideal\_time + 2.0\*Rx\_Clock\_Recovery\_Dj\*rand()

*Example:*

(Rx\_Clock\_Recovery\_Dj (Usage Info)(Value 0.1)(Type UI)

(Description "Tx Bounded Jitter in UI."))

*Parameter:* **Rx\_Clock\_Recovery\_Sj**

*Required:* No

*Descriptors*:

Usage: Info

Type: Float or UI

Format: Value, List, Range, Corner, Increment, or Steps

Default: <numeric\_literal*>*

Description:<string>

*Definition:* Half the peak to peak variation of a sinusoidal phase noise exhibited by the recovered clock and included in the clock\_times vector returned by the AMI\_GetWave function. Entries are assumed to be in units of seconds when declared as Type Float.

*Usage Rules:*

*Other Notes:* actual\_time = ideal\_time + Rx\_Clock\_Recovery\_Sj\*sin(Pi\*rand())

*Example:*

(Rx\_Clock\_Recovery\_Sj (Usage Info)(Corner 0.05 0.07 0.4)(Type UI)

(Description "RX Sinusoidal Jitter in UI."))

*Parameter:* **Rx\_Clock\_Recovery\_DCD**

*Required:* No

*Descriptors*:

Usage: Info

Type: Float or UI

Format: Value, List, Range, Corner, Increment, or Steps

Default: <numeric\_literal*>*

Description:<string>

*Definition:* Half the peak to peak variation of a clock duty cycle distortion exhibited by the recovered clock and included in the clock\_times vector returned by the AMI\_GetWave function. Entries are assumed to be in units of seconds when declared as Type Float.

*Usage Rules:*

*Other Notes:* actual\_time=ideal\_time+Rx\_Clock\_Recovery\_DCD\*(-1.0)^n

*Example:*

(Rx\_Clock\_Recovery\_DCD (Usage Info)(Corner 0.008 0.016 0.005)

(Type UI)(Description "RX Duty Cycle Distortion in UI."))

*Other Notes:*

**Rx\_Clock\_Recovery\_Dj** may be used as a repository of all deterministic jitter. However any combination of **Rx\_Clock\_PDF, Rx\_Clock\_Recovery\_Dj**, **Rx\_Clock\_Recovery\_Sj** and **Rx\_Clock\_Recovery\_DCD** is allowed, but the the model maker should make sure that jitter components are not double counted. Total clock recovery deterministic jitter that is included in the clock\_times vector returned by the AMI\_GetWave function should be equal to the sum of **Rx\_Clock\_PDF, Rx\_Clock\_Recovery\_Dj**, **Rx\_Clock\_Recovery\_Sj** and **Rx\_Clock\_Recovery\_DCD**.

Total Clock Recovery Deterministic Jitter accounted for in clock\_times:

actual\_time = ideal\_time + 2.0\*Rx\_Clock\_Recovery\_Dj\*rand()

+ Rx\_Clock\_Recovery\_Sj\*sin(Pi\*rand())

+ Rx\_Clock\_Recovery\_DCD\*(-1.0)^n

+ <deterministic contribution from **Rx\_Clock\_PDF>**

The following optional Reserved Parameters are used to modify the statistics

associated with receiver's recovered clock. These parameters are used to account for

jitter that is not included in either the clock\_times returned by Rx AMI\_GetWave or

the Rx\_Clock\_Recovery parameters. This data is used by the simulator when post-

processing the results from the model; the budget values specified by these

parameters are not passed directly to the model itself.

*Parameter:* **Rx\_Rj**

*Required:* No

*Descriptors*:

Usage: Info

Type: Float or UI

Format: Value, List, Range, Corner, Increment, or Steps

Default: <numeric\_literal*>*

Description:<string>

*Definition:* The standard deviation of a Gaussian phase noise driven by impairments external to the receiver that are input to the RX CDR, but are not included in the CDR clock\_times output. This phase noise is to be accounted for by the EDA tool, in both Statistical and Time-Domain simulations. Entries are assumed to be in units of seconds when declared as Type Float.

*Usage Rules:*

*Other Notes:* clock\_times(n)= time+Rx\_Rj \*gaussian\_rand()

time = ideal\_time in Statistical, and Time-Domain when clock\_times(n) is not available

= clock\_times(n) in Time-Domain when clock\_times(n) is returned by Rx AMI\_Getwave

*Example:*

(Rx\_Rj (Usage Info)(Corner 0.005 0.006 0.004)(Type UI)

(Description "Rx Random Jitter in UI."))

*Parameter:* **Rx\_Dj**

*Required:* No

*Descriptors*:

Usage: Info

Type: Float or UI

Format: Value, List, Range, Corner, Increment, or Steps

Default: <numeric\_literal*>*

Description:<string>

*Definition:* The worst case half peak to peak variation of the recovered clock, not including the random jitter specified by **Rx\_Rj**, **Rx\_Sj**, or **Rx\_DCD**. **Rx\_Dj** shall include all deterministic and uncorrelated bounded jitter that is not accounted for by Rx clock\_times, **Rx\_Rj**, or Rx\_Clock\_Recovery parameters. This phase noise is to be accounted for by the EDA tool in both Statistical and Time-Domain simulations. Entries are assumed to be in units of seconds when declared as Type Float.

*Usage Rules:*

*Other Notes:* actual\_time = time + 2.\*Rx\_Dj\*rand()

time = ideal\_time in Statistical, and Time-Domain when clock\_times(n) is not available

= clock\_times(n) in Time-Domain when clock\_times(n) is returned by Rx AMI\_Getwave

*Example:*

(Rx\_Dj (Usage Info)(Value 0.1)(Type UI)

(Description "Tx Bounded Jitter in UI."))

*Parameter:* **Rx\_Sj**

*Required:* No

*Descriptors*:

Usage: Info

Type: Float or UI

Format: Value, List, Range, Corner, Increment, or Steps

Default: <numeric\_literal*>*

Description:<string>

*Definition:* Half the peak to peak variation of a sinusoidal phase noise, but are not included in the CDR clock\_times output. This phase noise is to be accounted for by the EDA tool in both Statistical and Time-Domain simulations. Entries are assumed to be in units of seconds when declared as Type Float.

*Usage Rules:*

*Other Notes:* actual\_time = time+ Rx\_Sj\*sin(Pi\*rand())

time = ideal\_time in Statistical, and Time-Domain when clock\_times(n) is not available

= clock\_times(n) in Time-Domain when clock\_times(n) is returned by Rx AMI\_Getwave

*Example:*

(Rx\_Sj (Usage Info)(Corner 0.05 0.07 0.04)(Type UI)

(Description "RX Sinusoidal Jitter in UI."))

*Parameter:* **Rx\_DCD**

*Required:* No

*Descriptors*:

Usage: Info

Type: Float or UI

Format: Value, List, Range, Corner, Increment, or Steps

Default: <numeric\_literal*>*

Description:<string>

*Definition:* Half the peak to peak variation of a clock duty cycle distortion. This phase noise is to be accounted for by the EDA tool in both Statistical and Time-Domain simulations. Entries are assumed to be in units of seconds when declared as Type Float.

*Usage Rules:*

*Other Notes:* actual\_time = time + Rx\_DCD\*(-1.0)^n

n is the nth clock

time = ideal\_time in Statistical, and Time-Domain when clock\_times(n) is not available

= clock\_times(n) in Time-Domain when clock\_times(n) is returned by Rx AMI\_Getwave

*Example:*

(Rx\_DCD (Usage Info)(Corner 0.008 0.016 0.005)(Type UI)

(Description "RX Duty Cycle Distortion in UI."))

*Other Notes:*

**Rx \_Dj** may be used as a repository of all deterministic jitter not included in clock\_times. However any combination of **Rx\_ Dj**, **Rx\_ Sj** and **Rx\_ DCD** is allowed, but the the model maker should make sure that jitter components are not double counted. Total clock recovery deterministic jitter that is not included in the clock\_times vector returned by the AMI\_GetWave function should be equal to the sum of **Rx\_ Dj**, **Rx\_ Sj** and **Rx\_ DCD**.

Total Clock Recovery Deterministic Jitter not acounted for in clock\_times:

actual\_time = time + 2.\*Rx\_Dj\*rand()

+ Rx\_Sj\*sin(Pi\*rand())

+ Rx\_DCD\*(-1.0)^n

The following optional Reserved Parameter is used to modify the statistics associated with the data input to the receiver's sampling latch (a.k.a. 'slicer'). This data is used by the simulator when post-processing the results from the model; the budget values specified by this parameter are not passed directly to the model itself.

*Parameter:* **Rx\_Noise**

*Required:* No

*Descriptors*:

Usage: Info or Out

Type: Float

Format: Value, List, Range, Corner, Increment, or Steps

Default: <numeric\_literal*>*

Description:<string>

*Definition:* The standard deviation, in Volts, of a white Gaussian random process, which is to be added by the EDA tool to the signal measured at the sampling latch of a receiver.

*Usage Rules:* If Rx\_Noise is Usage Out, then the EDA tool shall use the value returned by Rx AMI\_Init if Rx AMI\_GetWave is not used. If Rx AMI\_GetWave is used, then the EDA tool may apply the value returned by each AMI\_GetWave call to the waveform returned by that call to AMI\_GetWave, or use the average value of **Rx\_Noise** returned by all calls to AMI\_GetWave (after **Ignore\_Bits**), or the value of **Rx\_Noise** returned by the last call to AMI\_GetWave.

*Other Notes:* wave(t)=wave(t)+Rx\_Noise\*gaussian\_rand()

wave(t) is the waveform returned by Rx AMI\_GetWave

*Example:*

(Rx\_Noise (Usage Info)(Value .010) (Type Float)

(Description "Rx amplitude noise at sampling latch in Volts."))

Note:

The "Rx\_Clock\_Recovery Parameters" (**Rx\_Clock\_PDF**, **Rx\_Clock\_Recovery\_Mean**, **Rx\_Clock\_Recovery\_Rj**, **Rx\_Clock\_Recovery\_Dj**, **Rx\_Clock\_Recovery\_Sj** and **Rx\_Clock\_Recovery\_DCD**, should be used by the simulator when analyzing the output of Rx AMI\_Init (for statistical analysis) or Rx AMI\_GetWave (time domain) when Rx AMI\_GetWave does not return clock\_times. When Rx AMI\_GetWave returns clock\_times, the simulator should not use the "Rx\_Clock\_Recovery Parameters".

Note:

The "Rx Jitter Parameters" (**Rx\_Rj, Rx\_Dj, Rx\_Sj** and **Rx\_DCD**, should be used by the simulator when analyzing the output of either Rx AMI\_Init (for statistical analysis) or Rx AMI\_GetWave (for time domain analysis).

Tables summarizing the rules for the jitter, noise and sensitivity parameters.

Table 17 – Allowed Data Types for Reserved Parameters

|  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- |
| **Reserved Parameter** | **General Rules** | | **Allowed Usage** | | | |
| **Required** | **Default** | **Info** | **In** | **Out** | **InOut** |
| Tx\_Jitter | No | No Jitter | X |  | X3 |  |
| Tx\_Dj | No | 0 | X |  |  |  |
| Tx\_Rj | No | 0 | X |  |  |  |
| Tx\_Sj | No | 0 | X |  |  |  |
| Tx\_DCD | No | 0 | X |  | X3 |  |
| Tx\_Sj\_Frequency | No | Undefined | X |  |  |  |
| Rx\_Receiver\_Sensitivity | No | 0 | X |  | X |  |
| Rx\_Clock\_PDF | No | Clock Centered | X |  |  |  |
| Rx\_Clock\_Recovery\_Mean | No | 0 | X |  |  |  |
| Rx\_Clock\_Recovery\_Dj | No | 0 | X |  |  |  |
| Rx\_Clock\_Recovery\_Rj | No | 0 | X |  |  |  |
| Rx\_Clock\_Recovery\_Sj | No | 0 | X |  |  |  |
| Rx\_Clock\_Recovery\_DCD | No | 0 | X |  |  |  |
| Rx\_Dj | No | 0 | X |  |  |  |
| Rx\_Rj | No | 0 | X |  |  |  |
| Rx\_Sj | No | 0 | X |  |  |  |
| Rx\_DCD | No | 0 | X |  |  |  |
| Rx\_Noise | No | 0 | X |  | X |  |

Table 18 – Allowed Data Types for Reserved Parameters

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Reserved Parameter** | **Data Type** | | | | |
| **Float** | **UI** | **Integer** | **String** | **Boolean** |
| Tx\_Jitter |  | X |  |  |  |
| Tx\_Dj |  | X |  |  |  |
| Tx\_Rj |  | X |  |  |  |
| Tx\_Sj |  | X |  |  |  |
| Tx\_DCD | X | X |  |  |  |
| Tx\_Sj\_Frequency | X |  |  |  |  |
| Rx\_Receiver\_Sensitivity | X |  |  |  |  |
| Rx\_Clock\_PDF | X | X |  |  |  |
| Rx\_Clock\_Recovery\_Mean | X | X |  |  |  |
| Rx\_Clock\_Recovery\_Dj | X | X |  |  |  |
| Rx\_Clock\_Recovery\_Rj | X | X |  |  |  |
| Rx\_Clock\_Recovery\_Sj | X | X |  |  |  |
| Rx\_Clock\_Recovery\_DCD | X | X |  |  |  |
| Rx\_Dj | X | X |  |  |  |
| Rx\_Rj | X | X |  |  |  |
| Rx\_Sj | X | X |  |  |  |
| Rx\_DCD | X | X |  |  |  |
| Rx\_Noise | X |  |  |  |  |

Table 19 – Allowed Data Formats for Reserved Parameters

|  |  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
| **Reserved Parameter** | **Data Format** | | | | | | | | | |
| **Value** | **Range** | **Corner** | **List** | **Increment** | **Steps** | **Gaussian** | **Dual-Dirac** | **DjRj** | **Table** |
| Tx\_Jitter |  |  |  |  |  |  | X | X | X | X |
| Tx\_Dj | X | X | X | X | X | X |  |  |  |  |
| Tx\_Rj | X | X | X | X | X | X |  |  |  |  |
| Tx\_Sj | X | X | X | X | X | X |  |  |  |  |
| Tx\_DCD | X | X | X | X | X | X |  |  |  |  |
| Tx\_Sj\_Frequency | X | X | X | X | X | X |  |  |  |  |
| Rx\_Receiver\_Sensitivity | X | X | X | X | X | X |  |  |  |  |
| Rx\_Clock\_PDF |  |  |  |  |  |  | X | X | X | X |
| Rx\_Clock\_Recovery\_Mean | X | X | X | X | X | X |  |  |  |  |
| Rx\_Clock\_Recovery\_Dj | X | X | X | X | X | X |  |  |  |  |
| Rx\_Clock\_Recovery\_Rj | X | X | X | X | X | X |  |  |  |  |
| Rx\_Clock\_Recovery\_Sj | X | X | X | X | X | X |  |  |  |  |
| Rx\_Clock\_Recovery\_DCD | X | X | X | X | X | X |  |  |  |  |
| Rx\_Dj | X | X | X | X | X | X |  |  |  |  |
| Rx\_Rj | X | X | X | X | X | X |  |  |  |  |
| Rx\_Sj | X | X | X | X | X | X |  |  |  |  |
| Rx\_DCD | X | X | X | X | X | X |  |  |  |  |
| Rx\_Noise | X | X | X | X | X | X |  |  |  |  |

With the exception of the "Table" format, the Tx\_Jitter parameter has been essentially superseded by the Reserved\_Parameters Tx\_Rj, Tx\_Dj, Tx\_Sj, Tx\_Sj\_Frequency, and Tx\_DCD, which enable SerDes transmitter jitter to be specified in greater detail. It is recommended for AMI model developers to use these preferred jitter parameters when possible instead of Tx\_Jitter.With the exception of the "Table" format, the Rx\_Clock\_PDF parameter has been essentially superseded by the Reserved\_Parameters Rx\_Clock\_Recovery\_Rj, Rx\_Clock\_Recovery\_Dj, Rx\_Clock\_Recovery\_Sj, and Rx\_Clock\_Recovery\_DCD, which enable SerDes receiver jitter to be specified in greater detail. It is recommended for AMI model developers to use these preferred jitter parameters when possible instead of Rx\_Clock\_PDF.

RESERVED PARAMETER AND DATA TYPE RULE SUMMARY TABLES

The tables below summarize the valid combinations of Reserved Parameters, defaults, Data Types and Data Formats.

Table – General Rules and Allowed Usage for Reserved Parameters

|  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- |
| **Reserved Parameter** | **General Rules** | | **Allowed Usage** | | | |
| **Required** | **Default** | **Info** | **In** | **Out** | **InOut** |
| AMI\_Version1 | Yes | -- | X |  |  |  |
| Init\_Returns\_Impulse | Yes | -- | X |  |  |  |
| GetWave\_Exists | Yes | -- | X |  |  |  |
| Use\_Init\_Output2 | No | True | X |  |  |  |
| Ignore\_Bits | No | 0 | X |  |  |  |
| Max\_Init\_Aggressors | No | 0 | X |  |  |  |
| Tx\_Jitter | No | No Jitter | X |  | X3 |  |
| Tx\_DCD | No | 0 | X |  | X3 |  |
| Rx\_Receiver\_Sensitivity | No | 0 | X |  | X |  |
| Rx\_Clock\_PDF | No | Clock Centered | X |  | X |  |
| Supporting\_Files | No | -- | X |  |  |  |
| DLL\_Path | No | -- |  | X |  |  |
| DLL\_ID | No | -- |  | X |  |  |
| Repeater\_Type | No | -- | X |  |  |  |

1. Required for AMI\_Version 5.1 and later, and illegal before AMI\_Version 5.1
2. Illegal for AMI\_Version 5.1 and later
3. Illegal for AMI\_Version 6.0 and later

Table – Allowed Data Types for Reserved Parameters

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Reserved Parameter** | **Data Type** | | | | |
| **Float** | **UI** | **Integer** | **String** | **Boolean** |
| AMI\_Version1 |  |  |  | X |  |
| Init\_Returns\_Impulse |  |  |  |  | X |
| GetWave\_Exists |  |  |  |  | X |
| Use\_Init\_Output2 |  |  |  |  | X |
| Ignore\_Bits |  |  | X |  |  |
| Max\_Init\_Aggressors |  |  | X |  |  |
| Tx\_Jitter | X | X |  |  |  |
| Tx\_DCD | X | X |  |  |  |
| Rx\_Receiver\_Sensitivity | X |  |  |  |  |
| Rx\_Clock\_PDF | X | X |  |  |  |
| Supporting\_Files |  |  |  | X |  |
| DLL\_Path |  |  |  | X |  |
| DLL\_ID |  |  |  | X |  |
| Repeater\_Type |  |  |  | X |  |

1. Required for AMI\_Version 5.1 and later, and illegal before AMI\_Version 5.1
2. Illegal for AMI\_Version 5.1 and later

Table – Allowed Data Formats for Reserved Parameters

|  |  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
| **Reserved Parameter** | **Data Format** | | | | | | | | | |
| **Value** | **Range** | **Corner** | **List** | **Increment** | **Steps** | **Gaussian** | **Dual-Dirac** | **DjRj** | **Table** |
| AMI\_Version1 | X |  |  |  |  |  |  |  |  |  |
| Init\_Returns\_Impulse | X |  |  |  |  |  |  |  |  |  |
| GetWave\_Exists | X |  |  |  |  |  |  |  |  |  |
| Use\_Init\_Output2 | X |  |  |  |  |  |  |  |  |  |
| Ignore\_Bits | X |  |  |  |  |  |  |  |  |  |
| Max\_Init\_Aggressors | X |  |  |  |  |  |  |  |  |  |
| Tx\_Jitter |  |  |  |  |  |  | X | X | X | X |
| Tx\_DCD | X | X | X | X | X | X |  |  |  |  |
| Rx\_Receiver\_Sensitivity | X | X | X | X | X | X |  |  |  |  |
| Rx\_Clock\_PDF |  |  |  |  |  |  | X | X | X | X |
| Supporting\_Files |  |  |  |  |  |  |  |  |  | X |
| DLL\_Path | X |  |  |  |  |  |  |  |  |  |
| DLL\_ID | X |  |  |  |  |  |  |  |  |  |
| Repeater\_Type | X |  |  |  |  |  |  |  |  |  |

1. Required for AMI\_Version 5.1 and later, and illegal before AMI\_Version 5.1
2. Illegal for AMI\_Version 5.1 and later

Table 23 summarizes the relationships between the different Format and Data Types for Reserved or Model Specific Parameters.

Table – Allowed Data Types for Format Values

|  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- |
| **Format** | **Data Type** | | | | | |
| **Float** | **UI** | **Integer** | **String** | **Boolean** | **Tap** |
| Value | X | X | X | X | X | X |
| Range | X | X | X |  |  | X |
| Corner | X | X | X | X | X | X |
| List | X | X | X | X | X | X |
| Increment | X | X | X |  |  | X |
| Steps | X | X | X |  |  | X |
| Gaussian | X | X |  |  |  |  |
| Dual-Dirac | X | X |  |  |  |  |
| DjRj | X | X |  |  |  |  |
| Table | X | X | X | X | X |  |

MODEL SPECIFIC PARAMETERS

The following section describes the Model Specific (user-defined) Parameters. The model maker can specify any number of Model Specific Parameters for their model. The Model Specific Parameter branch shall begin with the reserved words “Model\_Specific”.

*Example:*

(Model\_Specific

(CTLE

(Description "CTLE consists of two selectable sets of Poles and Zeros")

(Row (Range 0 0 1)(Type Integer)(Usage InOut)(Description "Two CTLEs"))

(Poles (Usage In)(Description "CTLE Poles")

(Type Integer Float Float Float Float Float Float)

(Table

(Labels "Row" "Real\_1" "Imag\_1" "Real\_2" "Imag\_2" "Real\_3" "Imag\_3")

(0 -3.06e+9 9.94e+9 -2.91e+9 5.94e+9 -1.36e+9 0.0)

(1 -1.03e+10 0.0 -4.21e+9 5.42e+9 0.0 0.0)

)

)

(Zeros (Usage In)(Description "CTLE Zeros")

(Type Integer Float Float Float Float)

(Table

(Labels "Row" "Real\_1" "Imag\_1" "Real\_2" "Imag\_2")

(0 -3.62e+9 0.0 -2.33e+9 6.68e+9)

(1 -2.93e+9 1.10e+9 0.0 0.0)

)

)

)

)

**TAPPED DELAY LINE EXAMPLE**

A tapped delay line can be described by creating a separate parameter for each tap weight and grouping all the tap weights for a given tapped delay line in a single parameter group which is given the name of the tapped delay line. If in addition the individual tap weights are each given a name which is their tap number (i.e., "-1" is the name of the first precursor tap, "0" is the name of the main tap, "1" is the name of the first postcursor tap, etc.) and the tap weights are declared to be of type Tap, then the EDA tool can assume that the individual parameters are tap weights in a tapped delay line, and use that assumption to perform tasks such as optimization. The model developer is responsible for choosing whether or not to follow this convention.

The type Tap implies that the parameter takes on floating point values. Note that if the type Tap is used and the parameter name is not a number, this is an error condition for which EDA tool behavior is not specified.

*Example:*

(mySampleAMI | Parameter Definition File name

(Description "Sample AMI File")

(Reserved\_Parameters | Required heading

(AMI\_Version (Usage Info)(Type String)(Value "5.1")

(Description "Valid for AMI\_Version 5.1 and above"))

(Ignore\_Bits (Usage Info)(Type Integer)(Value 21)

(Description "Ignore 21 Bits"))

(Max\_Init\_Aggressors (Usage Info)(Type Integer)(Value 25))

(Init\_Returns\_Impulse (Usage Info)(Type Boolean)(Value True))

(GetWave\_Exists (Usage Info)(Type Boolean)(Value True))

) | End Reserved\_Parameters

(Model\_Specific | Required heading

(txtaps

(-2 (Usage InOut)(Type Tap)(Range 0.1 -0.1 0.2)

(Description "Second Precursor Tap"))

(-1 (Usage InOut)(Type Tap)(Range 0.2 -0.4 0.4)

(Description "First Precursor Tap"))

(0 (Usage InOut)(Type Tap)(Range 1 0.4 1)

(Description "Main Tap"))

(1 (Usage InOut)(Type Tap)(Range 0.2 -0.4 0.4)

(Description "First Postcursor Tap"))

(2 (Usage InOut)(Type Tap)(Range 0.1 -0.1 0.2)

(Description "Second Postcursor Tap"))

) | End txtaps

) | End Model\_Specific

) | End mySampleAMI

# Repeaters

A Repeater is a type of device that is placed in the middle of the channel to compensate channel loss. Repeater has two categories, Redriver and Retimer. A Redriver equalizes the upstream channel signal and retransmits it to the downstream channel. The output signal is continuously driven by the input signal. A Redriver does not have a CDR, and no retiming is performed when the Redriver retransmits the signal. A Retimer equalizes the upstream channel signal, recovers the clock using a CDR and generates a digital stimulus that is transmitted to the downstream channel.

A Repeater is modeled by two back-to-back input-output IBIS-AMI models as shown in Fig. 1.

Rx

analog

model

Rx

algorithmic

model

Tx

algorithmic

model

Tx

analog

model

Repeater model

Rx IBIS model

Tx IBIS model

Figure 1: Repeater model

The analog part of the Rx model represents the input termination at the device input. The analog part of the Tx model represents the output impedance at the device output. The two algorithmic models represent equalizations, clock data recovery or CDR (if it exists) and pre-emphasis inside the device. In a Redriver, both algorithmic models can optionally implement the AMI\_GetWave function. In a Retimer, the Rx algorithmic model must implement AMI\_GetWave and the function must return clock ticks. The Retimer Tx algorithmic model can optionally implement AMI\_GetWave. The order of signal flow in a Repeater model is from Rx analog to Rx algorithmic to Tx algorithmic to Tx analog. Looking from the Rx analog portion, the Rx algorithmic block is assumed to have infinite input impedance. Looking from the Tx analog portion, the Tx algorithmic block is assumed to have an output of an ideal voltage source.

A Repeater model is specified in a single .ibs file that includes both input and output models. An example redriver.ibs file is:

[IBIS Ver] 5.2

[File Name] Redriver.ibs

[Component] Redriver

…

[Pin] signal\_name model\_name R\_pin L\_pin C\_pin

1p Redriver\_Rx\_1p Redriver\_Rx

1n Redriver\_Rx\_1n Redriver\_Rx

2p Redriver\_Tx\_2p Redriver\_Tx

2n Redriver\_Tx\_2n Redriver\_Tx

[Diff\_Pin] inv\_pin vdiff tdelay\_typ tdelay\_min tdelay\_max

1p 1n NA NA NA NA

2p 2n NA NA NA NA

[Repeater Pin]

1p 2p

[Model] Redriver\_Rx

Model\_type Input

…

[Algorithmic Model]

Executable Windows\_VisualStudio10.0.30319\_32 Redriver\_Rx\_32.dll Redriver\_Rx.ami

Executable Windows\_VisualStudio10.0.30319\_64 Redriver\_Rx\_64.dll Redriver\_Rx.ami

Executable Linux\_gcc4.6.1\_32 Redriver\_Rx\_32.so Redriver\_Rx.ami

Executable Linux\_gcc4.6.1\_64 Redriver\_Rx\_64.so Redriver\_Rx.ami

[End Algorithmic Model]

[Model] Redriver\_Tx

Model\_type Output

…

[Algorithmic Model]

Executable Windows\_VisualStudio10.0.30319\_32 Redriver\_Tx\_32.dll Redriver\_Tx.ami

Executable Windows\_VisualStudio10.0.30319\_64 Redriver\_Tx\_64.dll Redriver\_Tx.ami

Executable Linux\_gcc4.6.1\_32 Redriver\_output\_32.so Redriver\_Tx.ami

Executable Linux\_gcc4.6.1\_64 Redriver\_output\_64.so Redriver\_Tx.ami

[End Algorithmic Model]

[End]

New AMI Reserved Parameters:

The Rx AMI model of a Repeater must have the Reserved Parameter “Repeater\_Type”. This is a String parameter with either the value “Retimer” or “Redriver”.

As mentioned above, a Retimer Rx must has AMI\_GetWave (GetWave\_Exist = True) and the AMI\_GetWave function must return clock\_ticks. The simulation platform shall generate a digital input to the Retimer Tx by sampling the Rx AMI\_GetWave output waveform ½ UI after each clock tick, The digital stimulus shall have values of -½ and +½.

In Repeater AMI simulations, both Repeater analog models are treated as if they are linear and time-invariant. The incoming (upstream) analog channel of the Redriver, including the upstream Tx analog model, the physical channel and the Repeater Rx analog model, is represented by an impulse response. The outgoing (downstream) analog channel of the Repeater, including the Repeater Tx analog model, the physical channel and the downstream Rx analog model, is represented by another impulse response.

The time domain simulation flow for a Repeater link shown in Figure 2 is defined below.

Repeater

Rx

Tx1

Rx1

Tx2

Rx2

channel 1

channel 2

Repeater

Repeater Tx

Incoming

(upstream)

channel

outgoing

(downstream)

channel

Figure 2: Repeater link

Here Tx1 denotes the Repeater upstream channel (channel 1) Tx AMI model (including analog and algorithmic models), Rx1 the Repeater Rx AMI model (including analog and algorithmic models), Tx2 the Repeater Tx AMI model (including analog and algorithmic models) and Rx2 the Repeater downstream channel (channel 2) Rx AMI model (including analog and algorithmic models).

Step 1. The simulation platform obtains the impulse response of the upstream analog channel, which represents the combined impulse response of Tx1’s analog model, physical channel 1, and Rx1’s analog model.

Step 2. The output of step 1 is presented to Tx1’s AMI\_Init function and Tx1’s AMI\_Init function is executed.

Step 3. The output of step 2 is presented to Rx1’s AMI\_Init function and Rx1’s AMI\_Init function is executed.

Step 4. The simulation platform obtains the impulse response of the downstream analog channel, which represents the combined impulse response of Tx2’s analog model, physical channel 2, and Rx2’s analog model.

Step 5. The output of step 4 is presented to Tx2’s AMI\_Init function and Tx2’s AMI\_Init function is executed.

Step 6. The output of step 5 is presented to Rx2’s AMI\_Init function and Rx2’s AMI\_Init function is executed.

Step 7. The simulation platform performs simulation on the upstream channel, which consists of Tx1, physical channel 1, and Rx1, according to the AMI flow defined in the specification for channels without Repeaters.

Step 8a. Redriver: The simulation platform uses the signal waveform at the output end of Rx1’s algorithmic model in step 7, regardless whether Rx1’s AMI\_GetWave exists or not, as the stimulus of Tx2’s algorithmic model, regardless whether Tx2’s AMI\_GetWave exists or not, and performs simulation on the downstream channel, which consists of Tx2, physical channel 2 and Rx2, according to the AMI flow defined in the spec for channels without Redrivers.

Step 8b. Retimer: The simulation platform samples the output waveform of Retimer Rx AMI\_GetWave at ½ UI after each clock tick returned by the function, generates a digital stimulus as the input to Tx2’s algorithmic model, regardless whether Tx2’s AMI\_GetWave exists or not, and performs simulation on the downstream channel, which consists of Tx2, physical channel 2 and Rx2, according to the AMI flow defined in the spec for channels without Redriver. The logic level of the digital stimulus is 1 if sampled value >= Rx1’s Rx\_Receiver\_Sensitivity and 0 if sampled value <= Rx1’s Rx\_Receiver\_Sensitivity. If –Rx1’s Rx\_Receiver\_Sensitivity < sampled value < Rx1’s Rx\_Reciver\_Sensitivity, the logic level is unchanged from the previous bit. The digital stimulus have values of -½ volt for logic 0 and +½ volt for logic 1.

Step 9. The simulation platform calls the AMI\_Close function of each algorithmic model in Tx1, Rx1, Tx2 and Rx2.

Since the Redriver output signal is driven continuously by the input analog signal and does not have a sampling latch, clock times, if returned by a Redriver model, jitter parameters and the Rx\_Noise parameter specified in Redriver .ami files are ignored by the simulation platform. Since the Retimer output signal is driven by a digital stimulus as described above in step 8b, jitter and noise parameters specified in Retimer .ami files are applied according to the specification for channels without Repeaters.

The statistical simulation flow for a Repeater link shown in Fig. 2 is defined below.

Step 1. The simulation platform obtains the impulse response of the upstream analog channel, which represents the combined impulse response of Tx1’s analog model, physical channel 1, and Rx1’s analog model.

Step 2. The output of step 1 is presented to the Tx1’s AMI\_Init function and Tx1’s AMI\_Init function is executed.

Step 3. The output of step 2 is presented to the Rx1’s AMI\_Init function and the Rx1’s AMI\_Init function is executed.

Step 4. The simulation platform obtains the impulse response of the downstream analog channel, which represents the combined impulse response of Tx2’s analog model, physical channel 2, and Rx2’s analog model.

Step 5. The output of step 4 is presented to Tx2’s AMI\_Init function and Tx2’s AMI\_Init function is executed.

Step 6. The output of step 5 is presented to Rx2’s AMI\_Init function and Rx2’s AMI\_Init function is executed.

Step 7a. Redriver: The simulation platform convolves impulse responses returned by Rx1’s AMI\_Init in step 3 and by Rx2’s AMI\_Init in step 6 to obtained the full channel impulse response and uses it to perform statistical simulation.

Step 7b. Retimer: The simulation platform uses the impulse responses returned by Rx1’s AMI\_Init in step 3 to perform a statistical simulation of channel 1. The simulation platform uses the impulse responses returned by Rx2’s AMI\_Init in step 6 to perform a statistical simulation of channel 2.

A mixture of Redrivers and Retimers can be cascaded in a channel.

# EMI Parameters

There are two sections here: one for a [Component] and one for a [Model].

This section describes the structure of the EMI parameters under a top-level [Component] keyword. It is used to describe the EMI parameters associated with a [Component]. The parameters shall be surrounded by the [Begin EMI Component] and [End EMI Component] keywords.

The following keywords are defined:

[Begin EMI Component]

[End EMI Component]

[Pin EMI]

[Pin Domain EMI]

The following subparameters are defined:

Domain

Cpd

C\_Heatsink\_gnd

C\_Heatsink\_float

*Keyword:* [Begin EMI Component]

*Required:* No

*Description:* Marks the beginning of the Component EMI parameters.

*Sub-Params:* Domain, Cpd, C\_Heatsink\_gnd, C\_Heatsink\_float

Domain indicates whether the component is digital, analog, or part digital part analog. Analog circuits are more susceptible to low-level noise. Analog circuits operate at very low signal levels (mV or uV) and can contain high gain amplifiers. In contrast, digital circuits operate at relatively large signal levels (compared to analog circuits).

The syntax for Domain is:

Domain Domain\_value

Where Domain\_value is an enumerated argument, and is one of:

Digital, Analog, Digital\_analog

This subparameter is optional. If not entered, the default is Digital.

Cpd is the power dissipation capacitance parameter. Cpd (Power Dissipation Capacitance) is the internal parasitic capacitance (e.g., gate-to-source and gate-to-drain capacitance) plus the equivalent capacitance associated with the through currents when both transistors (n-channel and p-channel) are momentarily conducting.

Cpd is typically for CMOS devices, and helps provide a more accurate estimation of the power bus current, and therefore the noise voltage on the power bus. If the high frequency noise on the power bus (due to switching of digital circuits) is known, then the radiation can be calculated.

Sometimes Iccd (Dynamic power supply current) is found in databooks. It is normally given for FACT families. Iccd is specified in units of mA/MHz.

Cpd can be calculated from Iccd by the equation:

*Cpd (nF) = Iccd (mA/MHz) / Vcc (V).*

The syntax for Cpd is:

Cpd = capacitance\_value

The units of capacitance\_value are farads.

This subparameter is optional. If not entered, the default is 0.0 F.

C\_Heatsink\_Float and C\_Heatsink\_Gnd define the heatsink capacitance and connection conditions. C\_Heatsink\_Float indicates that the heatsink is floating, and C\_Heatsink\_Gnd indicates that the heatsink is grounded.

Internal currents inside a (high speed) IC can be closely coupled onto a heatsink. As the heatsink is physically much larger than the IC silicon chip and bond wires, it is a more efficient radiator. Knowing the capacitance of the heatsink the radiated electric field can be estimated.

Only one of these subparameters can be defined. It is not legal to define both. It is legal to omit both. In this case it means that a heatsink is not present.

The subparameter takes one argument: the heatsink capacitance

The syntax for Heatsink\_cap is:

C\_Heatsink\_float = capacitance\_value

C\_Heatsink\_gnd = capacitance\_value

The units for capacitance\_value are farads.

This subparameter is optional. If not entered, the default is that the component does not have a heatsink.

*Keyword:* [End EMI Component]

*Required:* No

*Description:* Marks the end of the Component EMI parameters.

*Example:*

[Begin EMI Component]

Domain Digital

Cpd = 6.4pF

C\_Heatsink\_gnd = 3.4pF

[End EMI Component]

*Keyword:* [Pin EMI]

*Required:* No

*Description:* Specifies the EMI parameters for a Pin.

*Sub-Params:* domain\_name, clock\_div

*Usage Rules:* Each line must contain three columns. The first column shall contain the pin name. This pin name shall match a pin name in the [Pin] keyword. (The pin name is the first column in the [Pin] record.)

The second column is the domain name. This specifies the clock domain for that pin. This is used by [Pin Domain EMI]. The field should be set to NA if unused.

The default for domain\_name is that the percentage of power used is 100%.

The third column is the clock division. This is the ratio of the frequency at this pin to the reference pin. The reference pin is always set to “1.0”. The ratio is a floating point number. The choice of the reference pin does not matter as this information is pin to pin ratios. It is suggested that the pin with the maximum frequency is chosen as the reference.

The field should be set to NA if unused.

The default for clock\_div is 1.0

Column length limits are:

pin\_name 5 characters max

domain\_name 20 characters max

clock\_div 5 characters max

It is not a requirement to specify every pin. An undefined pin will default to 100% power usage for Domain\_name, and 1.0 for clock\_div.

*Keyword:* [Pin Domain EMI]

*Required:* No

*Description:* Specifies the percentage of power used in each clock domain.

Sub-Params: percentage

*Usage Rules:* Each line must contain two columns. The first column must contain the domain\_name. This name must match a domain name in the [Pin EMI] keyword. (The domain name is the second column in that record.)

The percentage represents a user definable percentage of the power used by that domain. It is an integer in the range 0 < percentage =< 100

Column length limits are:

domain\_name 20 characters max

percentage 5 characters max

*Example:*

[Begin EMI Component]

Domain Digital

Cpd = 6.4pF

|

[Pin EMI] domain\_name clock\_div

4 MEM 0.5

5 MEM 0.5

7 NA 0.5 | domain\_name defaults to 100%

8 RIOG NA | clock\_div defaults to 1.0

14 CPU 1.0

15 RIOG 0.5

|

[Pin Domain EMI] percentage

CPU 40

MEM 30

RIOG 30

|

[End EMI Component]

This section describes the structure of the EMI parameters under a top-level [Model] keyword. It is used to describe the EMI parameters associated with a [Model]. The parameters must be surrounded by the [Begin EMI Model] and [End EMI Model] keywords.

The following keywords are defined:

[Begin EMI Model]

[End EMI Model]

The following subparameters are defined:

Model\_emi\_type

Model\_Domain

*Keyword:* [Begin EMI Model]

*Required:* No

*Description:* Marks the beginning of the Model EMI parameters.

*Sub-Params:* Model\_emi\_type, Domain

Model\_emi\_type indicates whether the model (for this pin) is a ferrite or not.

The syntax for Model\_emi\_type is:

Model\_emi\_type Model\_emi\_type\_value

Where Model\_emi\_type\_value is an enumerated argument, and is one of:

Ferrite, Not\_a\_ferrite

If not entered (the default), the model is Not\_a\_ferrite.

Model\_Domain indicates whether the model is digital or analog. This is only used if the [Component EMI] Domain is set to Digital\_analog. If the [Component EMI] Domain is set to anything else, Model\_Domain is ignored.

The syntax for Domain is:

Model\_Domain Domain\_value

Where Domain\_value is one of:

Digital, Analog

If not entered, the default is to use the [Component EMI] Domain setting and its default.

*Keyword:* [End EMI Model]

*Required:* No

*Description:* Marks the end of the Model EMI parameters.

*Example:*

[Begin EMI Model]

Domain Analog

Model\_emi\_type Ferrite

[End EMI Model]