**BUFFER ISSUE RESOLUTION DOCUMENT (BIRD)**

**BIRD NUMBER:** 129.1

**ISSUE TITLE:** Add "polarity" Argument to D\_to\_A Converters

**REQUESTOR:**  Arpad Muranyi, Mentor Graphics

**DATE SUBMITTED:** March 24, 2011

**DATE REVISED:** March 14, 2013

**DATE ACCEPTED BY IBIS OPEN FORUM:** Rejected April 26, 2013

**STATEMENT OF THE ISSUE:**

[External Model]s and [External Circuit]s with analog ports communicate through A\_to\_D and/or D\_to\_A converters with the purely digital signals of the EDA tool. The current specification assumes that true differential buffer models have a single analog input for the input stimulus. However, in some situations it may be desirable to allow the model maker to make differential buffer models with two analog ports for the stimulus input, one using a direct, and the other using an inverted stimulus signal.

This can be easily achieved by defining two D\_to\_A converters, both connected to D\_drive, one driving the direct analog port and the other driving the inverted analog port of a differential model. The current specification does not prohibit the usage of multiple D\_to\_A converters with the same digital control ports (such as D\_drive or D\_enable). The only problem with the current specification is that it requires that vlow is less than vhigh for the D\_to\_A converter's parameters which prevents the possibility to make use of the same voltage (and edge rate) parameters for two D\_to\_A converters used in such a differential arrangement.

The simplest solution to this problem is to add one more (optional) argument to the D\_to\_A converter syntax which would tell the EDA tool to implement the converted in an inverting mode.

**ANALYSIS PATH/DATA THAT LED TO SPECIFICATION:**

Another option was also considered, which would simply remove the requirement of vlow < vhigh. This idea was discarded because this syntax can get rather confusing considering that the name of these arguments in the header line are "vlow" and "vhigh", and the corresponding trise and tfall are both entered as positive values.

BIRD 129.1 was issued to update the changes proposed in BIRD 129 to be based on the IBIS v5.1 Specification and to be consistent with its new format.

**ANY OTHER BACKGROUND INFORMATION:**

This BIRD is driven by the effort of simplifying the parameterization of the analog AMI model parameters when they are defined by the reserved word AMIfile() making use of parameters in the .ami parameter file (as described in BIRD 117 and 118). Without this change, the inverting and non-inverting D\_to\_A converters of a true differential analog model would require their own (duplicate) set of parameters which makes the content of the .ami files unnecessarily cluttered.

As this BIRD is superseded by BIRD160.1, this BIRD was rejected by the IBIS Open Forum at its April 26, 2013 teleconference.

*Keywords:* [External Model], [End External Model]

*Required:* No

*Description:* Used to reference an external file written in one of the supported languages containing an arbitrary circuit definition, but having ports that are compatible with the [Model] keyword, or having ports that are compatible with the [Model] keyword plus an additional signal port for true differential buffers.

*Sub-Params:* Language, Corner, Parameters, Ports, D\_to\_A, A\_to\_D

*Usage Rules:* The [External Model] keyword must be positioned within a [Model] section and it may only appear once for each [Model] keyword in a .ibs file. It is not permitted under the [Submodel] keyword.

[Circuit Call] may not be used to connect an [External Model].

A native IBIS [Model]’s data may be incomplete if the [Model] correctly references an [External Model]. Any native IBIS keywords that are used in such a case must contain syntactically correct data and subparameters according to native IBIS rules. In all cases, [Model]s which reference [External Model]s must include the following keywords and subparameters:

Model\_type

Vinh, Vinl (as appropriate to Model\_type)

[Voltage Range] and/or [Pullup Reference], [Pulldown Reference], [POWER Clamp Reference], [GND Clamp Reference], [External Reference]

[Ramp]

In models without the [External Model] keyword, data for [Ramp] should be measured using a load that conforms to the recommendations in Section 9, "NOTES ON DATA DERIVATION METHOD". However, when used within the scope of [External Model], the [Ramp] keyword is intended strictly to provide EDA tools with a quick first-order estimate of driver switching characteristics. When using [External Model], therefore, data for [Ramp] may be measured using a different load, if it results in data that better represent the driver’s behavior in standard operation. Also in this case, the R\_load subparameter is optional, regardless of its value, and will be ignored by EDA simulators. For example, the 20% to 80% voltage and time intervals for a differential buffer may be measured using the typical differential operating load appropriate to that buffer’s technology. Note that voltage and time intervals must always be recorded explicitly rather than as a reduced fraction, in accordance with [Ramp] usage rules.

The following keywords and subparameters may be omitted, regardless of Model\_type, from a [Model] using [External Model]:

C\_comp, C\_comp\_pullup, C\_comp\_pulldown, C\_comp\_power\_clamp, C\_comp\_gnd\_clamp

[Pulldown], [Pullup], [POWER Clamp], [GND Clamp]

Subparameter Definitions:

Language:

Accepts “SPICE”, “VHDL-AMS”, “Verilog-AMS”, “VHDL-A(MS)” or “Verilog-A(MS)” as arguments. The Language subparameter is required and must appear only once.

Corner:

Three entries follow the Corner subparameter on each line:

corner\_name file\_name circuit\_name

The corner\_name entry is “Typ”, “Min”, or “Max”. The file\_name entry points to the referenced file in the same directory as the .ibs file.

Up to three Corner lines are permitted. A “Typ” line is required. If “Min” and/or “Max” data is missing, the tool may use “Typ” data in its place. However, the tool should notify the user of this action.

Models instantiated by corner\_name "Min" describe slow, weak performance, and models instantiated by corner\_name "Max" describe fast, strong performance.

The circuit\_name entry provides the name of the circuit to be simulated within the referenced file. For SPICE files, this is normally a “.subckt” name. For VHDL-AMS files, this is normally an “entity(architecture)” name pair. For Verilog-AMS files, this is normally a “module” name.

No character limits, case-sensitivity limits or extension conventions are required or enforced for file\_name and circuit\_name entries. However, the total number of characters in each Corner line must comply with the rules in Section 3. Furthermore, lower-case file\_name entries are recommended to avoid possible conflicts with file naming conventions under different operating systems. Case differences between otherwise identical file\_name entries or circuit\_name entries should be avoided. External languages may not support case-sensitive distinctions.

Parameters:

Lists names of parameters that can be passed into an external model file. Each Parameters assignment must match a name or keyword in the external file or language. The list of Parameters may span several lines by using the word Parameters at the start of each line. The Parameters subparameter is optional, and the external model must operate with default settings without any Parameters assignments.

Parameter passing is not supported in SPICE. VHDL-AMS and VHDL-A(MS) parameters are supported using “generic” names, and Verilog-AMS and Verilog-A(MS) parameters are supported using “parameter” names.

Ports:

Ports are interfaces to the [External Model] which are available to the user and tool at the IBIS level. They are used to connect the [External Model] to die pads. The Ports parameter is used to identify the ports of the [External Model] to the simulation tool. The port assignment is by position and the port names do not have to match exactly the names inside the external file. The list of port names may span several lines if the word Ports is used at the start of each line.

Model units under [External Model] may only use reserved ports. The reserved, pre-defined port names are listed in the General Assumptions heading above. As noted earlier, digital and analog reserved port functions will be assumed by the tool and connections made accordingly. All the ports appropriate to the particular Model\_type subparameter entry must be explicitly listed (see below). Note that the user may connect SPICE, Verilog-A(MS) and VHDL-A(MS) models to A\_to\_D and D\_to\_A converters using custom names for analog ports within the model unit, as long as the digital ports of the converters use the digital reserved port names.

The rules for pad connections with [External Model] are identical to those for [Model]. The [Pin Mapping] keyword may be used with [External Model]s but is not required. If used, the [External Model] specific voltage supply ports—A\_puref, A\_pdref, A\_gcref, A\_pcref, and A\_extref—are connected as defined under the [Pin Mapping] keyword. In all cases, the voltage levels connected on the reserved supply ports are defined by the [Power Clamp Reference], [GND Clamp Reference], [Pullup Reference], [Pulldown Reference], and/or [Voltage Range] keywords, as in the case of [Model].

Digital-to-Analog/Analog-to-Digital Conversions:

These subparameters define all digital-to-analog and analog-to-digital converters needed to properly connect digital signals with the analog ports of referenced external SPICE, Verilog-A(MS) or VHDL-A(MS) models. These subparameters must be used when [External Model] references a file written in the SPICE, Verilog-A(MS), or VHDL-A(MS) languages. They are not permitted with Verilog-AMS or VHDL-AMS external files.

D\_to\_A:

As assumed in [Model], some interface ports of [External Model] circuits expect digital input signals. As SPICE, Verilog-A(MS), or VHDL-A(MS) models understand only analog signals, some conversion from digital to analog format is required. For example, input logical states such as “0” or “1”, implied in [Model], must be converted to actual input voltage stimuli, such as a voltage ramp, for SPICE simulation.

The D\_to\_A subparameter provides information for converting a digital stimulus, such as “0” or “1”, into an analog voltage ramp (a digital “X” input is ignored by D\_to\_A converters). Each digital port which carries data for conversion to analog format must have its own D\_to\_A line.

The D\_to\_A subparameter is followed by eight or optionally nine arguments:

d\_port port1 port2 vlow vhigh trise tfall corner\_name polarity

The d\_port entry holds the name of the digital port. This entry is used for the reserved port names D\_drive, D\_enable, and D\_switch. The port1 and port2 entries hold the SPICE, Verilog-A(MS) or VHDL-A(MS) analog input port names across which voltages are specified. These entries are used for the user-defined port names, together with another port name, used as a reference.

Normally port1 accepts an input signal and port2 is the reference for port1. However, for an opposite polarity stimulus, port1 could be connected to a reference port and port2 could serve as the input.

The vlow and vhigh entries accept analog voltage values which must correspond to the digital off and on states, where the vhigh value must be greater than the vlow value. When polarity is Non-Inverting, vlow corresponds to the digital off state '0', vhigh corresponds to the digital on state '1', trise corresponds to the analog edge rate going from the digital off to on state, and tfall corresponds to the analog edge rate going from the digital on to off state. When polarity is Inverting, the analog behavior corresponds to the opposite digital states. For example, a 3.3 V ground-referenced buffer would list vlow as 0 V and vhigh as 3.3 V. The trise and tfall entries are times, must be positive, and define input ramp rise and fall times between 0 and 100 percent.

The corner\_name entry holds the name of the external model corner being referenced, as listed under the Corner subparameter.

The last argument, polarity, is optional. If present, its value must be "Inverting" or "Non-Inverting". If the argument is not present, "Non-Inverting" is in effect.

At least one D\_to\_A line must be present, corresponding to the “Typ” corner model, for each digital line to be converted. Additional D\_to\_A lines for other corners may be omitted. In this case, the typical corner D\_to\_A entries will apply to all model corners and the “Typ” corner\_name entry may be omitted.

A\_to\_D:

The A\_to\_D subparameter is used to generate a digital state (“0”, “1”, or “X”) based on analog voltages generated by the SPICE, Verilog-A(MS) or VHDL-A(MS) model or analog voltages present at the pad/pin. This allows an analog signal from the external SPICE, Verilog-A(MS) or VHDL-A(MS) circuit or pad/pin to be read as a digital signal by the simulation tool.

The A\_to\_D subparameter is followed by six arguments:

d\_port port1 port2 vlow vhigh corner\_name

The d\_port entry lists the reserved port name D\_receive. As with D\_to\_A, the port1 entry would normally contain the reserved name A\_signal (see below) or a user-defined port name, while port2 may list any other analog reserved port name, used as a reference. The voltage measurements are taken in this example from the port1 entry with respect to the port2 entry. These ports must also be named by the Ports subparameter.

The vlow and vhigh entries list the low and high analog threshold voltage values. The reported digital state on D\_receive will be “0” if the measured voltage is lower than the vlow value, “1” if above the vhigh value, and “X” otherwise.

The corner\_name entry holds the name of the external model corner being referenced, as listed under the Corner subparameter.

At least one A\_to\_D line must be supplied corresponding to the “Typ” corner model. Other A\_to\_D lines for other corners may be omitted. In this case, the typical corner A\_to\_D entries will apply to all model corners.

IMPORTANT: measurements for receivers in IBIS are normally assumed to be conducted at the die pads/pins. In such cases, the electrical input model data comprises a “load” which affects the waveform seen at the pads. However, for models measure the analog input response at the die pads or inside the circuit (this does not preclude tools from reporting digital D\_receive and/or analog port responses in addition to at-pad A\_signal response). If at-pad measurements are desired, the A\_signal port would be named in the A\_to\_D line under port1. The A\_to\_D converter then effectively acts “in parallel” with the load of the circuit. If internal measurements are desired (e.g., if the user wishes to view the signal after processing by the receiver), the user-defined signal port would be named in the A\_to\_D line under port1. The A\_to\_D converter is effectively “in series” with the receiver model. The vhigh and vlow parameters should be adjusted as appropriate to the measurement point of interest.

Note that, while the port assignments and SPICE, Verilog-A(MS) or VHDL-A(MS) model must be provided by the user, the D\_to\_A and A\_to\_D converters will be provided automatically by the tool (the converter parameters must still be declared by the user). There is no need for the user to develop external SPICE, Verilog-A(MS) or VHDL-A(MS) code specifically for these functions.

A conceptual diagram of the port connections of a SPICE, Verilog-A(MS) or VHDL-A(MS) [External Model] is shown in Figure 24. The example illustrates an I/O buffer. Note that the drawing implies that the D\_receive state changes in response to the analog signal my\_receive, not A\_signal:



1. - Example of an [External Model] I/O Buffer Using SPICE,  
   Verilog-A(MS), or VHDL-A(MS)

Pseudo-Differential Buffers:

Pseudo-differential buffers may be described using a pair of [External Model]s which may or may not be identical. Each of the analog I/O signal ports (usually A\_signal) is connected to a specific pad through the [Pin] list in the usual fashion, and the two ports are linked together as a differential pair through the [Diff Pin] keyword.

The reserved signal name A\_signal is required for the I/O signal ports of [External Model]s connected to pads used in a pseudo-differential configuration.

Users should note that, in pseudo-differential buffers, only one formal signal port is used to stimulate the two [External Model] digital inputs (D\_drive). One of these inputs will reflect the timing and polarity of the formal signal port named by the user, while the other input is inverted and (potentially) delayed with respect to the formal port as defined under the [Diff Pin] keyword. THIS SECOND PORT IS AUTOMATICALLY CREATED BY THE SIMULATION TOOL. Users do not have to create special structures to invert or delay the driven digital signal. Simulation tools will correctly implement the two input ports once the [Diff Pin] keyword has been detected in the .ibs file. This approach is identical to that used in native IBIS.

The D\_to\_A adapters used for SPICE, Verilog-A(MS) or VHDL-A(MS) files can be set up to control ports on pseudo-differential buffers. If SPICE, Verilog-A(MS) or VHDL-A(MS) is used as an external language, the [Diff Pin] vdiff subparameter overrides the contents of vlow and vhigh under A\_to\_D.

IMPORTANT: For pseudo-differential buffers under [External Model], the analog input response may only be measured at the die pads. The [Diff Pin] parameter is required, and controls both the polarity and the differential thresholds used to determine the D\_receive port response (the D\_receive port will follow the state of the non-inverting pin/pad as referenced to the inverting pin/pad). For SPICE, Verilog-A(MS) or VHDL-A(MS) models, the A\_to\_D line must name the A\_signal port under either port1 or port2, as with a single-ended buffer. The A\_to\_D converter then effectively acts “in parallel” with the load of the buffer circuit. The vhigh and vlow parameters will be overridden by the [Diff Pin] vdiff declarations.

The port relationships are shown in Figure 25.



1. -Example SPICE, Verilog-A(MS) or VHDL-A(MS) Implementation

Figure 26 illustrates the same concepts with a \*-AMS model. Note that the state of D\_receive is determined by the tool automatically by observing the A\_signal ports. The outputs of the actual receiver circuits in the \*-AMS models are not used for determining D\_receive.



1. - Example \*-AMS Implementation

Two additional differential timing test loads are available:

Rref\_diff, Cref\_diff

These subparameters are also available under the [Model Spec] keyword for typical, minimum, and maximum corners.

These timing test loads require both sides of the differential model to be operated. They can be used with the existing timing test loads Rref, Cref, and Vref. The existing timing test loads and Vmeas are used if Rref\_diff and Cref\_diff are NOT given.

True Differential Models:

True differential buffers may be described using [External Model]. In a true differential [External Model], the differential I/O ports which connect to die pads use the reserved names A\_signal\_pos and A\_signal\_neg, as shown in Figure 27.



1. - Port Names for True Differential I/O Buffer

IMPORTANT: All true differential models under [External Model] assume single-ended digital port connections (D\_drive, D\_enable, D\_receive).

The [Diff Pin] keyword is still required within the same [Component] definition when [External Model] describes a true differential buffer. The [Model] names or [Model Selector] names referenced by the pair of pins listed in an entry of the [Diff Pin] MUST be the same.

The D\_to\_A or A\_to\_D adapters used for SPICE, Verilog-A(MS) or VHDL-A(MS) files may be set up to control or respond to true differential ports. An example is shown in Figure 28.



1. - Example SPICE, Verilog-A(MS) or VHDL-A(MS) Implementation of a  
   True Differential Buffer

If at-pad or at-pin measurement using a SPICE, Verilog-A(MS) or VHDL-A(MS) [External Model] is desired, the vlow and vhigh entries under the A\_to\_D subparameter must be consistent with the values of the [Diff Pin] vdiff subparameter entry (the vlow value must match -vdiff, and the vhigh value must match +vdiff). The logic states produced by the A\_to\_D conversion follow the same rules as for single-ended buffers, listed above. An example is shown at the end of this section.

IMPORTANT: For true-differential buffers under [External Model], the user can choose whether to measure the analog input response at the die pads or internal to the circuit (this does not preclude tools from reporting digital D\_receive and/or analog responses in addition to at-pad A\_signal response). If at-pad measurements for a SPICE, Verilog-A(MS) or VHDL-A(MS) model are desired, the A\_signal\_pos port would be named in the A\_to\_D line under port1 and A\_signal\_neg under port2. The A\_to\_D converter then effectively acts “in parallel” with the load of the buffer circuit. If internal measurements are desired (e.g., if the user wishes to view the signal after processing by the input buffer), the user-defined analog signal port would be named in the A\_to\_D line under port1. The A\_to\_D converter is “in series” with the receiver buffer model. The vhigh and vlow parameters should be adjusted appropriate to the measurement point of interest, so long as they as they are consistent with the [Diff Pin] vdiff declarations.

Note that the thresholds refer to the state of the non-inverting signal, using the inverting signal as a reference. Therefore, the output signal is considered high when, for example, the non-inverting input is +200 mV above the inverting input. Similarly, the output signal is considered low when the same non-inverting input is -200 mV “above” the inverting input.

EDA tools will report the state of the D\_receive port for true differential \*-AMS [External Model]s according to the AMS code written by the model author; the use of [Diff Pin] does not affect the reporting of D\_receive in this case. EDA tools are free to additionally report the state of the I/O pads according to the [Diff Pin] vdiff subparameter.

For SPICE, Verilog-A(MS) or VHDL-A(MS) and \*-AMS true differential [External Model]s, the EDA tool must not override or change the model author’s connection of the D\_receive port.

Four additional Model\_type arguments are available under the [Model] keyword. One of these must be used when an [External Model] describes a true differential model:

I/O\_diff, Output\_diff, 3-state\_diff, Input\_diff

Two additional differential timing test loads are available:

Rref\_diff, Cref\_diff

These subparameters are also available under the [Model Spec] keyword for the typical, minimum, and maximum corner cases.

These timing test loads require that both the inverting and non-inverting ports of the differential model refer to valid buffer model data (not terminations, supply rails, etc.). The differential test loads may also be combined with the single-ended timing test loads Rref, Cref, and Vref. Note that the single-ended timing test loads plus Vmeas are used if Rref\_diff and Cref\_diff are NOT supplied.

Series and Series Switch Models:

Native IBIS did not define the transition characteristics of digital switch controls. Switches were assumed to either be on or off during a simulation and I-V characteristics could be defined for either or both states. The [External Model] format allows users to control the state of a switch through the D\_switch port. As with other digital ports, the use of SPICE, Verilog-A(MS) or VHDL-A(MS) in an [External Model] requires the user to declare D\_to\_A ports, to convert the D\_switch signal to an analog input to the SPICE, Verilog-A(MS) or VHDL-A(MS) model (whether the port’s state may actually change during a simulation is determined by the EDA tool used).

Series and Series\_switch devices both are described under the [External Model] keyword using the reserved port names A\_pos and A\_neg. Note that the [Series Pin Mapping] keyword must be present and correctly used elsewhere in the file, in order to properly set the logic state of the switch. The A\_pos port is defined in the first entry of the [Series Pin Mapping] keyword, and the A\_neg port is defined in the pin2 entry. For series switches, the [Series Switch Groups] keyword is required.

Ports required for various Model\_types:

As [External Model] makes use of the [Model] keyword’s Model\_type subparameter, not all digital and analog reserved ports may be needed for all Model\_types. Table 13 and Table 14 below define which reserved port names are required for various Model\_types.

Table – Required Port Names for Single-ended Model\_type Assignments

|  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- |
| **Model\_type** | **D\_drive** | **D\_enable** | **D\_receive** | **A\_signal** | **D\_switch** | **A\_pos** | **A\_neg** |
| I/O\* | X | X | X | X |  |  |  |
| 3-state\* | X | X |  | X |  |  |  |
| Output\*, Open\* | X |  |  | X |  |  |  |
| Input |  |  | X | X |  |  |  |
| Terminator |  |  |  | X |  |  |  |
| Series |  |  |  |  |  | X | X |
| Series\_switch |  |  |  |  | X | X | X |

Table – Required Port Names for Differential Model\_type Assignments

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Model\_type** | **D\_drive** | **D\_enable** | **D\_receive** | **A\_signal\_pos** | **A\_signal\_neg** |
| I/O\_diff | X | X | X | X | X |
| 3-state\_diff | X | X |  | X | X |
| Output\_diff | X |  |  | X | X |
| Input\_diff |  |  | X | X | X |

*Examples:*

Example [External Model] using SPICE:

[Model] ExBufferSPICE

Model\_type I/O

Vinh = 2.0

Vinl = 0.8

|

| Other model subparameters are optional

|

| typ min max

[Voltage Range] 3.3 3.0 3.6

|

[Ramp]

dV/dt\_r 1.57/0.36n 1.44/0.57n 1.73/0.28n

dV/dt\_f 1.57/0.35n 1.46/0.44n 1.68/0.28n

|

[External Model]

Language SPICE

|

| Corner corner\_name file\_name circuit\_name (.subckt name)

Corner Typ buffer\_typ.spi buffer\_io\_typ

Corner Min buffer\_min.spi buffer\_io\_min

Corner Max buffer\_max.spi buffer\_io\_max

|

| Parameters - Not supported in SPICE

|

| Ports List of port names (in same order as in SPICE)

Ports A\_signal my\_drive my\_enable my\_receive my\_ref

Ports A\_puref A\_pdref A\_pcref A\_gcref A\_extref

|

| D\_to\_A d\_port port1 port2 vlow vhigh trise tfall corner\_name

D\_to\_A D\_drive my\_drive my\_ref 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_enable my\_enable A\_gcref 0.0 3.3 0.5n 0.3n Typ

|

| A\_to\_D d\_port port1 port2 vlow vhigh corner\_name

A\_to\_D D\_receive my\_receive my\_ref 0.8 2.0 Typ

|

| Note: A\_signal might also be used instead of a user-defined interface port

| for measurements taken at the die pads

|

[End External Model]

Example [External Model] using VHDL-AMS:

[Model] ExBufferVHDL

Model\_type I/O

Vinh = 2.0

Vinl = 0.8

|

| Other model subparameters are optional

|

| typ min max

[Voltage Range] 3.3 3.0 3.6

|

[Ramp]

dV/dt\_r 1.57/0.36n 1.44/0.57n 1.73/0.28n

dV/dt\_f 1.57/0.35n 1.46/0.44n 1.68/0.28n

|

[External Model]

Language VHDL-AMS

|

| Corner corner\_name file\_name entity(architecture)

Corner Typ buffer\_typ.vhd buffer(buffer\_io\_typ)

Corner Min buffer\_min.vhd buffer(buffer\_io\_min)

Corner Max buffer\_max.vhd buffer(buffer\_io\_max)

|

| Parameters List of parameters

Parameters delay rate

Parameters preemphasis

| Ports List of port names (in same order as in VHDL-AMS)

Ports A\_signal A\_puref A\_pdref A\_pcref A\_gcref

Ports D\_drive D\_enable D\_receive

|

[End External Model]

Example [External Model] using Verilog-AMS:

[Model] ExBufferVerilog

Model\_type I/O

Vinh = 2.0

Vinl = 0.8

|

| Other model subparameters are optional

|

| typ min max

[Voltage Range] 3.3 3.0 3.6

|

[Ramp]

dV/dt\_r 1.57/0.36n 1.44/0.57n 1.73/0.28n

dV/dt\_f 1.57/0.35n 1.46/0.44n 1.68/0.28n

|

[External Model]

Language Verilog-AMS

|

| Corner corner\_name file\_name circuit\_name (module)

Corner Typ buffer\_typ.v buffer\_io\_typ

Corner Min buffer\_min.v buffer\_io\_min

Corner Max buffer\_max.v buffer\_io\_max

|

| Parameters List of parameters

Parameters delay rate

Parameters preemphasis

|

| Ports List of port names (in same order as in Verilog-AMS)

Ports A\_signal A\_puref A\_pdref A\_pcref A\_gcref

Ports D\_drive D\_enable D\_receive

|

[End External Model]

Example [External Model] using VHDL-A(MS):

[Model] ExBufferVHDL\_analog

Model\_type I/O

Vinh = 2.0

Vinl = 0.8

|

| Other model subparameters are optional

|

| typ min max

[Voltage Range] 3.3 3.0 3.6

|

[Ramp]

dV/dt\_r 1.57/0.36n 1.44/0.57n 1.73/0.28n

dV/dt\_f 1.57/0.35n 1.46/0.44n 1.68/0.28n

|

[External Model]

Language VHDL-A(MS)

|

| Corner corner\_name file\_name circuit\_name entity(architecture)

Corner Typ buffer\_typ.vhd buffer(buffer\_io\_typ)

Corner Min buffer\_min.vhd buffer(buffer\_io\_min)

Corner Max buffer\_max.vhd buffer(buffer\_io\_max)

|

| Parameters List of parameters

Parameters delay rate

Parameters preemphasis

|

| Ports List of port names (in same order as in VHDL-A(MS))

Ports A\_signal my\_drive my\_enable my\_receive my\_ref

Ports A\_puref A\_pdref A\_pcref A\_gcref A\_extref

|

| D\_to\_A d\_port port1 port2 vlow vhigh trise tfall corner\_name

D\_to\_A D\_drive my\_drive my\_ref 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_enable my\_enable A\_gcref 0.0 3.3 0.5n 0.3n Typ

|

| A\_to\_D d\_port port1 port2 vlow vhigh corner\_name

A\_to\_D D\_receive my\_receive my\_ref 0.8 2.0 Typ

|

| Note: A\_signal might also be used instead of a user-defined interface port

| for measurements taken at the die pads

Example [External Model] using Verilog-A(MS):

[Model] ExBufferVerilog\_analog

Model\_type I/O

Vinh = 2.0

Vinl = 0.8

|

| Other model subparameters are optional

|

| typ min max

[Voltage Range] 3.3 3.0 3.6

|

[Ramp]

dV/dt\_r 1.57/0.36n 1.44/0.57n 1.73/0.28n

dV/dt\_f 1.57/0.35n 1.46/0.44n 1.68/0.28n

|

[External Model]

Language Verilog-A(MS)

|

| Corner corner\_name file\_name circuit\_name (module)

Corner Typ buffer\_typ.va buffer\_io\_typ

Corner Min buffer\_min.va buffer\_io\_min

Corner Max buffer\_max.va buffer\_io\_max

| Parameters List of parameters

Parameters delay rate

Parameters preemphasis

|

| Ports List of port names (in same order as in Verilog-A(MS))

Ports A\_signal my\_drive my\_enable my\_receive my\_ref

Ports A\_puref A\_pdref A\_pcref A\_gcref A\_extref

|

| D\_to\_A d\_port port1 port2 vlow vhigh trise tfall corner\_name

D\_to\_A D\_drive my\_drive my\_ref 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_enable my\_enable A\_gcref 0.0 3.3 0.5n 0.3n Typ

|

| A\_to\_D d\_port port1 port2 vlow vhigh corner\_name

A\_to\_D D\_receive my\_receive my\_ref 0.8 2.0 Typ

|

| Note: A\_signal might also be used instead of a user-defined interface port

| for measurements taken at the die pads

|

[End External Model]

Example of True Differential [External Model] using SPICE:

[Model] Ext\_SPICE\_Diff\_Buff

Model\_type I/O\_diff

Rref\_diff = 100

|

| Other model subparameters are optional

|

| typ min max

[Voltage Range] 3.3 3.0 3.6

|

[Ramp]

dV/dt\_r 1.57/0.36n 1.44/0.57n 1.73/0.28n

dV/dt\_f 1.57/0.35n 1.46/0.44n 1.68/0.28n

|

[External Model]

Language SPICE

|

| Corner corner\_name file\_name circuit\_name (.subckt name)

Corner Typ diffio.spi diff\_io\_typ

Corner Min diffio.spi diff\_io\_min

Corner Max diffio.spi diff\_io\_max

|

| Ports List of port names (in same order as in SPICE)

Ports A\_signal\_pos A\_signal\_neg my\_receive my\_drive my\_enable

Ports A\_puref A\_pdref A\_pcref A\_gcref A\_extref my\_ref A\_gnd

|

| D\_to\_A d\_port port1 port2 vlow vhigh trise tfall corner\_name

D\_to\_A D\_drive my\_drive my\_ref 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_drive my\_drive my\_ref 0.0 3.0 0.6n 0.3n Min

D\_to\_A D\_drive my\_drive my\_ref 0.0 3.6 0.4n 0.3n Max

D\_to\_A D\_enable my\_enable my\_ref 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_enable my\_enable my\_ref 0.0 3.0 0.6n 0.3n Min

D\_to\_A D\_enable my\_enable my\_ref 0.0 3.6 0.4n 0.3n Max

|

| A\_to\_D d\_port port1 port2 vlow vhigh corner\_name

A\_to\_D D\_receive A\_signal\_pos A\_signal\_neg -200m 200m Typ

A\_to\_D D\_receive A\_signal\_pos A\_signal\_neg -200m 200m Min

A\_to\_D D\_receive A\_signal\_pos A\_signal\_neg -200m 200m Max

|

[End External Model]

Example of True Differential [External Model] using VHDL-AMS:

[Model] Ext\_VHDL\_Diff\_Buff

Model\_type I/O\_diff

Rref\_diff = 100

|

| typ min max

[Voltage Range] 3.3 3.0 3.6

|

[Ramp]

dV/dt\_r 1.57/0.36n 1.44/0.57n 1.73/0.28n

dV/dt\_f 1.57/0.35n 1.46/0.44n 1.68/0.28n

|

| Other model subparameters are optional

|

[External Model]

Language VHDL-AMS

|

| Corner corner\_name file\_name entity(architecture)

Corner Typ diffio\_typ.vhd buffer(diff\_io\_typ)

Corner Min diffio\_min.vhd buffer(diff\_io\_min)

Corner Max diffio\_max.vhd buffer(diff\_io\_max)

|

| Parameters List of parameters

Parameters delay rate

Parameters preemphasis

|

| Ports List of port names (in same order as in VHDL-AMS)

Ports A\_signal\_pos A\_signal\_neg D\_receive D\_drive D\_enable

Ports A\_puref A\_pdref A\_pcref A\_gcref

|

[End External Model]

Example of Pseudo-Differential [External Model] using SPICE:

| Note that [Pin] and [Diff Pin] declarations are shown for clarity

|

|

[Pin] signal\_name model\_name R\_pin L\_pin C\_pin

1 Example\_pos Ext\_SPICE\_PDiff\_Buff

2 Example\_neg Ext\_SPICE\_PDiff\_Buff

|

| ...

|

[Diff Pin] inv\_pin vdiff tdelay\_typ tdelay\_min tdelay\_max

1 2 200mV 0ns 0ns 0ns

|

| ...

|

[Model] Ext\_SPICE\_PDiff\_Buff

Model\_type I/O

|

| Other model subparameters are optional

|

| typ min max

[Voltage Range] 3.3 3.0 3.6

|

[Ramp]

dV/dt\_r 1.57/0.36n 1.44/0.57n 1.73/0.28n

dV/dt\_f 1.57/0.35n 1.46/0.44n 1.68/0.28n

|

[External Model]

Language SPICE

|

| Corner corner\_name file\_name circuit\_name (.subckt name)

Corner Typ diffio.spi diff\_io\_typ

Corner Min diffio.spi diff\_io\_min

Corner Max diffio.spi diff\_io\_max

|

| Ports List of port names (in same order as in SPICE)

Ports A\_signal my\_drive my\_enable my\_ref

Ports A\_puref A\_pdref A\_pcref A\_gcref A\_gnd A\_extref

|

| D\_to\_A d\_port port1 port2 vlow vhigh trise tfall corner\_name

D\_to\_A D\_drive my\_drive my\_ref 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_drive my\_drive my\_ref 0.0 3.0 0.6n 0.3n Min

D\_to\_A D\_drive my\_drive my\_ref 0.0 3.6 0.4n 0.3n Max

D\_to\_A D\_enable my\_enable A\_pcref 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_enable my\_enable A\_pcref 0.0 3.0 0.6n 0.3n Min

D\_to\_A D\_enable my\_enable A\_pcref 0.0 3.6 0.4n 0.3n Max

|

| A\_to\_D d\_port port1 port2 vlow vhigh corner\_name

A\_to\_D D\_receive A\_signal my\_ref 0.8 2.0 Typ

A\_to\_D D\_receive A\_signal my\_ref 0.8 2.0 Min

A\_to\_D D\_receive A\_signal my\_ref 0.8 2.0 Max

|

| This example shows the evaluation of the received signals at the die

| pads. [Diff Pin] defines the interpretation of the A\_to\_D output

| polarity and levels and overrides the A\_to\_D settings shown above.

|

[End External Model]

*Keywords:* [External Circuit], [End External Circuit]

*Required:* No

*Description:* Used to reference an external file containing an arbitrary circuit description using one of the supported languages.

*Sub-Params:* Language, Corner, Parameters, Ports, D\_to\_A, A\_to\_D

*Usage Rules:* Each [External Circuit] keyword must be followed by a unique name that differs from any name used for any [Model] or [Submodel] keyword.

The [External Circuit] keyword may appear multiple times. It is not scoped by any other keyword.

Each instance of an [External Circuit] is referenced by one or more [Circuit Call] keywords discussed later. (The [Circuit Call] keyword cannot be used to reference a [Model] keyword.)

The [External Circuit] keyword and contents may be placed anywhere in the file, outside of any [Component] keyword group or [Model] keyword group, in a manner similar to that of the [Model] keyword.

Subparameter Definitions:

Language:

Accepts “SPICE”, “VHDL-AMS”, “Verilog-AMS”, “VHDL-A(MS)” or “Verilog-A(MS)” as arguments. The Language subparameter is required and must appear only once.

Corner:

Three entries follow the Corner subparameter on each line:

corner\_name file\_name circuit\_name

The corner\_name entry is “Typ”, “Min”, or “Max”. The file\_name entry points to the referenced file in the same directory as the .ibs file.

Up to three Corner lines are permitted. A “Typ” line is required. If “Min” and/or “Max” data is missing, the tool may use “Typ” data in its place. However, the tool should notify the user of this action.

The circuit\_name entry provides the name of the circuit to be simulated within the referenced file. For SPICE files, this is normally a “.subckt” name. For VHDL-AMS files, this is normally an “entity(architecture)” name pair. For Verilog-AMS files, this is normally a “module” name.

No character limits, case-sensitivity limits or extension conventions are required or enforced for file\_name and circuit\_name entries. However, the total number of characters in each Corner line must comply with Section 3. Furthermore, lower-case file\_name entries are recommended to avoid possible conflicts with file naming conventions under different operating systems. Case differences between otherwise identical file\_name entries or circuit\_name entries should be avoided. External languages may not support case-sensitive distinctions.

Parameters:

Lists names of parameters that may be passed into an external circuit file. Each Parameters assignment must match a name or keyword in the external file or language. The list of Parameters can span several lines by using the word Parameters at the start of each line. The Parameters subparameter is optional, and the external circuit must operate with default settings without any Parameters assignments.

Parameter passing is not supported in SPICE. VHDL-AMS and VHDL-A(MS) parameters are supported using “generic” names, and Verilog-AMS and Verilog-A(MS) parameters are supported using “parameter” names.

Ports:

Ports are interfaces to the [External Circuit] which are available to the user and tool at the IBIS level. They are used to connect the [External Circuit] to die pads. The Ports parameter is used to identify the ports of the [External Circuit] to the simulation tool. The port assignment is by position and the port names do not have to match exactly the names inside the external file. The list of port names may span several lines if the word Ports is used at the start of each line.

The Ports parameter is used to identify the ports of the [External Circuit] to the simulation tool. The port assignment is by position and the port names do not have to match exactly the port names in the external file. The list of port names may span several lines if the word Ports is used at the start of each line.

[External Circuit] allows any number of ports to be defined, with any names which comply with Section 3 format requirements. Reserved port names may be used, but ONLY DIGITAL PORTS will have the pre-defined functions listed in the General Assumptions heading above. User-defined and reserved port names may be combined within the same [External Circuit].

The [Pin Mapping] keyword cannot be used with [External Circuit] in the same [Component] description.

Digital-to-Analog/Analog-to-Digital Conversions:

These subparameters define all digital-to-analog and analog-to-digital converters needed to properly connect digital signals with the analog ports of referenced external SPICE, Verilog-A(MS) or VHDL-A(MS) models. These subparameters must be used when [External Circuit] references a file written in the SPICE, Verilog-A(MS) or VHDL-A(MS) language. They are not permitted with Verilog-AMS or VHDL-AMS external files.

D\_to\_A:

As assumed in [Model] and [External Model], some interface ports of [External Circuit]s expect digital input signals. As SPICE, Verilog-A(MS) or VHDL-A(MS) models understand only analog signals, some conversion from digital to analog format is required. For example, input logical states such as “0” or “1” must be converted to actual input voltage stimuli, such as a voltage ramp, for SPICE simulation.

The D\_to\_A subparameter provides information for converting a digital stimulus, such as “0” or “1”, into an analog voltage ramp (a digital “X” input is ignored by D\_to\_A converters). Each digital port which carries data for conversion to analog format must have its own D\_to\_A declaration.

The D\_to\_A subparameter is followed by eight or optionally nine arguments:

d\_port port1 port2 vlow vhigh trise tfall corner\_name polarity

The d\_port entry holds the name of the digital port. This entry may contain user-defined port names or the reserved port names D\_drive, D\_enable, and D\_switch. he port1 and port2 entries hold the SPICE, Verilog-A(MS) or VHDL-A(MS) analog input port names across which voltages are specified. These entries contain user-defined port names. One of these port entries must name a reference for the other port (for example, A\_gnd).

Normally, port1 accepts an input signal and port2 is the reference for port1. However, for an opposite polarity stimulus, port1 could be connected to a voltage reference and port2 could serve as the input.

The vlow and vhigh entries accept voltage values which correspond to fully-off and fully-on states, where the vhigh value must be greater than the vlow value. When polarity is Non-Inverting, vlow corresponds to the digital off state '0', vhigh corresponds to the digital on state '1', trise corresponds to the analog edge rate going from the digital off to on state, and tfall corresponds to the analog edge rate going from the digital on to off state. When polarity is Inverting, the analog behavior corresponds to the opposite digital states. For example, a 3.3 V ground-referenced buffer would list vlow as 0 V and vhigh as 3.3 V. The trise and tfall entries are times, must be positive and define input ramp rise and fall times between 0 and 100 percent.

The corner\_name entry holds the name of the external circuit corner being referenced, as listed under the Corner subparameter.

The last argument, polarity, is optional. If present, its value must be "Inverting" or "Non-Inverting". If the argument is not present, "Non-Inverting" is in effect.

Any number of D\_to\_A subparameter lines is allowed, so long as each contains a unique port name entry and at least one unique port1 or port2 entry (i.e., several D\_to\_A declarations may use the same reference node under port1 or port2). At least one D\_to\_A line must be present, corresponding to the “Typ” corner model, for each digital line to be converted. Additional D\_to\_A lines for other corners may be omitted. In this case, the typical corner D\_to\_A entries will apply to all model corners and the “Typ” corner\_name entry may be omitted.

A\_to\_D:

The A\_to\_D subparameter is used to generate a digital state (“0”, “1”, or “X”) based on analog voltages from the SPICE, Verilog-A(MS) or VHDL-A(MS) model or from the pad/pin. This allows an analog signal from the external SPICE, Verilog-A(MS) or VHDL-A(MS) circuit to be read as a digital signal by the simulation tool.

The A\_to\_D subparameter is followed by six arguments:

d\_port port1 port2 vlow vhigh corner\_name

The d\_port entry lists port names to be used for digital signals going. As with D\_to\_A, the port1 entry would contain a user-defined analog signal. Port2 would list another port name to be used as a reference. The voltage measurements are taken from the port1 entry with respect to the port2 entry. These ports must also be named by the Ports subparameter.

The vlow and vhigh entries list the low and high analog threshold voltage values. The reported digital state on D\_receive will be “0” if the measured voltage is lower than the vlow value, “1” if above the vhigh value, and “X” otherwise.

The corner\_name entry holds the name of the external model corner being referenced, as listed under the Corner subparameter.

Any number of A\_to\_D subparameter lines is allowed, so long as each line contains at least one column entry which is distinct from the column entries of all other lines. In practice, this means that A\_to\_D subparameter lines describing different corners will have identical port names. Other kinds of variations described through A\_to\_D subparameter lines should use unique port names. For example, a user may wish to create additional A\_to\_D converters for individual analog signals to monitor common mode behaviors on differential buffers.

At least one A\_to\_D line must be supplied corresponding to the “Typ” corner model. Other A\_to\_D lines for other corners may be omitted. In this case, the typical corner D\_to\_A entries will apply to all model corners.

IMPORTANT: measurements for receivers in IBIS may be conducted at the die pads or the pins. In such cases, the electrical input model data comprises a “load” which affects the waveform seen. However, for [External Circuit]s, the user may choose whether to measure the analog input response in the usual fashion or internal to the circuit (this does not preclude tools from reporting digital D\_receive and/or analog responses in addition to normal A\_signal response). If native IBIS measurements are desired, the A\_signal port would be named in the A\_to\_D line under port1. The A\_to\_D converter then effectively acts “in parallel” with the load of the circuit. If internal measurements are desired (e.g., if the user wishes to view the signal after processing by the receiver), the user-defined analog signal port would be named in the A\_to\_D line under port1. The A\_to\_D converter is effectively “in series” with the receiver model. The vhigh and vlow parameters should be adjusted appropriate to the measurement point of interest.

Note that, while the port assignments and SPICE, Verilog-A(MS) or VHDL-A(MS) model data must be provided by the user, the D\_to\_A and A\_to\_D converters will be provided automatically by the tool. There is no need for the user to develop external SPICE, Verilog-A(MS) or VHDL-A(MS) code specifically for these functions.

The [Diff Pin] keyword is NOT required for true differential [External Circuit] descriptions.

Pseudo-differential buffers are not supported under [External Circuit]. Use the existing [Model] and [External Model] keywords to describe these structures.

Note that the EDA tool is responsible for determining the specific measurement points for reporting timing and signal quality for [External Circuit]s.

In all other respects, [External Circuit] behaves exactly as [External Model].

*Examples:*

Example of Model B as an [External Circuit] using SPICE:

[External Circuit] BUFF-SPICE

Language SPICE

|

| Corner corner\_name file\_name circuit\_name (.subckt name)

Corner Typ buffer\_typ.spi bufferb\_io\_typ

Corner Min buffer\_min.spi bufferb\_io\_min

Corner Max buffer\_max.spi bufferb\_io\_max

|

| Parameters - Not supported in SPICE

|

| Ports List of port names (in same order as in SPICE)

Ports A\_signal int\_in int\_en int\_out A\_control

Ports A\_puref A\_pdref A\_pcref A\_gcref

|

| D\_to\_A d\_port port1 port2 vlow vhigh trise tfall corner\_name

D\_to\_A D\_drive int\_in my\_gcref 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_drive int\_in my\_gcref 0.0 3.0 0.6n 0.3n Min

D\_to\_A D\_drive int\_in my\_gcref 0.0 3.6 0.4n 0.3n Max

D\_to\_A D\_enable int\_en my\_gnd 0.0 3.3 0.5n 0.3n Typ

D\_to\_A D\_enable int\_en my\_gnd 0.0 3.0 0.6n 0.3n Min

D\_to\_A D\_enable int\_en my\_gnd 0.0 3.6 0.4n 0.3n Max

|

| A\_to\_D d\_port port1 port2 vlow vhigh corner\_name

A\_to\_D D\_receive int\_out my\_gcref 0.8 2.0 Typ

A\_to\_D D\_receive int\_out my\_gcref 0.8 2.0 Min

A\_to\_D D\_receive int\_out my\_gcref 0.8 2.0 Max

|

| Note, the A\_signal port might also be used and int\_out not defined in

| a modified .subckt.

|

[End External Circuit]

Example [External Circuit] using VHDL-AMS:

[External Circuit] BUFF-VHDL

Language VHDL-AMS

|

| Corner corner\_name file\_name entity(architecture)

Corner Typ buffer\_typ.vhd bufferb(buffer\_io\_typ)

Corner Min buffer\_min.vhd bufferb(buffer\_io\_min)

Corner Max buffer\_max.vhd bufferb(buffer\_io\_max)

|

| Parameters List of parameters

Parameters delay rate

Parameters preemphasis

|

| Ports List of port names (in same order as in VHDL-AMS)

Ports A\_signal A\_puref A\_pdref A\_pcref A\_gcref A\_control

Ports D\_drive D\_enable D\_receive

|

[End External Circuit]

Example [External Circuit] using Verilog-AMS:

[External Circuit] BUFF-VERILOG

Language Verilog-AMS

|

| Corner corner\_name file\_name circuit\_name (module)

Corner Typ buffer\_typ.v bufferb\_io\_typ

Corner Min buffer\_min.v bufferb\_io\_min

Corner Max buffer\_max.v bufferb\_io\_max

|

| Parameters List of parameters

Parameters delay rate

Parameters preemphasis

|

| Ports List of port names (in same order as in Verilog-AMS)

Ports A\_signal A\_puref A\_pdref A\_pcref A\_gcref A\_control

Ports D\_drive D\_enable D\_receive

|

[End External Circuit]

Example [External Circuit] using SPICE:

| Interconnect Structure as an [External Circuit]

|

|

[External Circuit] BUS\_SPI

Language SPICE

|

| Corner corner\_name file\_name circuit\_name (.subckt name)

Corner Typ bus\_typ.spi Bus\_typ

Corner Min bus\_min.spi Bus\_min

Corner Max bus\_max.spi Bus\_max

|

| Parameters - Not supported in SPICE

|

| Ports are in same order as defined in SPICE

Ports vcc gnd io1 io2

Ports int\_ioa vcca1 vcca2 vssa1 vssa2

Ports int\_iob vccb1 vccb2 vssb1 vssb2

|

| No A\_to\_D or D\_to\_A required, as no digital ports are used

|

[End External Circuit]

Example [External Circuit] using VHDL-AMS:

[External Circuit] BUS\_VHD

Language VHDL-AMS

|

| Corner corner\_name file\_name entity(architecture)

Corner Typ bus.vhd Bus(Bus\_typ)

Corner Min bus.vhd Bus(Bus\_min)

Corner Max bus.vhd Bus(Bus\_max)

|

| Parameters List of parameters

Parameters r1 l1

Parameters r2 l2 temp

|

| Ports are in the same order as defined in VHDL-AMS

Ports vcc gnd io1 io2

Ports int\_ioa vcca1 vcca2 vssa1 vssa2

Ports int\_iob vccb1 vccb2 vssb1 vssb2

Example [External Circuit] using Verilog-AMS:

[External Circuit] BUS\_V

Language Verilog-AMS

|

| Corner corner\_name file\_name circuit\_name (module)

Corner Typ bus.v Bus\_typ

Corner Min bus.v Bus\_min

Corner Max bus.v Bus\_max

|

| Parameters List of parameters

Parameters r1 l1

Parameters r2 l2 temp

|

| Ports are in the same order as defined in Verilog-AMS

Ports vcc gnd io1 io2

Ports int\_ioa vcca1 vcca2 vssa1 vssa2

Ports int\_iob vccb1 vccb2 vssb1 vssb2

|

[End External Circuit]

The scope of the following keywords is limited to the [Component] keyword. They apply to the specific set of pin numbers and internal nodes only within that [Component].